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Key Points:

- Generalized method of estimating dissipation rate from Seagliders filtered by stratification increases scope of ocean turbulence estimates
- Annual cycle of turbulent dissipation in the top 1,000 m in the North Atlantic reveals seasonal cycle of mixing
- One-dimensional scaling for wind- and buoyancy-derived turbulence explains annual cycle of dissipation

Supporting Information:

• Supporting Information S1

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Annual Cycle of Turbulent Dissipation Estimated from Seagliders

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Abstract The rate of dissipation of turbulent kinetic energy is estimated using Seaglider observations of vertical water velocity in the midlatitude North Atlantic. This estimate is based on the large-eddy method, allowing the use of measurements of turbulent energy at large scales O(1-10 m) to diagnose the rate of energy dissipated through viscous processes at scales O(1 mm). The Seaglider data considered here were obtained in a region of high stratification $(1 \times 10^{-4} < N < 1 \times 10^{-2} \text{s}^{-1})$, where previous implementations of this method fail. The large-eddy method is generalized to high-stratification by high-pass filtering vertical velocity with a cutoff dependent on the local buoyancy frequency, producing a year-long time series of dissipation rate spanning the uppermost 1,000 m with subdaily resolution. This is compared to the dissipation rate estimated from a moored 600 kHz acoustic Doppler current profiler. The variability of the Seaglider-based dissipation correlates with one-dimensional scalings of wind- and buoyancy-driven mixed-layer turbulence.

Plain Language Summary Measuring ocean turbulence is crucial for understanding how heat and carbon dioxide are transferred from the atmosphere to the deep ocean. However, measurements of ocean turbulence are sparse. Here autonomous Seagliders are used to estimate turbulence in the surface kilometer of the North Atlantic Ocean. Using an estimate of the vertical water velocity from the flight of the Seaglider through the water, we estimate turbulence by assuming the energy of the largest turbulent fluctuations is representative of the energy dissipated at molecular scales. This approach has been used previously in an ocean region where the vertical gradient of density is small. Our results show that this previous approach fails when the vertical density gradient increases, as it does not account for other processes that are unrelated to turbulence. We introduce a generalized method that isolates only the turbulent processes by accounting for the strength of the vertical density gradient. We show that this new estimate agrees with other turbulence measurements. Our estimate also agrees well with a simple estimates of turbulence from atmospheric processes. This study therefore presents method that can be applied to existing and new Seaglider data to greatly increase our measurements of ocean turbulence.

1. Introduction

The exchange of heat, momentum, and carbon dioxide between the atmosphere and ocean is governed by the turbulent processes that occur within the mixed layer. These turbulent processes are driven by interactions between wind, waves, surface buoyancy loss, and horizontal buoyancy gradients in the upper ocean. Classical one-dimensional representations of mixed layer turbulence rely on simple scalings of surface forcing due to surface buoyancy loss and wind stress (Gargett, 1989; Large et al., 1994; Pollard et al., 1972; Tennekes & Lumley, 1972; Thorpe, 2005; Shay & Gregg, 1984). Recent advances in the theory of submesoscale processes suggest an important role in the generation of turbulence for instabilities associated with strong horizontal buoyancy gradients and for Langmuir turbulence from the interaction between the mean flow and Stokes drift (Belcher et al., 2012; Buckingham et al., 2016; Hoskins, 1982; Li et al., 2017; Thomas et al., 2013, 2016). The relevance of one-dimensional representations of ocean turbulence compared to those associated with



three-dimensional submesoscale motions remains an important question, particularly for simulating accurate mixed layer depths in ocean climate models (Belcher et al., 2012).

Oceanic turbulence acts to enhance the mixing of momentum, heat, salt and carbon compared to the rates associated with molecular diffusion (Tennekes & Lumley, 1972). The dissipation of turbulent kinetic energy at rate ϵ and the associated energy lost through viscous processes therefore acts as an important sink in the global ocean energy budget, balancing the energy input to the ocean by wind and the sun (Ferrari & Wunsch, 2008; Wunsch & Ferrari, 2004). Turbulence exists at scales of $O(10^{-3}$ to 10^{1})m and is therefore not resolved in a wide spectrum of numerical models. It is instead parameterized as a scalar "eddy diffusivity," the suitability of which depends on how well turbulent processes are understood (e.g., Griffies et al., 2005). Further, the mixing associated with oceanic turbulence also impacts the rates of biological production and associated carbon export by affecting the vertical distribution of nutrients and plankton within the nutrient-limited euphotic zone (Sarmiento & Gruber, 2006). Yet estimates of the magnitude, variability, and spatial distribution of dissipation both within and below the mixed layer remain scarce.

Estimates of dissipation are traditionally limited to point estimates from vertical microstructure profilers (Sheen et al., 2013). These provide very high resolution data in the vertical but have limited spatial and temporal coverage. Other direct estimates involve tethered/bottom mounted acoustic Doppler current profilers (ADCP), which give very high temporal coverage during the course of a mooring deployment but provide limited spatial or vertical information (Lucas et al., 2014; Polzin et al., 2014). Indirect estimates of the enhanced mixing associated with turbulence (i.e., those that do not physically measure turbulent overturns) are derived from tracer release experiments or inverse methods. These provide a net rate of mixing based on the time- and space-integrated evolution of a tracer (Watson et al., 2013), or the balance assumed to maintain a steady state density field (Zika et al., 2010). Each method has some limitations, particularly in resolving the spatiotemporal variability of mixing that is critical to determine the underpinning physical processes. Recent developments utilizing the vertical water velocity estimated from Seagliders look to fill this gap by increasing the temporal and spatial coverage of direct dissipation estimates, given the long endurance (4–6 months) of autonomous Seaglider missions (Beaird et al., 2012).

In this article, we present a year-long time series of the estimated dissipation rate from the surface to 1,000 m and assess the processes that drive changes in the depth of the actively mixing layer in the upper ocean. This reveals that upper-ocean dissipation can be largely explained by simple classical scalings for the turbulence generated by the buoyancy fluxes and wind stress acting on the sea surface. Previous estimates of turbulent dissipation from Seagliders use the large-eddy method (LEM), in which the kinetic energy of the largest turbulent eddies is assumed to feed turbulent dissipation at the smallest scales. A key step in this method is to separate internal wave motions from turbulent eddies. Beaird et al. (2012) found that a 30-m high-pass filter was appropriate to separate waves from overturns in the subpolar North Atlantic. Here we generalize the method by developing a filter with a cutoff dependent on the local buoyancy frequency, which sets the high-frequency limit of the internal wave band (D'Asaro & Lien, 2000).

In the following section, we introduce the Seaglider data set and detail the methodology used to estimate the rate of dissipation. We also outline a set of classical scalings for upper-ocean dissipation. In section 3, we compare the Seaglider-based estimate of dissipation rate to an independent estimate from a moored ADCP, and assess the agreement between the Seaglider-derived dissipation and the classical scalings for upper-ocean dissipation. In the final section, we summarize the results of this study.

2. Data and Methods

Temperature, salinity and pressure profiles from Seagliders in the northeast Atlantic were used to estimate the dissipation of turbulent kinetic energy by applying the LEM. Seagliders are autonomous underwater vehicles that control their position within the water column by pumping oil in and out of an external bladder, thus varying their density by adjusting their volume (Eriksen et al., 2001). Seaglider missions are typically designed to profile vertically (from the surface to 1,000 m) in a sawtooth fashion, transmitting the data collected by onboard conductivity, temperature, and pressure sensors via satellite at the sea surface. The Seaglider data used in this analysis were collected as part of the Ocean Surface Mixing, Ocean Submesoscale Interaction Study (OSMOSIS; NERC grant NE/I019999/1). The time series of Seaglider data is composed of three separate missions that are described in detail within Damerell et al. (2016) and Thompson et al. (2016). The complete time series extends from September 2012 to September 2013, and the three missions combine to give a total



of 4,099 profiles. The Seagliders sampled between 48.6°N, 48.8°N, 16.3°W and 16.1°W (Figure S6a in the supporting information; also see Figures 1, 3, and 4 in Thompson et al., 2016). The nominal sampling interval at depths less than 300 m is approximately 5 s but can be as high as 8-10 s depending on the control operations the glider performs. Below 300 m the nominal sampling frequency is ~ 10 s but may also be longer. The irregularity of the sampling interval and the change at 300 m can add noise to the energy spectra of vertical velocity.

Vertical water velocity is calculated by comparing the vertical profiling speed of the Seaglider to an idealized model of the Seaglider flight determined from the vertical density profile and the lift/drag/buoyancy characteristics of the Seaglider (Frajka-Williams et al., 2011). Following from Frajka-Williams et al. (2011) we remove data from the 25-s period following a controlled change in the glider roll or pitch. Further, we discard data within 40 m of the profile apogees. During controlled glider maneuvers the assumption of steady flight that is critical to the glider flight model does not hold.

The scale of turbulent dissipation in the ocean is on the order of millimeters. Gliders cannot measure at this scale, so a dissipation rate estimate from glider vertical velocity must rely on a scaling of the turbulent kinetic energy equation. The scaling used here is the LEM applied to Seaglider data (Beaird et al., 2012). This scaling is based on the assumption of a steady cascade of energy from the largest scales of turbulent motions to the viscous scales at which energy is dissipated (Moum, 1996; Taylor, 1935). In steady state and assuming no leakage of energy, dissipation at viscous scales can therefore be determined from the kinetic energy velocity scale (q') in the largest turbulent eddies of O(1-10) m and their overturning time scale yielding $\epsilon \sim (q')^3/l$ (Gargett, 1999). The scales of the largest turbulent eddies are resolved by glider sampling.

The choice of the turbulence length scale I is an important one and is ideally represented by the Thorpe length scale if high-resolution vertical density profiles are available (Thorpe, 1977). Alternative estimates of I have been extensively discussed in previous studies (e.g., Gargett, 1999). The Ozmidov length scale, $L_{Oz} = \epsilon^{1/2} N^{-3/2}$, is one such scale and is the largest turbulent eddy that is unaffected by stratification (Dillon, 1982). Observations suggest a linear relationship between the Thrope length scale and the Ozmidov length scale, both within the weakly stratified mixed layer and strongly stratified pycnocline (Dillon, 1982; Ferron et al., 1998; Wesson & Gregg, 2012).

Beaird et al. (2012) applied the LEM in estimating dissipation from glider vertical velocity using observations from the weakly stratified subpolar North Atlantic. Using the Ozmidov length scale for I, they present an estimate of dissipation in terms of a velocity scale q' and the buoyancy frequency N as

$$e = c_c N(q')^2, \tag{1}$$

where c_{ϵ} is a constant of proportionality that acts to scale the estimate of the rate of dissipation (e) relative to a direct measurement of this variable. To calculate N, we adiabatically redistribute (sort) fluid parcels according to the methodology outlined in Bray and Fofonoff (1981). This represents the background stratification acting to restore a turbulent overturn. When computed using a sorted N, the Ozmidov length scale matches the Thorpe length scale even in the mixed layer (Dillon, 1982). Within this data set, when computed using the unsorted density profile, \sim 28% of mixed layer N data points are negative. The velocity scale q' is defined as the rms of the vertical velocity.

To estimate the rate of dissipation from the vertical water velocity, Beaird et al. (2012) first filter vertical velocity to remove low-frequency internal wave variability using a high-pass filter with a fixed 30-m cutoff. When applied here in more strongly stratified waters, this cutoff wavelength fails to remove internal wave variability as the vertical stratification is stronger and more variable. Freely propagating internal waves have frequencies (ω) in the range $f < \omega < N$ where f is the Coriolis parameter (D'Asaro & Lien, 2000). Here we use an alternative approach to define q' by using an adaptive high-pass fourth-order Butterworth filter set to the value of the vertical stratification N. When N is large, this filter should isolate turbulent processes within the inertial subrange. When N is very low, within the surface mixed layer for example, this filtering acts to remove the mean and any trend with respect to depth from the vertical velocity. Note that in the case of an inadequately tuned flight or flight model, spurious vertical velocity signals may appear as a mean or trend with depth (Frajka-Williams et al., 2011) Dissipation is calculated in 20-m vertical bins from the surface to 900 m. To validate the LEM method, we use a time series of dissipation estimated from a moored 600-kHz ADCP (deployed as part of the OSMOSIS field campaign) using the structure function method outlined in Lucas et al. (2014) and within the supporting information (Guerra & Thomson, 2017; Horwitz & Hay, 2017; Lhermitte, 1969; Liu et al., 2011;



Lorke, 2007; Lorke et al., 2008; McCaffrey et al., 2015; McMillan & Hay, 2017; McMillan et al., 2016; Mohrholz et al., 2008; RDInstruments, 2011; Rippeth et al., 2003; Rudnick & Cole, 2011; Rumyantseva et al., 2015; Sauvageot, 1992; Scannell et al., 2017; Simpson et al., 2011, 2015; Talke et al., 2013; Thomson et al., 2010, 2012; Wiles et al., 2006; Zedel et al., 1996). The ADCP is mounted at \sim 50 m on the central mooring (48.7°N, 16.2°W) of the OSMOSIS mooring array (Buckingham et al., 2016; Damerell et al., 2016), providing a full annual time series of the rate of dissipation coinciding with the glider deployments.

As an alternative to the Ozmidov length scale, we computed e using Thorpe length scales. This approach underestimated the dissipation rate below the mixed layer, but matched the magnitude of the ADCP-based dissipation rate when the mixed layer deepened to below the depth of the ADCP. The low vertical sampling resolution (\sim 0.8–1.5 m) of the Seaglider-based density profile likely results in an overestimate of Thorpe length scales, and an underestimate of e when N is high. Beaird et al. (2012) describe similar issues when using the Thorpe length scale for e when applying the LEM. Consequently, we use the Ozmidov length scale throughout.

There are some general limitations to this approach that should be noted. As mentioned above, the glider flight model assumes steady flight. Controlled changes to the glider roll and pitch can be limited by increasing the interval at which the glider activates the guidance and control systems. This is not practical near the surface and at apogee, which is why we remove data within 40 m of the profile apogee. Consequently, our dissipation rate estimate will miss some of the surface mixed layer that is shallower than 40 m. We indicate periods within the glider time series when excessive roll maneuvers affect the dissipation rate estimate. Further, to determine c_{e^*} comparison to an existing estimate of dissipation rate is required, which should cover a representative range of dissipations. Here we utilize a time series of dissipation rate estimated from the moored 600 kHz ADCP, as this has been evaluated against direct estimates of dissipation rate from microstructure profilers. The value of c_{e} and the magnitude of e is therefore dependent on any uncertainty in the ADCP-based dissipation rate.

Further considerations were required for the Seaglider data specific to this study due to the irregular sampling interval of the glider's CTD, resulting in a step change in the estimated dissipation rate at 300 m. As discussed in the supporting information removing this step change required filtering with a band-pass filter with a low-frequency cutoff at *N* and a high-frequency cutoff at 1/60 s (Lomb, 1976).

We compare the updated glider estimate of dissipation rate to the dissipation rate expected from surface air-sea heat fluxes and wind-stress using daily fields for shortwave radiation, longwave radiation, latent heat flux, sensible heat flux, and 10-m winds from the ERA-Interim reanalysis product (Dee et al., 2011). Using fields with a horizontal resolution of 0.75° , data were selected from the grid cell at 48.75° N and 16.5° W to coincide with the glider data. Wind stress is calculated based on the approach of Large and Pond (1981) and Trenberth et al. (1990) at low wind speeds (Figures S6b and S6c; our conclusions are not affected by the choice of wind-stress algorithm). When the Earth's rotation is ignored, the simplest estimates of turbulence in the mixed layer are governed by buoyant convection and wind-driven surface shear stress (Gargett, 1989; Shay & Gregg, 1984, 1986). Convection in the mixed layer is driven by a surface buoyancy flux B_0 , given by

$$B_0 = -g\rho^{-1}[\alpha c_p^{-1}(Q_{SW} + Q_{LW} + Q_{LH} + Q_{SH}) + \beta Q_{LH}L^{-1}S],$$
 (2)

where g is the acceleration due to gravity, ρ the mixed layer density, c_p the specific heat capacity of seawater ($\sim 4 \times 10^3 \, \mathrm{J \, kg^{-1} \, K^{-1}}$), L the latent heat of evaporation ($\sim 2.5 \times 10^6 \, \mathrm{J/kg}$) and S the mixed layer salinity (Shay & Gregg, 1986). The coefficients α and β represent the thermal expansion and haline contraction of seawater, while Q_{SW} , Q_{LW} , Q_{LH} , and Q_{SH} are heat fluxes due to incoming short wave radiation, outgoing longwave radiation, the latent heat of evaporation and sensible heat flux, respectively. Assuming a linear decrease through the mixed layer (Gargett, 1989), B_0 gives an estimate of the dissipation of turbulent kinetic energy by convection (ϵ_O) as

$$\epsilon_Q = \frac{1}{2} B_0 H \tag{3}$$

where H is the mixed layer depth, determined here as the depth at which the density exceeds the density at 10 m by 0.03 kg/m³.

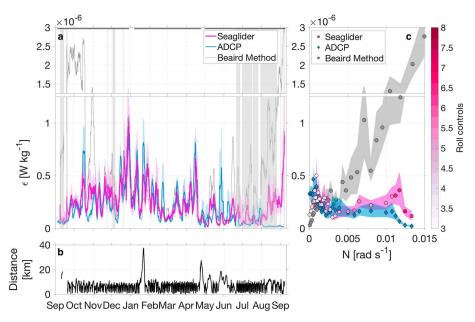


Figure 1. (a) Seaglider-based rate of dissipation (magenta) compared to dissipation rate estimated using the ADCP-based structure function approach (blue) and the original Beaird et al. (2012) method to estimate dissipation from glider observations using a fixed 30 m high-pass filter (gray). Time series are smoothed using a 4-day running mean. The colored shading shows the 90% confidence interval determined using a Monte Carlo approach. The gray shading indicates periods of excessive glider roll maneuvers. An estimate of glider-based dissipation rate is flagged when the number of roll maneuvers in a given 20 m depth bin exceeds 6. The gray shading indicates periods in which more than half the data used to calculate the 4-day average is flagged. The horizontal black bars denote individual glider deployments. (b) Distance between the Seaglider and the ADCP. (c) Seaglider- and ADCP-based dissipation rates averaged into bins of buoyancy frequency, N. Each N-bin contains 100 glider observations. The color of the glider data points indicates the mean number of glider roll maneuvers. The colored shading shows the 90% confidence interval determined using a Monte Carlo approach. ADCP = acoustic Doppler current profiler.

An estimate of the rate of dissipation associated with wind-driven turbulence (ϵ_{τ}) can be made by using the wall-layer scaling (e.g., Tennekes & Lumley, 1972; Thorpe, 2005) for the vertical extent of shear-driven eddies

$$\epsilon_{\tau} = \int_{-H}^{0} \frac{u_{*}^{3}}{\kappa z} dz,\tag{4}$$

where $\kappa = 0.4$ is the von Karman constant and z depth. The scale u_* for vertical turbulent velocities is determined from the surface wind stress τ as

$$u_* = \sqrt{\frac{\tau}{\rho}}. (5)$$

Dissipation due to breaking surface waves is likely to be one order of magnitude greater than ϵ_Q and ϵ_r . However, as discussed above, we do not use the glider dissipation at depths less than 40 m. These depths are beyond the influence of breaking surface waves and will not capture a substantial portion of the wind-driven turbulence. (Gargett, 1989; Thorpe, 2005).

3. Results

In order to estimate the rate of dissipation using the methodology described in section 2, the value of c_e must be determined by comparison with a simultaneous estimate of the dissipation. Here we compare the glider estimate of dissipation rate to a time series of dissipation calculated from the moored 600 kHz ADCP (Figure 1). The nearest depth bin to the measured ADCP depth is selected from the Seaglider estimate of dissipation. A linear least squares fit between the three glider deployments and the ADCP dissipation rate estimate yields $c_e = 1.96 \pm 0.2$. The full time series are displayed in Figure 1a, with confidence intervals computed at the 90% level using a Monte Carlo approach. We perform 5,000 simulations for which we randomly sample 90% of the

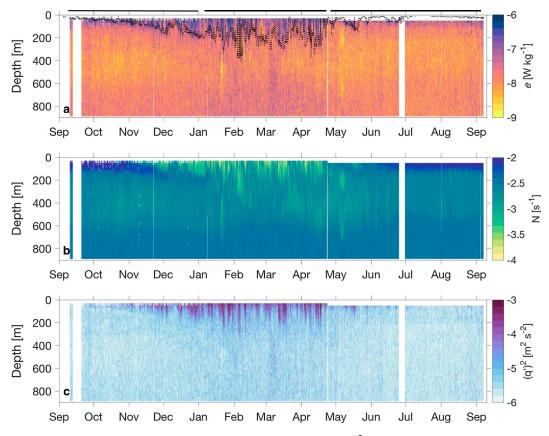


Figure 2. Time series of (a) Seaglider-based dissipation rate e, (b) N and (c) $(q')^2$ from equation (1). Each variable is calculated in 20-m vertical bins from the surface to 900 m. The black line represents the mixed layer depth determined as the depth at which density exceeds the density at 10 m by $0.03 \, \text{kg/m}^3$. The horizontal black bars indicate each individual glider deployment.

data points with replacement used to determine the displayed 4-day mean. The glider and ADCP estimates of dissipation rate generally agree within the confidence interval of the glider estimate, except during periods of excessive glider roll maneuvers, indicated by the gray shading (also see Figure S7).

During the first two glider deployments, from September 2012 to April 2013, when stratification at the ADCP depth was weakening in the transition to winter, the glider and ADCP estimates show dissipation levels of 10^{-7} to 10^{-6} W/kg, with good agreement illustrated by a correlation coefficient between the filtered time series of R=0.81 (Figure 1a). From May onwards, during the third glider deployment, there are sporadic periods of disagreement. In May and June, agreement was poor when the glider is a distance of >10 km from the ADCP mooring. Conversely, in January when the distance between the glider and ADCP mooring increases beyond 10 km, the agreement between dissipation estimates remains good. This may suggest that turbulence levels are coherent over a lateral extent of O(10) km in the winter, and less so in May/June. Agreement between the glider and ADCP was also poor in August to September 2013 when excessive glider rolling reduced reliability (gray shading; Figure 1a). The glider and ADCP dissipation averaged into bins of buoyancy frequency N also suggest a good agreement between ADCP and glider estimates (Figure 1c). At low N, the glider estimate appears to underestimate the rate of dissipation, associated with periods when the glider dissipation falls short of peaks in ADCP dissipation during the winter. The agreement is also less good at some high values of N, but the glider data are affected by excessive roll maneuvers.

A comparison between the method used here to estimate dissipation rate from glider measurements and the method outlined in Beaird et al. (2012) is also made in Figures 1a and 1c. This indicates that the generalized method described here better estimates the rate of dissipation during summer and autumn/fall, when the Beaird et al. (2012) method overestimates dissipation. Stratification is highest during these periods, and a filter that passes variations with a wavelength less than 30 m seems to be insufficient to remove internal

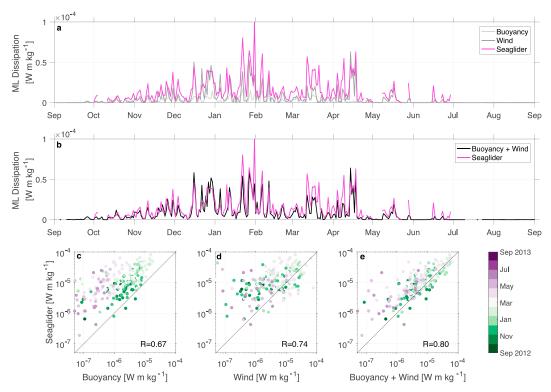


Figure 3. (a) Seaglider-based dissipation rate integrated through the mixed layer (magenta), mixed layer dissipation rate induced by surface buoyancy forcing (light gray; ϵ_Q from equation (3)) and mixed layer dissipation rate induced by surface wind forcing (dark gray; ϵ_{τ} from equation (4)). (b) Mixed layer glider dissipation rate (magenta) and $\epsilon_Q + \epsilon_{\tau}$ (black). (c-e) Mixed layer glider dissipation rate plotted against ϵ_Q , ϵ_{τ} , and $\epsilon_Q + \epsilon_{\tau}$, with colors representing time.

wave-related signals. When averaged in to bins of N, the dissipation rate estimated using the Beaird et al. (2012) method underestimates the dissipation rate at low N and overestimates the dissipation at high N.

Using the scale factor (c_e) derived from the glider/ADCP comparison, we can then estimate the full annual cycle of dissipation rate from the surface to 1,000 m at 48.7°N, 16.2°W (Figure 2a). In Figure 2 we include data shallower than 40 m, except during spring when data quality was poor due to excessive roll maneuvers (see Figures 1 and S7). No data shallower than 40 m was used for comparison with ADCP dissipation rate. Through the fall, coinciding with pulses in the dissipation rates of $O(10^{-6})$ W/kg, stratification breaks down as the mixed layer deepens. The mixed layer remains at a depth of approximately 200 m during January – April, reaching a maximum of ~400 m in February. Through the spring and early summer of 2013, the mixed layer shoals rapidly as stratification increases. This shoaling is interspersed with daily to weekly changes in mixed layer depth that correspond to sporadic periods of elevated dissipation. Below the mixed layer, the vertical profile of dissipation reaches a minimum of $O(10^{-9})$ W/kg between 200 and 600 m where stratification is weakest. Below 600 m the estimated dissipation is higher where stratification is elevated.

Previous analyses in this region have focussed on the importance of submesoscale instabilities in driving elevated turbulence within the mixed layer (Thompson et al., 2016). Here to understand the processes that govern dissipation within the upper ocean, we compare simple scalings for turbulence due to surface buoyancy loss and wind stress to the mixed layer-integrated glider dissipation neglecting dissipation shallower than 40 m (Figure 3). Below 40 m, we do not expect our glider estimate to be influenced by surface waves, which influence the profile of ϵ within a few significant wave heights of the surface (D'Asaro, 2014). In general, wind-driven mixed layer dissipation is higher than dissipation by buoyant convection, more closely matching the magnitude of the glider dissipation rate (Figures 3a, 3c, and 3d). The relative contributions of wind stress and buoyant convection do however vary throughout the year. For example, from September through November, as the mixed layer deepens, the dissipation rates induced by wind forcing and buoyancy loss are mostly comparable. During this period, surface buoyancy loss is dominant, while the peaks in wind-induced dissipation are typically less than those during winter (Figures S6b and S6c).



From December to April, the contribution of wind forcing is greater than that of buoyancy loss, increasing the contribution of wind-driven upper-ocean dissipation to around 70% of the total. As the mixed layer shoals from April onwards, the surface buoyancy flux changes sign, driving less buoyant convection, so that the contribution of wind-driven dissipation increases to around 90%. A strong correlation between the glider-derived upper-ocean dissipation rate and both time series of buoyancy- and wind-driven dissipation suggests that these simple scalings for the effects of wind- and buoyancy-driven turbulence can explain much of the variation in the observed upper-ocean dissipation. The agreement with the glider-based dissipation rate is particularly strong for the combined buoyancy and wind contributions (R = 0.80). These results suggest that upper-ocean dissipation in this area at depths beyond the influence of surface waves, may be characterized by one-dimensional estimates of turbulence induced by air-sea buoyancy fluxes and wind forcing. Further, this comparison demonstrates the changing nature of mixed layer dissipation throughout the year. The wintertime deepening of the mixed layer is driven almost equally by surface buoyancy loss and wind forcing. During the spring however, wind forcing drives the sporadic mixing (and mixed layer deepening) as surface buoyancy gain induces a general shoaling of the mixed layer.

There are short periods when the glider-derived dissipation is elevated and the one-dimensional estimates of turbulence are low, during January, February and March for example. At these times there are several peaks glider dissipation rate that are a factor of two larger than the one-dimensional estimate of turbulence. A comparison with the results of Thompson et al. (2016) suggest these periods of disagreement broadly coincide with times at which three-dimensional submesoscale instabilities are more likely. The glider-derived dissipation rate compares well in terms of both magnitude and variability with the ADCP-derived dissipation and matches the variability of estimates from one-dimensional mixed layer scalings. This gives confidence in the validity of our our glider-derived estimate, through a range of stratification levels. Further, these results suggest that in this region submesoscale instabilities may play a lesser role in driving turbulent dissipation in the upper ocean in contrast to findings in western boundary current environments (D'Asaro et al., 2011).

4. Conclusions

This study documents a full annual cycle of surface to 1,000-m turbulent dissipation rate in the ocean, and the physical forcings of its variability. It provides insight into the seasonal variation of the turbulent dissipation in the midlatitude North Atlantic within the mixed layer, and the relationship between upper-ocean dissipation and the depth of the mixed layer. Further, this analysis highlights the key processes that drive dissipation within the upper ocean and regulate the depth of the ocean surface boundary layer. These results were obtained by generalizing the method to determine turbulent dissipation from standard Seaglider measurements (Beaird et al., 2012) to a wider range of stratification levels. Upper-ocean dissipation is characterized by pulses of elevated turbulence that extend through most of the mixed layer and correspond to periods of a deepening mixed layer. These pulses of dissipation and daily-to-weekly changes in the depth of the mixed layer occur during both winter and spring, as the mixed layer deepens or shoals, respectively.

Here simple one-dimensional estimates of the mixed layer dissipation driven by air-sea buoyancy and wind forcings capture most of the observed variability of dissipation within the mixed layer deeper than 40 m. This allows a dissection of the relative roles of buoyancy and wind forcings in driving variability in the mixed layer. While buoyancy and wind forcings play a comparable role in the early winter as the mixed layer deepens, wind forcing dominates as a driver of mixed layer dissipation through the rest of the year. This generates, for example, the springtime pulses in dissipation that coincide with short-term deepenings of the mixed layer. Despite missing much of the wave-driven turbulence near the surface, the Seaglider-derived dissipation rate appears to capture the bulk of the variation of upper-ocean turbulence. Short-term deviations between estimates of dissipation rate and the classical forcing-based scalings may be associated with submesoscale processes (Thompson et al., 2016), the effects of which are not represented by the scalings used here. This paper introduces an updated method of determining dissipation rates from standard Seaglider observations, enabling depth-varying estimates of turbulence over many months. Application of this method to existing and future long-duration glider data sets promises further insights into the drivers of turbulent dissipation.

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