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Studies of inherent lubricity coatings for low surface roughness galvanised steel for automotive applications

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ABSTRACT

Surface lubricity on TiO₂ coated galvanised steels can be controlled by solution depositing perfluorooctanoic (**C8**), lauric (**C12**) or stearic (**C18**) acids to avoid lubricating oils/emulsions or substrate pre etching to remove surface oxide that add cost and waste. Water contact angles reveal increased surface hydrophobicity on coated samples that correlate with linear friction testing, suggesting water contact angle can be used to screen lubricity compounds. Linear friction testing shows that **C12** and **C18** lower the coefficient of friction (μ) by 50–60% compared with uncoated substrates whilst **C8** drops μ from 0.31 to 0.22. Surfaces have been characterised by X ray photoelectron spectroscopy, scanning electron microscopy and atomic force microscopy, whilst infrared confirms that as deposited coatings contain physisorbed and deprotonated acids chemisorbed through esters and thermal gravimetric analysis confirms increasing loadings from **C8** to **C12** to **C18**. Surface washing removes physisorbed material and lowers μ by increasing surface organisation and alkyl chain packing that enhances frictional energy dissipation through steric quenching. Copyright © 2017 John Wiley & Sons, Ltd.

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KEY WORDS: lubricity; friction; sorption; automotive steel; sheet metal forming

INTRODUCTION

Galvanised steel is formed into complex shapes for vehicle bodies through techniques such as deep drawing that relies on material ductility to create new shapes as the substrate is forced over tools by the mechanical action of a punch.^{1,2} Adequate lubrication is essential to reduce friction to avoid wear on the substrate surface caused by frictional force at the interface between the substrate and the shaping tools.³ Currently, drawing oils, emulsions or colloids are deposited onto automotive steels by spray, roll or drip coating to act as deep drawing lubricants.⁴ Whilst these emulsions are non-toxic, they rely on the surface texture of the substrate to remain in place during forming.⁵ However, the poorer paint

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finish, which can result from surface roughness,⁶ means the automotive sector is increasingly driving towards smoother substrates.

Consequently, there is a need to develop alternative lubricants that can operate at a wider range of surface texture specifications of automotive steels. Conformal deposition at a molecular level avoids macro-surface roughness issues because it operates at an entirely different length scale (pm compared with μm). Previously, low surface energy monolayers have been used to generate low friction surfaces on different materials, e.g. stearate on Al⁷ or steel,^{8,9} silanes on Si¹⁰ or phosphonates on Cu¹¹. In general, the organic molecules that form such monolayers contain linker groups that bind to substrate surface atoms and alkyl chains that orient away from the surface to reduce interfacial shear forces.¹² However, prior reports for the surface functionalise metals or metal oxides have often used pretreatments such as polishing¹³ or plasma cleaning⁸ to generate homogeneous, ultra-clean and/or oxide-free surfaces. In a laboratory, these approaches work well but, on a production line, these extra steps increase cost and waste. Thus, we have taken the opposite approach and, rather than remove surface oxide, we have studied the self-assembly of carboxylic acids either onto precast TiO₂ films or, where there is incomplete TiO₂ surface coverage, directly onto the native ZnO surface layer of galvanised steel. We have chosen to use study the addition of a TiO₂ layer onto the galvanised substrate because carboxylic acids have been observed to chemisorb as monolayers onto metal oxide surfaces (e.g. TiO₂) through ester linkages^{14,15} in a similar way to that used in dye-sensitised solar cells.^{16,17}

In this paper, we report studies of using stearic, lauric or perfluorooctanoic acid to generate cost-effective, low toxicity, processable films with controlled surface lubricity on low surface roughness, galvanised automotive steel. Whilst low friction, stearate films have been reported on Al⁷, steel,^{8,9,13} and mica,¹⁹ to our knowledge, lauric and perfluorooctanoic acid have not been studied in this context. We have linked detailed characterisation of these surfaces with coefficient of friction (μ) and contact angle data. Whilst correlations between atomic force microscopy (AFM) friction coefficients and contact angle data have been reported for glass substrates,¹⁸ we also report the first attempts to determine whether such a correlation exists for galvanised steel substrates as such correlation would enable contact angle measurements to be used as screening methods for compounds that could imbue surface lubricity.

MATERIALS AND METHODS

Samples and chemicals

Galvanised steel (DX56, Tata Steel) was cut into 10 × 20 mm² coupons for characterisation and 50 × 300 mm² strips for linear friction testing. The steel composition (wt%) was Al 0.036, C 0.0022, Mo 0.001, Ni 0.001, N 0.0035, P 0.009, Si 0.003, S 0.010, Sn 0.004, Ti 0.050, V 0.002, Cr 0.012, Cu 0.026, Mn 0.088 and B 0.002, and the balance was Fe. The surface roughness was 0.97 ± 0.05 μm , measured using a Marsurf profilometer. All other chemicals were sourced from Sigma Aldrich and used without further purification.

Surface functionalisation

Samples were air dried after each of the following steps. Surface oil was removed from the steel by scrubbing with water and detergent and then ultra-sonicating in acetone for 5 min. Selected

substrates were immersed in an isopropanolic solution of $\text{Ti}(\text{OPr})_4$ (10 mM) for 30 s. Substrates were then immersed in 100 mM isopropanolic solutions of the carboxylic acids for 30 s before analysis. Selected samples were then either rinsed with acetone for 2 min or immersed in 100 mM $\text{NaOH}_{(\text{aq})}$ for 30 s.

Characterisation

Contact angle measurements ($n = 5$, 5 μl deionized water) were made using the sessile drop technique with a USB 2.0 camera and goniometer, and the data were fitted using FTA 32 software (FTA 32 Europe). Infrared (IR) spectra (4 scans, 4 cm^{-1} resolution) were recorded on a Perkin Elmer 100 Series attenuated total reflection Fourier transform infrared spectroscopy spectrometer, between 650 and 4000 cm^{-1} . Field emission gun scanning electron microscopy (SEM) was carried out on a Hitachi S4800 at 1.0 kV ($J_{\text{emission}} = 5 \mu\text{A}$ and working distance = 11.5 mm). Energy-dispersive X-ray (EDX) spectra were recorded using a Silicon Drift X-Max EDX detector and INCA EDX software (Oxford Instruments, Abingdon, UK) at 15.0 kV ($J_{\text{emission}} = 15 \mu\text{A}$, working distance = 17.0 mm and acquisition = 100 s). AFM data were measured over $10 \times 10 \mu\text{m}$ scan areas on a JPK Nanowizard 3 AFM in contact mode using a Si tip (thickness 3 μm and length 225 μm) with a force constant of 2.8 N m^{-1} . The tip velocity was 20 $\mu\text{m s}^{-1}$ with a line rate of 0.5 Hz. X-ray photoelectron spectra (XPS) were recorded on an Axis Supra XPS (Kratos Analytical) using a monochromated Al K_α source and large area slot mode detector (300 \times 800 μm analysis area). Data were recorded using a charge neutraliser to limit differential charging, and binding energies were calibrated to the main hydrocarbon peak (BE 284.8 eV). For each etch, a survey scan was recorded using a pass energy of 160 eV. Data were fitted using CASA software with Shirley backgrounds. A 0.1 eV step size was used when recording the high-resolution spectra and a pass energy of 20 eV. Thermal gravimetric analysis (TGA) data were recorded on a Pyris 1 TGA, heating from 25 to 550°C at 25°C min^{-1} under N_2 (20 ml min^{-1}). Coefficients of friction were measured using linear friction testing (LFT), a strip drawing test similar to that reported by Trzepieciniski *et al.*²⁰ at 22–24°C and 30–45% RH (Figure S1). To do this, samples (50 \times 300 mm, $n = 3$) were pulled between round and cylindrical tools, clamped together with a force of 5 kN, at 0.345 mm s^{-1} for a track length of 60 mm. This sliding speed is slower than that typically used in deep drawing but was used to invoke very high friction to cause much faster removal of the zinc layer. Otherwise, the tests would have required prohibitively very large amounts of material to study LFT. A new tool pair was used for each LFT test. The pulling force was measured and used to calculate the coefficient of friction (μ) by taking an average of the data between 40 and 50 mm along the track length (where the values for μ had typically reached a plateau and where there is no longer believed to be any contribution from static friction behaviour that might occur at approximately <10 mm) and using Equation (1). All LFT tests were carried out in triplicate with mean values quoted (errors quoted are standard deviations from the mean).

$$\mu = \text{pulling force} / (2 \times \text{normal force}) \quad (1)$$

Wear was assessed using digital photographs of the wear tools and by confocal microscopy using a Nanofocus μSurf Mobile on 2.1 \times 2.1 mm areas of steel samples at 20 \times magnification. The data were plotted using MOUNTAINS software, version 7.3.

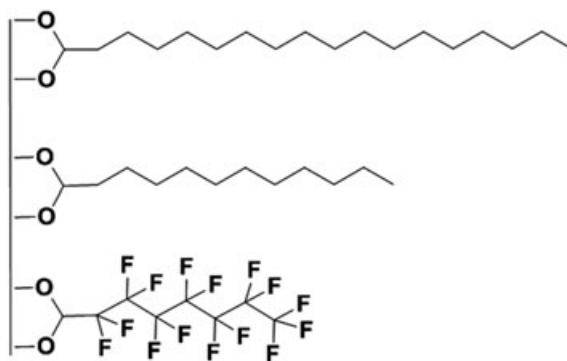
RESULTS AND DISCUSSION

Lubricity compounds and substrate

Lubricity compounds typically contain three main functionalities: a linker group to fix the compound to the substrate surface, a long (usually alkyl) chain that reduces surface energy and side groups attached to the long chain (Scheme 1a). In this work, three compounds have been studied all of which possess a carboxylic acid linker group. However, the compounds chosen vary in the length of alkyl chain and side groups they possess. Thus, perfluorooctanoic acid possesses only C F side groups and consists of an 8 carbon chain and is subsequently labelled here as **C8**. By comparison, lauric and stearic acid possess only C H side groups but consist of 12 and 18 carbon chains and so are labelled here as **C12** and **C18**, respectively. The substrate chosen for lubricity testing (DX56) is galvanised steel with low surface roughness, which is designed for use in the automotive sector. The DX56 surface consists of a galvanic coating weight of 50 90 g m⁻² that corresponds to a thickness of approximately 9 13 μm made up of 99.7 wt% Zn and 0.3 wt% Al. Thus, the outer surface of the DX56 substrate is expected to consist of a thin layer of predominantly ZnO.

Infrared spectroscopy

After removing surface oil from the DX56 substrate, the lubricity compounds have been deposited onto the steel by dip coating. IR data for **C8**-coated steel show a broad peak at approximately 3250 cm⁻¹ (Figure 1) that also appears in the spectrum of the neat acid (S2). This is ascribed to intermolecular H-bonding between the carboxylic acid moieties, suggesting there is physisorbed acid on the surface. However, the νC = O of neat **C8** is not observed at 1711 cm⁻¹ in the coated sample. Instead, two bands are observed at 1727 and 1652 cm⁻¹ (Figure 1), which are assigned as νC = O and the asymmetric νCO₂ of the carboxylate linker of **C8** bound to the oxide surface in the bridging coordination mode.²¹ Bands at 1430 and 1366 cm⁻¹ are assigned to the symmetric νCO₂ of the bridging coordination mode and tentatively to the asymmetric νCO₂ of carboxylates bound through monodentate coordination.²¹ Whilst this suggests multiple coordination modes for **C8**, no bands for the monodentate carboxylate symmetric stretching vibration are observed.



Scheme 1. Schematic of **C18** (top), **C12** (middle) or **C8** (bottom) bound to surface sites in bridging coordination mode. H atoms omitted for clarity.

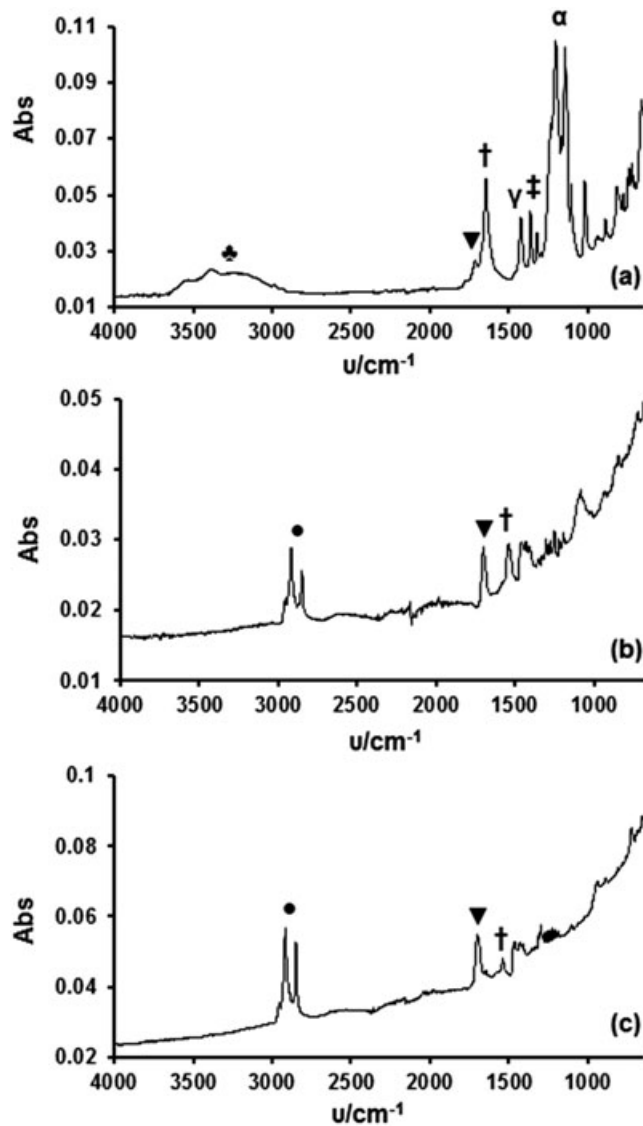


Figure 1. Infrared spectra of DX56 steel treated with (a) C8 (b) C12 or (c) C18. ●, ν C H; ♣, ν O H; ▼, ν C = O; †, ν CO₂ asym bridge; γ, ν CO₂ sym bridge; ‡, ν CO₂ asym mon; α, ν C F.

Previous studies have shown that carboxylic acids can chemisorb to metal oxide surfaces through covalent ester bonds^{7,10,21} and that physisorbed molecules can be readily removed by solvent rinsing.^{7,8,22} To study this, acetone rinsing shows that, whilst no carbonyl or carboxylate stretching bands are observed, ν C F are present between 1358 and 1140 cm^{-1} (S3). This confirms that C8 remains adsorbed and suggests that the dipole moments of the carboxylate-related bands may be oscillating parallel to the surface and so are invisible in the IR spectrum.²³ Further evidence for this is that, after

NaOH_(aq) treatment to de-esterify the **C8**, there are no carboxylate or C F bands in the spectrum confirming that all the remaining **C8** has been desorbed (S4).

Infrared spectra for **C12**-coated and **C18**-coated DX56 show ν C-H at 3000–2800 cm⁻¹ (Figure 1). Both spectra show intense ν C=O bands at approximately 1700 cm⁻¹ and weaker carboxylate asymmetric ν CO₂ at approximately 1550 cm⁻¹ whilst symmetric ν CO₂ bands are expected to be coincident with carboxylate-related bands from physisorbed **C12** or **C18**. The signals observed are ascribed to non-dissociated **C12** and **C18** acids along with surface-bound esters,^{7,10,13} suggesting that both of these coatings contain physisorbed and chemisorbed **C12** and **C18**, respectively. For both acetone rinsed coatings, symmetric and asymmetric ν CO₂ bands are observed at 1542 and 1400 cm⁻¹, respectively along with a band ascribed to methylene scissoring at 1465 cm⁻¹¹²⁴ (S3). These bands confirm that esterified, chemisorbed **C12** and **C18** remain on the surface whilst any physisorbed material is removed. Analysis of $\Delta\nu$ between ν CO₂ asym and ν CO₂ sym gives a value of approximately 140 cm⁻¹ for **C12** and **C18** coatings that is consistent with carboxylate groups coordinating to surface atoms in a bridging coordination mode.²⁵ Such sorption has been observed in prior studies whereby bonding proceeds through coordination of both carboxylate oxygen atoms to two different surface sites.^{4,10,22} Scheme 1b shows bidentate coordination of **C8**, **C12** and **C18** on a substrate surface.

Scanning electron microscopy

Scanning electron microscopy for ‘as received’ DX56 steel shows contamination ascribed to oil deposited before transit to minimise corrosion. After cleaning, SEM confirms oil removal (S5a). After dip coating DX56 in Ti(OiPr)₄ solution, the surface topography reduces due to the deposition of a TiO₂ film whilst EDX data confirms Ti is present (S5b). For the lubricity compounds, the **C8** surface shows few new features beyond the TiO₂-coated DX56 although the surface appears darker, suggesting that the coating interacts differently with the electron beam (Figure 2a). The **C12** surface shows more surface features, suggesting a thicker film has been deposited (Figure 2b), whilst the **C18** surface shows needle-like structures (Figure 2c), suggesting stearic acid has deposited as a separate phase.

Atomic force microscopy data (S7) of 10 × 10 μm areas of the samples show low surface topography for the DX56 substrate (±10 nm). After Ti(OPr)₄ treatment, new features are observed, which are 200–250 nm in height and which are ascribed to TiO₂ particles that we observe in the SEM. After deposition of **C8** (S8), a much higher surface topography is observed (±1000 nm) but this drops to ±80 nm after rinsing in line with removal of some physisorbed **C8**. However, the surface topography is still much greater than the substrate, suggesting that a model similar to Figure 6d is occurring for **C8**. For the **C12** surface, the surface topography is ±200 nm but this drops to ±10 nm barring spikes for residual TiO₂ particles (S9). However, the water contact angle (WCA) remains hydrophobic and the coefficient of friction remains low. This suggests monolayer **C12** coverage represented in Figure 6c. The as-deposited **C18** surface shows angular particles with surface topography ±80 nm (S10). XRD shows that these particles are crystalline indicating phase separation of excess stearate material (S11). After acetone rinsing, these particles disappear but the surface topography (±50 nm) suggests multiple layers of **C18** remain.

X-ray photoelectron spectroscopy

X-ray photoelectron spectroscopy data for cleaned DX56 show Zn 2p_{1/2} and Zn 2p_{3/2} photoelectron peaks at 1021.2 and 1044.0 eV, respectively,^{26–28} as well as a weak Al 2p photoelectron peak at 73.9 eV (S12 and S13). This is expected as Al is added to the galvanic Zn coating to control the

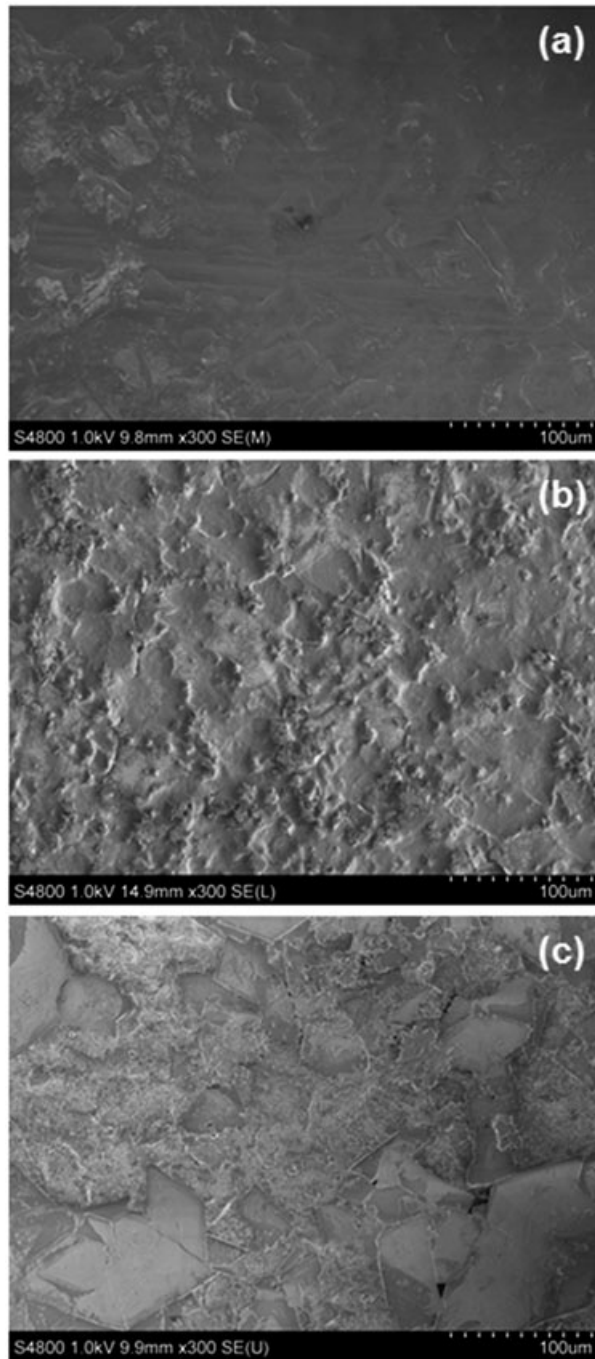


Figure 2. Scanning electron microscopy (SEM) data for TiO₂ coated DX56 steel treated with (a) C8, (b) C12 or (c) C18.

structure of the intermetallic formed at the interface between the Zn coating and the underlying steel.²⁶ A broad O 1s signal at 531.70 eV also confirms the presence of surface oxide,²⁶ mostly ZnO for the DX56 substrate. Figure 3 shows that, after Ti(OiPr)₄ treatment, Ti 2p_{1/2} and Ti 2p_{3/2} peaks are observed at 458.0 and 463.7 eV in agreement with previous studies.^{29–31} The O 1s signal also splits into two peaks at 531.2 and 529.5 eV for ZnO and the newly formed TiO₂.³²

TiO₂-coated DX56 treated with **C8** shows an intense F 1s photoelectron peak at 689.9 eV (S14) confirming the presence of fluorine on the surface.³³ A C 1s peak centred at approximately 291.8 eV de-convolutes to reveal the presence of C = O, CF₂, and CF₃ moieties for the fluorinated carboxylic acid³⁴ (Figure 3). For the TiO₂-coated DX56 treated with **C12** or **C18**, the C 1s peak envelopes de-convolutes to reveal the presence C = O, C–CO₂ and C–C components (Figure 3) as expected for these alkyl carboxylates. The assignments are in line with related studies for carboxylic acids binding to steel¹³ or iron oxide surfaces.¹⁰

As a way to compare the loadings of **C8**, **C12** and **C18**, the at% of C 1s was found to be 31.6%, 66.4% and 91.7%, respectively. In this context, for typical photo-electron kinetic energies (10–1000 eV), mean free path escape depths are 1–10 nm corresponding to 2–10 monolayers.³⁵ Thus, the lower at% of carbon and the higher intensity Zn 2p peaks for **C8** (3.7 at% Zn) suggest either poor coverage with substantial surface area not occupied by **C8** and/or a **C8** loading of 1–2 monolayers. For **C12**, the at% of C more than doubles whilst the Zn drops accordingly (1.2 at% Zn), suggesting either a higher coverage of **C12** and/or a multilayer **C12** loading. By comparison, the **C18** coating shows the highest at% for C along with the lowest intensity Zn 2p peaks (0.2 at% Zn) that suggests almost complete coverage of **C18** on the surface and/or a many multilayer loading of **C18**. To further understand loadings on TiO₂ surfaces, **C8**, **C12** or **C18** were sorbed onto Degussa P25 powder and then TGA was measured to study the mass loss following their combustion (S15 and S-Table 1). From these data, the mass of **C8**, **C12** or **C18** initially sorbed onto P25 was found to be 10.9%, 71.0% and 78.8%, respectively. After acetone washing, the sorbed masses of **C8**, **C12** or **C18** drop to 8.7%, 24.9% and 44.5%, respectively. Whilst these data show very little change in the **C8** loading after washing, the **C12** loading drops by almost two-thirds and **C18** drops by almost a half. These data correlate strongly with the IR data that lower peak intensities for the lubricity compounds (**C8**, **C12** or **C18**) spectra after acetone washing.

Assuming 10 mg of coated P25 TiO₂, the acetone-washed loadings correspond to 2.1, 12.4 and 15.6 μmoles of **C8**, **C12** or **C18**. Given that P25 has a surface area of approximately 50 m²g⁻¹,¹⁵ a 10 mg sample has a surface area of 0.5 m². The cross-sectional area of **C18** has been reported to be 20.7 Å².³⁶ Thus, to form a monolayer of **C18** on 10 mg of P25 should require 4.0 μmole of **C18**. Given that **C8** and **C12** both possess a similar carboxylate linkers to **C18**, it can be assumed that their cross-sectional areas should also be similar and thus should require similar loadings to achieve monolayer coverage. Thus, these data suggest an average of approximately 0.5, 3.0 and 4.0 monolayer coverage for **C8**, **C12** and **C18**, respectively.

Water contact angle measurements

The WCA of 'as received' DX56 galvanised steel were highly variable, which is ascribed to surface oil used to reduce corrosion in transit. After thorough cleaning, DX56 displays a more consistent WCA (55° ± 5°) (Figure 4). Whilst the WCA did not vary after Ti(OiPr)₄ treatment, the addition of either **C12** or **C18** generates hydrophobic surfaces with WCA of 88° ± 3° and 110° ± 8°, respectively, suggesting these surfaces have been covered by the carboxylic acids. Similar WCA values have been

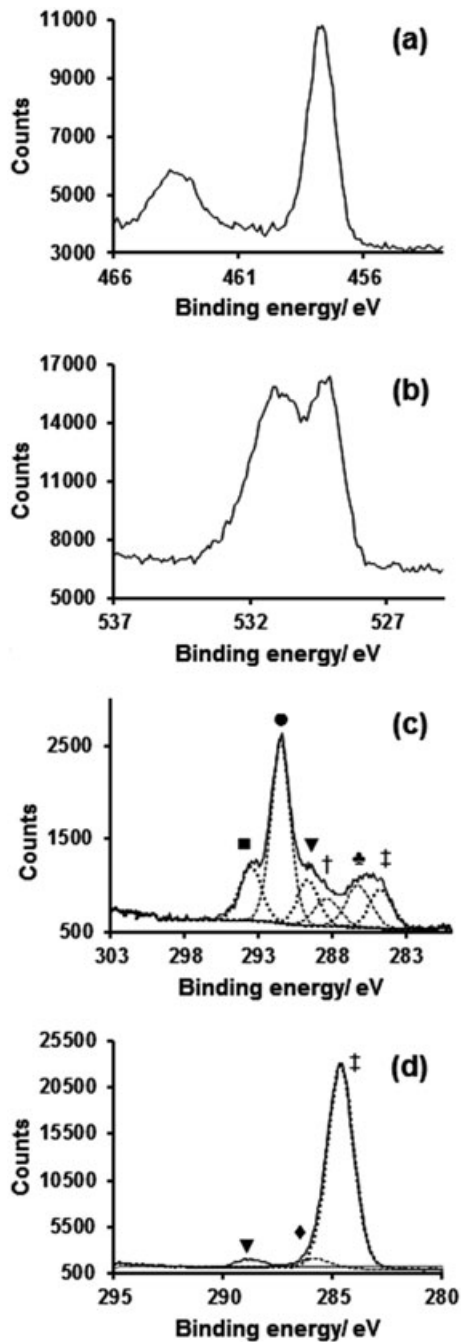


Figure 3. High resolution X ray photoelectron spectra of TiO_2 coated DX56 substrate (a) Ti 2p and (b) O 1s are regions. Other spectra show C 1s regions after treatment with (c) C8 or (d) C12. \blacktriangledown , C = O; \blacklozenge , $\text{C}-\text{CO}_2$; \ddagger , C - C; \blacksquare , CF_3 ; \bullet , CF_2 ; \dagger , COO; \clubsuit , C - O.

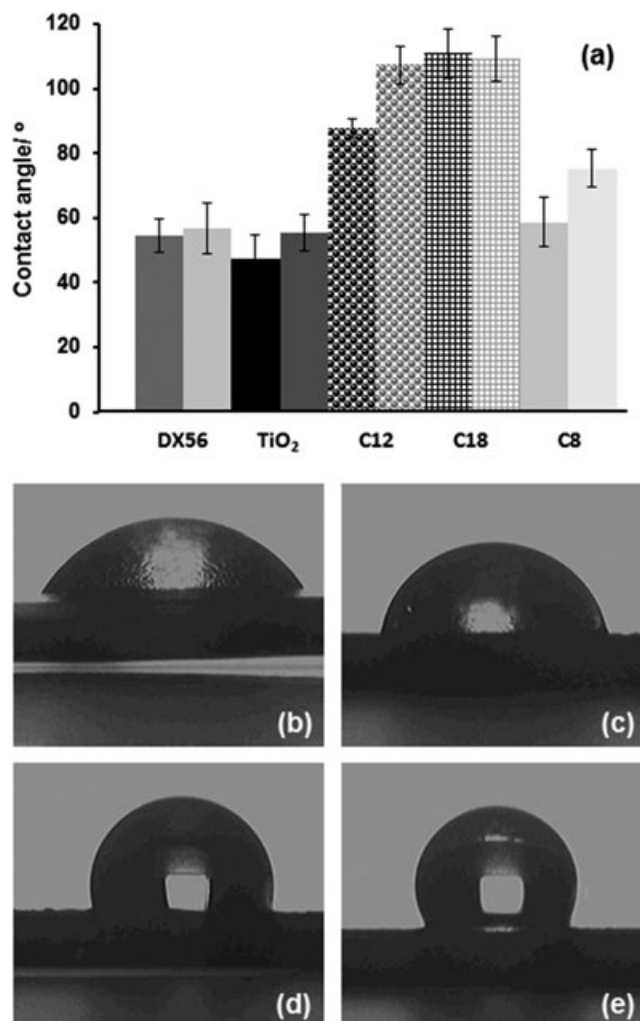


Figure 4. (a) Contact angles before (dark) and after (light) acetone rinsing and images for (b) TiO₂ coated DX56 and TiO₂ coated DX56 with (c) C8, (d) C12 and (e) C18.

reported for alkythiols on gold,³⁷ alkylsilanes on paper³⁸ and carboxylic acids on mica.³⁹ By comparison, the equivalent C8 samples display hydrophilic WCA similar to the TiO₂-coated and uncoated DX56 ($58^\circ \pm 7^\circ$). This may be due to lower or less homogeneous C8 surface coverage or potentially the formation of a C8 bilayer whereby a second layer of C8 molecules orient their carboxylic acid groups away from the surface, increasing interaction with droplet water molecules (Figure 6d). However, the TGA data for C8 adsorbed onto P25 TiO₂ show only 0.5 monolayer loading that suggests low coverage is the main reason for the low WCA value. To test this further, the WCA of acetone rinsed samples were also measured to ensure the removal of any physisorbed C8, C12 or C18.

As expected, acetone rinsing did not affect the WCA of DX56 or TiO₂-coated DX56. However, acetone rinsing **C8**-coated samples does increase WCA to 75° ± 6°, suggesting more of the surface consists of C F terminated chains. Similarly, the WCA of **C12** increases to 108° ± 6° in line with a more hydrophobic surface. In this case, removing physisorbed **C12** increases the proportion of the surface that is C H alkyl terminated. Finally, rinsing **C18**-coated samples does not change the WCA, which suggests that, prior to rinsing, the surface was already alkyl terminated (Figure 6d).

Linear friction testing

Coefficients of friction (μ) have been determined using LFT that is an aggressive tribological test, during which the galvanised coating is completely removed (Figure 5a). Figure 5b shows how μ varies along the samples. Cleaned DX56 shows the highest friction during the first 10 mm ($\mu > 0.35$), which then drops to between $\mu = 0.22$ – 0.30 . The initial increased friction observed may be due to several reasons including stick-slip behaviour resulting from substantial differences in roughness across the substrate surface, running in behaviour being influenced by surface roughness, the presence of a built-up transfer layer or adhesive friction between the tool and substrate. The dynamic value of μ (0.23) for TiO₂-coated DX56 suggests that adding TiO₂ to the surface does not influence lubricity. For the coated samples, μ displays little variation along the samples and this absence of variable friction behaviour suggests that surface coverage is sufficiently homogeneous to overcome substrate surface roughness.

Interestingly, the **C8** coating displays a dynamic μ of 0.20, which remains the same after acetone rinsing (Figure 5c). The high friction observed is in agreement with previous studies; high μ values have also been observed for perfluorinated carboxylic acids on silicon⁴⁰ and for perfluorinated phosphonates on copper.¹¹ High μ values have also been observed on related systems involving fluorinated⁴¹ or perfluorinated^{11,40} monolayers; discussions in the literature have attributed this to a number of factors including lower packing densities, relative to their hydrocarbon analogues, the molecular size of terminal groups and molecular disorder in the molecular films.⁴² By comparison, the **C12** and **C18** coatings give μ values of 0.11 and 0.10 (Figure 5c). This is in agreement with previously reported studies where large reductions in μ values have been reported for phosphonates on copper,¹¹ silanes on silicon,¹⁰ and carboxylic acids on Al⁷ and steel,⁹ wherein it is believed that energy dissipation occurs through steric quenching between neighbouring alkyl chains.⁴³ After acetone rinsing, the dynamic μ of **C12** and **C18** coatings remain the same, suggesting that sufficient chemisorbed material remains to imbue lubricity to these surfaces. Prior studies have shown that the stabilisation energy incurred through increasing the number (n) of methylene (CH₂) groups in a chain saturates between $n = 8$ – 10 .⁴³

Analysis of the wear tools using digital photography (S16) shows that, after LFT testing, there is less build up of larger zinc flakes on the wear tools that had been used to test the **C12** and **C18** coatings compared with the uncoated FF substrate that is in agreement with the LFT data that these coatings reduce the coefficient of friction for these samples. Also, in line with the wear tool imaging and LFT data, confocal microscopy (S17) shows smaller scratches for the **C12** and **C18** coatings that suggests that less material has been removed and hence that the wear is lower for these coatings.

A plot of μ versus WCA (Figure 6a) shows that a negative correlation exists between the coefficient of friction and surface wettability. This suggests that it should be possible to predict substrate lubricity from contact angle data because, whilst WCA data only provide averaged information across the surface area of the water droplet used, these data do provide a measure of the extent of functionalisation of surfaces. This is key because it has been reported that close-packed monolayers can facilitate low friction behaviour on some surfaces by enabling energy dissipation by steric quenching between

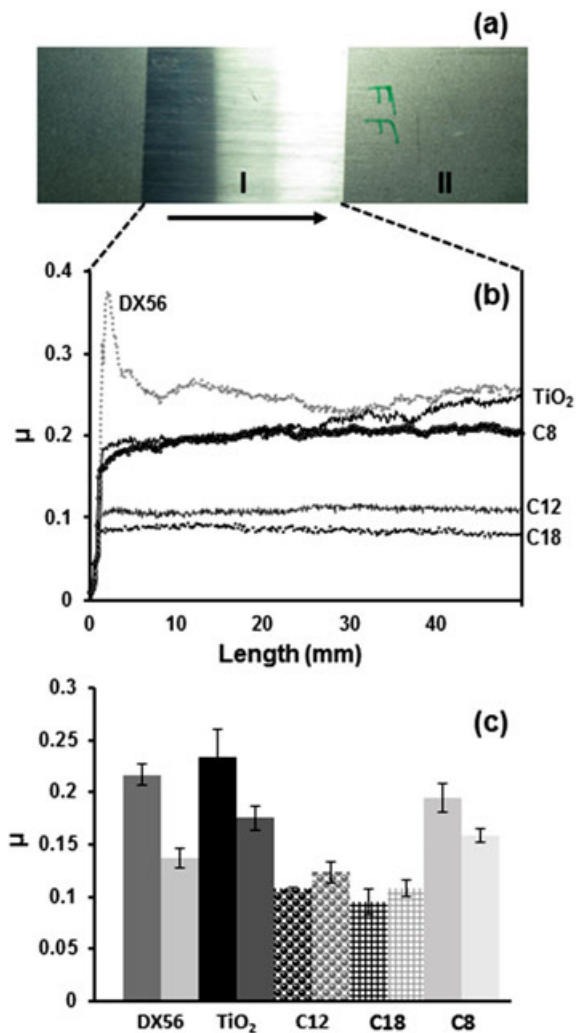


Figure 5. (a) Image of sample after linear friction testing, (b) dynamic coefficient of friction (μ) data and (c) mean μ for substrates before (dark shading) or after (light shading) acetone rinsing. DX56 steel (grey), TiO₂ coated DX56 (black) and DX56 coated with C12 (circles), C18 (hashed) and C8 (light grey). [Colour figure can be viewed at wileyonlinelibrary.com]

neighbouring alkyl chains during tribological contact.⁴³ Thus, whilst the correlation between WCA and μ effectively reflects surface coverage, the observed trend cannot take into account multiple layers and/or the molecular orientation within the surface films. However, with these provisos, our data do show that WCA can be used as a rapid screening method to identify substrate friction properties.

Applying this to our samples, for C8, this explains the high value of μ because the low surface coverage of C8 reduces intermolecular steric quenching, whilst uncoated areas possess no effective barrier during sliding (Figure 6c). By comparison, SEM and XPS data for the unrinsed C12 and C18 samples

INHERENT LUBRICITY SURFACES ON HDG STEEL

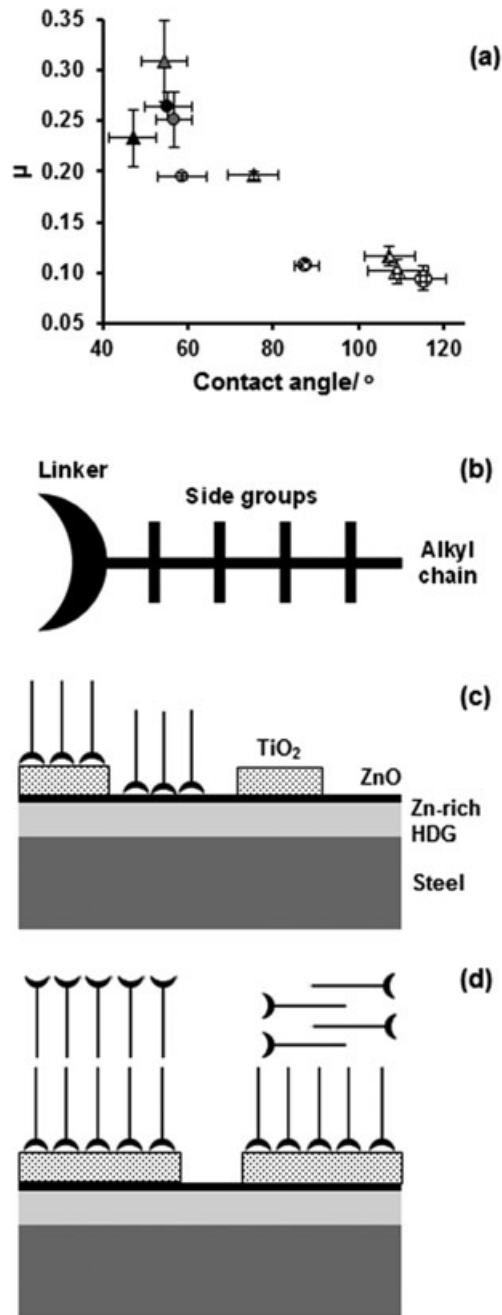


Figure 6. (a) Data for μ versus contact angle for DX56 steel (grey), TiO₂ coated DX56 steel (black) and DX56 steel with C12 (dotted), C18 (hashed) and C8 (open). Circles are before acetone rinsing, and triangles are after acetone rinsing, (b) schematic of lubricity compound, and proposed models for (c) monolayer and (d) multilayer coatings of carboxylic acids on DX56 steel.

show that the films are thicker than **C8**, show higher surface coverage and contain both physisorbed carboxylic acids and chemisorbed carboxylates (Figure 6c and 6d). Therefore, it is plausible to suggest that, prior to rinsing, the films act as more like barrier coatings, preventing interfacial contact between the substrate and tool during tribological contact. Interestingly, μ does not vary for these samples after solvent rinsing even though IR data shows that only chemisorbed carboxylates remain on the surface. This can be ascribed to the chemisorbed **C12** and **C18** carboxylates forming more ordered films where the alkyl chains are sufficiently ordered and close packed to enable steric quenching between neighbouring chains and thus to reduce frictional forces. This model for the structures of the coatings is shown (Figure 6b–6d). This shows that the TiO₂ layer formed as a result of dip coating process produces a partially covered surface. Between the TiO₂-rich areas is ZnO from oxidation of the Zn-rich galvanic layer. Where metal oxide is present, the carboxylic acids can then chemisorb through esterification to surface hydroxide groups to form a monolayer where the alkyl groups orient themselves away from the substrate surface. However, if the loading is high enough, additional layers can physisorb as shown in Figure 6d. Where free carboxylic acid groups orient themselves away from the substrate surface, it is possible for this to lower the WCA and increase μ . Whilst solvent rinsing can remove this physisorbed material, only de-esterification using strong base can remove the chemisorbed species.

CONCLUSIONS

Controlling surface lubricity is key for reducing wear during metal forming. At the same time, reducing waste and improving surface finish are driving the need to avoid oil-based lubrication and to reduce the substrate surface roughness required for such emulsions to work. Our approach to these problems has been to develop films that imbue inherent lubricity to metal surfaces. Whilst previous reports have suggested this is possible by pre-etching the substrate to remove surface oxide, we have instead attached monolayers of oriented alkyl chains directly to the oxide surface through carboxylate linkers. This approach is both cost-effective and scalable, and we have used it on substrates up to 30 cm in dimension. We have also screened different alkyl chain lengths and side groups (C F vs C H) and found that the initial deposits are thicker, multilayer films but that acetone washing removes physisorbed material for all the compounds tested. However, **C12** (lauric acid) is the most effective in terms of monolayer coverage, WCA and coefficient of friction. By comparison, **C8** (octanoic acid) shows low WCA and high μ whilst, for **C18** (stearic acid), phase-separated particles of **C18** are observed but, even after acetone rinsing, there is still too much material resulting in multilayer surface films. Whilst stearic acid is not expensive, this is still inefficient and wastes material. Through analysis of these data, it was also found that WCAs can act as an effective screening method for compounds that could increase the surface lubricity.

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SUPPORTING INFORMATION

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Fig. S1 LFT testing kit. Redrawn from T. Trzepieciniski, A. Bazan, H.G. Lemu, *Int. J. Automotive Tech.*, 2015, 16, 849.

Fig. S2 ATR-IR of neat (a) C8, (b) C12 and (c) C18

Fig. S3 ATR-IR spectra for (a) C8, (b) C12 or (c) C18 coated onto TiO₂-coated DX56 steel surfaces after acetone rinsing

Fig. S4 ATR-IR of C8 treated TiO₂-coated DX56 steel after desorption of C8 using NaOH(aq)

Fig. S5 Scanning electron microscopy (SEM) and energy dispersive x-ray spectroscopy (EDX) data for (a) DX56 steel after cleaning and (b) TiO₂-coated DX56. All EDX spectra recorded using 15.0 kV accelerating voltage.

Fig. S6 SEM and EDX data for (a) C8, (b) C12 and (c) C18 on TiO₂-coated DX56 steel. All EDX

spectra recorded using 15.0 kV accelerating voltage.

Fig. S7 AFM images of (a) DX56 and (c) associated line scan, (b) titanium isopropoxide treated DX56 and (d) associated line scan.

Fig. S8 AFM images of (a) C8 surface and (c) associated line scan, (b) C8 surface after acetone rinsing and (d) associated line scan.

Fig. S9 AFM images of (a) C12 surface and (c) associated line scan, (b) C12 surface after acetone rinsing and (d) associated line scan.

Fig. S10 AFM images of (a) C18 surface and (c) associated line scan, (b) C18 surface after acetone rinsing and (d) associated line scan.

Fig. S11 X-ray diffraction patterns of (a) DX56 steel substrate and (b) C18 deposited onto DX56 showing additional stearate signals at values of $2\theta < 13^\circ$ (†)

Fig. S12 Clockwise from left: Zn 2p, C 1s, O 1s, and Al 2p high resolution XPS data for cleaned DX56 steel

Fig. S13 (Clockwise from top left) XPS survey data of DX56 substrate, TiO₂ coated-DX56 and C12, C18 and C8 deposited on TiO₂ coated-DX56.

Fig. S14 F 1s high resolution XPS data for C8 coated on TiO₂-coated DX56 steel.

Fig. S15 TGA of lubricity compounds (a) deposited onto P25 titania and (b) deposited onto P25 titania and then acetone washed. Data show C8 (blue line), C12 (green line) and C18 (brown line).

Fig. S16 Images of flat tools (a) before LFT testing and after LFT testing of (b) DX56 substrate, (c) TiO₂ coated-DX56, (d) C8, (e) C12 and (f) C18 coatings

Fig. S17 Confocal images of DX56 substrate (a) before and (b) after contact with LFT flat tool, TiO₂ coated-DX56 substrate (c) before and (d) after contact with LFT flat tool, C8 substrate (e) before and (f) after contact with LFT flat tool, C12 substrate (g) before and (h) after contact with LFT flat tool, and C18 substrate (i) before and (j) after contact with LFT flat tool.

Table. S1 Weight losses from TGA data for C8, C12 and C18 adsorbed onto P25 titania either before or after acetone washing. Standard deviations of n = 3 replicates are shown in parentheses