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Seabed morphology and bed shear stress predict temperate reef habitats in a high energy marine region

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29 Abstract

30 High energy marine regions host ecologically important habitats like temperate reefs, but are 31 less anthropogenically developed and understudied compared to lower energy waters. In the 32 marine environment direct habitat observation is limited to small spatial scales, and high 33 energy waters present additional logistical challenges and constraints. Semi-automated 34 predictive habitat mapping is a cost-effective tool to map benthic habitats across large extents, 35 but performance is context specific. High resolution environmental data used for predictive 36 mapping are often limited to bathymetry, acoustic backscatter and their derivatives. However, 37 hydrodynamic energy at the seabed is a critical habitat structuring factor and likely an 38 important, yet rarely incorporated, predictor of habitat composition and spatial patterning. 39 Here, we used a machine learning classification approach to map temperate reef substrate and 40 biogenic reef habitat in a tidal energy development area, incorporating bathymetric derivatives at multiple scales and simulated tidally induced seabed shear stress. We mapped reef substrate 41 42 (four classes: sediment (not reef), stony reef (low resemblance), stony reef (medium – high 43 resemblance) and bedrock reef) with overall balanced accuracy of 71.7%. Our model to predict 44 potential biogenic Sabellaria spinulosa reef performed less well with an overall balanced 45 accuracy of 63.4%. Despite low performance metrics for the target class of potential reef in this 46 model, it still provided insight into the importance of different environmental variables for 47 mapping *S. spinulosa* biogenic reef habitat. Tidally induced mean bed shear stress was one of the 48 most important predictor variables for both reef substrate and biogenic reef models, with 49 ruggedness calculated at multiple scales from 3 m to 140 m also important for the reef substrate 50 model. We identified previously unresolved relationships between temperate reef spatial 51 distribution, hydrodynamic energy and seabed three-dimensional structure in energetic waters. 52 Our findings contribute to a better understanding of the spatial ecology of high energy marine 53 ecosystems and will inform evidence-based decision making for sustainable development, 54 particularly within the growing tidal energy sector.

55

56 Keywords

- 57 Reef mapping, bathymetry, tidal energy, machine learning, seascape ecology, spatial scale,
- 58 Sabellaria spinulosa, benthic ecology, hydrodynamics, ecosystem management.

59 1. Introduction

60 To understand ecological pattern and process, reliable information about the spatial

61 distribution of habitats is essential (Brown et al., 2011; Cogan et al., 2009; Turner, 1989). Aerial 62 and satellite remote sensing has revolutionised spatial ecology, providing spatially continuous 63 data on a variety of ecologically relevant variables at high resolution across broad extents (Kerr 64 and Ostrovsky, 2003; McDermid et al., 2005). This type of information is more challenging to 65 collect for the seabed beyond the shallow clear waters that can be observed with optical remote 66 sensing (D'Urban Jackson et al., 2020; Lecours et al., 2015). Advances in acoustic remote sensing 67 now enable collection of high-resolution (< 1m), spatially continuous seabed bathymetry and 68 acoustic reflectivity (commonly referred to as backscatter). However, detailed seabed mapping 69 is still costly and inefficient compared to terrestrial remote sensing, such that less than 18% of 70 the oceans has depth measurements at 1 km resolution or better (Mayer et al., 2018). Other 71 seabed properties, including benthic habitat characteristics, are even more challenging to map. 72 Methods for observing seafloor habitats and organismal communities are limited to fine to 73 moderate spatial scales (0.01 m – 1 km) using diver, camera, crewed/uncrewed vehicle, acoustic 74 or physical sampling (van Rein et al., 2009). To generate spatially continuous benthic habitat 75 maps over large extents, practitioners use statistical approaches to identify relationships 76 between discrete habitat observations and spatially continuous environmental data and 77 extrapolate into unobserved locations (Brown et al., 2011).

78 Temperate reefs are hard-bottom marine habitats between the tropics and the poles, and 79 include biodiverse ecosystems that provide billions of dollars in ecosystem goods and services 80 (Bennett et al., 2016; Taylor, 1998). Temperate reef substrate may be bedrock or stony 81 (geogenic) or derived from organisms (biogenic), both hosting communities of sessile and 82 mobile reef-associated species (Bué et al., 2020; Diesing et al., 2009; Holbrook et al., 1990). Due 83 to their ecological importance reef habitats are listed in various national and international 84 conservation legislation, including Annex 1 of the European Commission Habitats Directive 85 (European Commission, 2013). However, a lack of information about the distribution and 86 characteristics of reef habitats hampers effective ecosystem management (Diesing et al., 2009). 87 Temperate reef habitats are often found in high energy marine waters (Warwick and Uncles, 88 1980). These areas are challenging and costly to operate within compared to lower energy seas 89 and as such they are less anthropogenically developed and less well studied (Shields et al., 90 2011). In response to the global demand for low carbon energy, energetic waters are now of 91 commercial interest to the nascent marine renewable energy industry (Roche et al., 2016). To 92 ensure sustainable development, there is a growing need for baseline ecosystem information 93 about energetic waters. While previous attempts at mapping temperate reefs have shown some

94 success, it has proved challenging to distinguish between specific reef types like bedrock and

- 95 stony reef, and between reef and non-reef ground without considerable manual input (Dalkin,
- 96 2008; Eggleton and Meadows, 2013; Limpenny et al., 2010; Plets et al., 2012; Vanstaen and
- 97 Eggleton, 2011). Biogenic temperate reefs are similarly challenging to map, typically requiring
- 98 manual interpretation and digitisation of acoustic information (Jenkins et al., 2018; Limpenny et
- al., 2010; Lindenbaum et al., 2008; Pearce et al., 2014). There is a growing need for repeatable,
- 100 cost-effective habitat mapping in high energy waters, to understand the spatial ecology of these
- 101 understudied ecosystems and to support sustainable management in an evolving seascape of
- 102 offshore activity (Dannheim et al., 2020; Jouffray et al., 2020; Wilding et al., 2017).

103 Bathymetry, backscatter intensity and their derivatives are typically the main, or only 104 environmental predictor variables in benthic habitat models beyond shallow, clear waters, as 105 few other variables can be recorded at a comparable resolution. However, numerous other 106 variables are important in structuring benthic habitats. For example, water chemistry and 107 temperature, when modelled at appropriate spatial scales, can be important predictors of 108 benthic habitats (Davies and Guinotte, 2011). Hydrodynamic energy at the seabed is an 109 important structuring factor for benthic habitats and communities. As well as imparting 110 mechanical stress (Gove et al., 2015; Koehl, 1999), water flow controls water chemistry 111 (Gutiérrez et al., 2008), particulate food supply (Rosenberg, 1995; Sebens et al., 1998) and larval 112 dispersal (Cowen and Sponaugle, 2009). Alteration of flow regimes affects feeding efficiency, 113 growth rates and settlement of benthic species that are adapted to specific flow conditions 114 (Eckman and Duggins, 1993). Critically, hydrodynamic energy affects substrate composition 115 through sediment transport (Shields, 1936), which in turn controls benthic community 116 composition and imparts temporal variation within the system (Coggan et al., 2012; Warwick 117 and Uncles, 1980). Hydrodynamic energy has proved to be an important variable for mapping 118 benthic habitat spatial distribution at regional and national scales with resolution of kilometres (Huang et al., 2011; Robinson et al., 2011), but it is often overlooked or unavailable for 119 120 predictive mapping at finer scales (Brown et al., 2011; Pearman et al., 2020). The inclusion of 121 simulated wave induced seabed energy improved predictive habitat mapping for a wave 122 exposed region in temperate southern Australia (Rattray et al., 2015), and it follows that tidally 123 induced seabed energy is likely to be an important predictor of high energy habitats in regions 124 with fast tidal currents. However, to our knowledge no study has incorporated tidally induced 125 energy at the seabed with high-resolution bathymetry for predictive habitat mapping in 126 temperate, high tidal energy waters.

127 Tidally induced hydrodynamic energy is likely to influence the distribution of geogenic and128 biogenic reefs in different ways. Strong tidal currents erode and transport sediment, leaving

- 129 stable substrates that may be colonised by epibiota to form geogenic reefs. For biogenic reefs,
- 130 the effects of hydrodynamic energy depend on the reef-forming organism. *Sabellaria spinulosa*
- 131 is a reef-forming annelid that builds aggregations of tubes from suspended coarse sediment,
- 132 supporting diverse associated communities (Pearce, 2017). *S. spinulosa* reef distribution is
- 133 likely to be influenced by the availability of resuspended sediment as tube-building material, in
- 134 turn driven by hydrodynamic energy (Davies et al., 2009; Holt et al., 1998). We used semi-
- 135 automated predictive mapping, parameterized with multibeam echo sounder derived variables
- and incorporating simulated hydrodynamic energy data, to map previously unresolved
- 137 potential reef habitats in a marine area of interest for tidal energy development. We show that
- tidally induced bed shear stress is a highly important variable for predicting high energy reef
- 139 habitats. Our findings provide a deeper understanding of the relationships between
- 140 hydrodynamic conditions, seabed morphology and reef habitats, with implications for
- 141 sustainable development of understudied, high tidal energy waters.

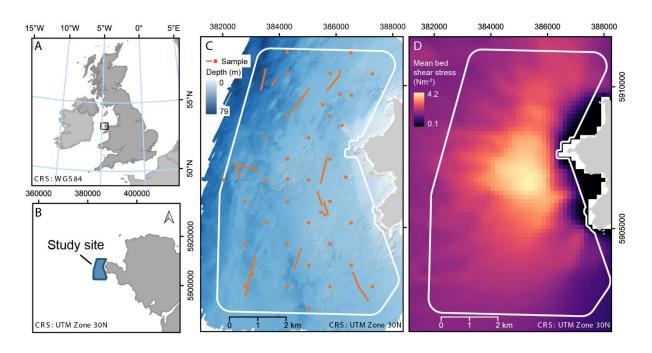




Figure 1. A & B) Location of the study site (black square in A) in north west Wales, UK. C) Bathymetry of
the study area (white boundary) showing point and transect drop-down video sampling locations. D)
Modelled tidally induced mean bed shear stress across the study area.

147 **2. Method**

148 2.1 Study Site

149 We mapped potential reef habitats in a 49 km² area to the west of Sir Ynys Môn (Isle of

Anglesey), Wales, UK (Fig. 1). Our study area comprised a 500 m buffer around a 35 km² area

151 leased for tidal energy device demonstration, which was then buffered inwards by 100 m from

152 the edge of input data extent to avoid edge effects. Tidal current speeds at the site reach 3.7 m s⁻

¹ and annual mean significant wave height is 1.26 to 1.5 m (Royal Haskoning DHV, 2019). Water

depth within the study area ranges from 3-79 m (Fig. 1C) and the seabed comprises a range of

155 benthic habitats from mobile sediment to stable cobble and bedrock colonised by slow growing

156 epifauna (Whitton, 2014). The site is known to contain potential reef, but the spatial

distribution of different reef types in the area is unresolved (MarineSpace, 2019).

158

159 2.2 Habitat Observations

160 We collected seabed video samples within the study site in June and July 2019 using the RV

161 Prince Madog (Fig. 1C, transect samples), with further samples obtained from a commercial

162 ecological survey of the study site (Fig. 1C, point samples). Sampling locations were spatially

163 well-distributed, captured a range of energy conditions, and targeted areas of the study site with

164 visually different bathymetric features. For transect video samples we used high-resolution

video (1080p, 60 frames per second) with a forward facing (45° to the seabed), mechanically

stabilised camera (FDR X3000, Sony), with dive lights for illumination and parallel lasers for

scaling. To record sampling positions, we used an ultra-short baseline (USBL) system (EasyTrak

168 Nexus Lite, Applied Acoustics) calibrated to a horizontal accuracy of 8 m. We sampled transects

by drifting for 1 hour or 1 km within an hour either side of slack water, in current speeds of lessthan 1 kt.

171 To extract discrete observation data without introducing multiple operator errors, a single 172 operator reviewed and classified the transect video footage. Starting from 1 min after the frame 173 started moving steadily on the seabed, we assigned a class for reef substrate and a class for 174 potential *S. spinulosa* reef (Table 1) to each 30 s section. Classes were derived from published 175 definitions of reef habitat categories developed to aid environmental management, conservation 176 and spatial planning, in which benthic habitats are categorised according to how closely they 177 resemble stony reef or biogenic Sabellaria spinulosa reef (Hendrick and Foster-Smith, 2006; 178 Irving, 2009; Limpenny et al., 2010). We only recorded observations for sections in which the 179 seabed was visible at close enough range to confidently assess particle size using the parallel 180 lasers for at least 50% of the section. We classified reef substrate as sediment (not reef), stony

181 reef (low resemblance), stony reef (mid-high resemblance) or bedrock (Irving, 2009). While we 182 initially classified stony reef into three resemblance classes, there were few high resemblance 183 observations, so we combined mid and high resemblance observations (Table 1). We classified 184 potential biogenic (Sabellaria spinulosa) reef separately to substrate because S. spinulosa can 185 colonise a range of substrates, and initial data exploration indicated that the predictor variables 186 we used, mainly morphological descriptors, were unlikely to distinguish between stony reef and 187 stony reef colonised by S. spinulosa. After preliminary data exploration we classified S. spinulosa 188 observations as not reef, comprising samples with no *S. spinulosa* tubes present and those with 189 individual tubes of less than 10% cover, and potential reef, comprising samples with colonies 190 over 2 cm high or more than 10% cover (Table 1). We extracted positions of the video 191 observations to within 8 m horizontal accuracy by matching the video timestamps to the USBL 192 timestamps. Data from one transect were discarded due to low positional accuracy. 193 We reclassified an additional point video sample dataset obtained from a commercial ecological 194 survey of the study site to our classification system based on the percent cover of substrates and 195 *S. spinulosa* reef recorded. These data were derived from drop down video sampling of the study 196 area in 2018 and had been analysed for biotope mapping with percent cover of species and 197 substrates quantified (MarineSpace, 2019). We gridded the combined transect and point video 198 observations on a 20 m resolution grid matching the environmental data, assigning the class 199 with the highest rank (Table 1) where there were multiple observations in a grid cell to give a

single observation per grid cell. We had total of 500 and 509 observations for substrate and

- 201 *Sabellaria spinulosa* respectively, the difference due to *S. spinulosa* reef obscuring the substrate
- in some samples.

204 205 206 **Table 1.** Drop-down video classification. Each 30 second section of video was assigned a class for reef substrate and potential biogenic reef. Class ranks were used to reduce multiple observations to a single

ground truth observation per pixel of environmental data. Distance between laser points = 50 mm.

CLASS	QUALIFIER	RANK	EXAMPLE
REEF SUBSTRATE			
SEDIMENT (NOT REEF)	Less than 10% particles of 64 mm or more.	1	
STONY REEF (LOW RESEMBLANCE)	10 – 40% particles of 64 mm or more. Epifauna present.	2	
STONY REEF (MID- HIGH RESEMBLANCE)	Over 40 % particles of 64 mm or more. Epifauna present.	3	
BEDROCK REEF	Bedrock present	4	
BIOGENIC REEF			
<i>NOT S. SPINULOSA</i> REEF	No <i>S. spinulosa</i> tubes seen, or <i>S. spinulosa</i> tubes present but covering less than 10%	1	
POTENTIAL <i>S.</i> <i>SPINULOSA</i> REEF	S. spinulosa colonies of over 2 cm height or with over 10% cover	2	

208 2.3 Environmental predictor variables

209 To predict the spatial distribution of potential reef habitats we used morphological derivatives 210 from bathymetry data and a measure of seabed energy as environmental predictor variables 211 (Table 2). Bathymetry data (1 m horizontal resolution) were collected using a multibeam echo 212 sounder (MBES) for the study site in 2018 during a commercial survey (Royal Haskoning DHV, 213 2019) (Fig. 1C). We generated six morphological derivatives from the bathymetry data using the 214 Surface Parameters and Raster Calculator tools in ArcGIS Pro (ESRI, CA, USA) and the Benthic 215 Terrain Modeller v3.0 plugin (Walbridge et al., 2018; Wright et al., 2005). The derivatives we 216 used were slope, curvature, eastness, northness, relative difference from mean value (RDMV) 217 and vector ruggedness measure (VRM) (Lecours et al., 2017; Sappington et al., 2007; Wilson et 218 al., 2007). We selected these based on their demonstrated predictive power in the literature, 219 their hypothesised predictive power within the context of this study, and following 220 recommendations from Lecours et al. (2017). Morphological derivatives are typically calculated 221 using a square window with an edge length of 3 pixels, but the scale at which they are generated 222 and the way in which they are calculated for different scales can influence their predictive 223 power (Misiuk et al., 2021; Porskamp et al., 2018). We define the scale of a derivative as the 224 edge length of the square window containing the bathymetric information that influences the 225 calculation, or the "analysis distance" sensu Misiuk et al. (2021). We generated all morphological 226 derivatives at scales of 3, 6, 15, 30, 60, 100 and 140 m, an approximate geometric progression 227 from the minimum window size up to the scale of the hydrodynamic data used (150 m, see 228 below), beyond which we assumed predictive capability to be minimal in the context of our 229 study. For scales of 3 m to 60 m we calculated derivatives by mean-aggregation of the 230 bathymetry data to 2, 5, 10 and 20 m, up to the spatial precision of ground truth samples, then 231 calculated derivatives using a 3 x 3 pixel window. For scales of 100 m and 140 m we calculated 232 derivatives from the 20 m resolution bathymetry using 5 x 5 and 7 x 7 pixel windows. These 233 methods of "resample-calculate" and "k x k window" are the most effective for characterising 234 features and information at different scales (Misiuk et al., 2021). Derivatives calculated using 235 bathymetry resolution of 1, 2, 5 and 10 m were mean-aggregated to 20 m to match the 236 resolution of the remaining data. Multi-collinearity in predictor variables was tested and 237 resolved by systematically removing highly collinear derivatives until the variance inflation 238 factor for all predictors was below 10, using the *usdm* package in R (Dormann et al., 2013; Naimi 239 et al., 2014; R Core Team, 2021) (Supporting information Fig S1). All derivative data were 240 generated across the full extent of the bathymetry data where the k x k window contained no 241 missing data.

242 To generate a predictor variable of seabed energy, we used a 3D Regional Ocean Modelling 243 System hydrodynamic model with a horizontal resolution of 150 m and 20 vertical layers, 244 covering the north west Wales region, derived from a larger extent model (Ward et al., 2015). 245 The model was set to compute and output mean tidally induced bottom bed shear stress over a typical spring-neap tidal cycle (Fig. 1D). Fast tidal currents are generated at the site as the tide 246 247 flows around the Isle of Anglesey and produce a local maximum of bed shear stress. Tidal 248 current speed and bed shear stress are reduced close to the coastline and further offshore. Mean 249 bed shear stress is a good predictor of substrate composition at regional scales (Ward et al., 250 2015) and is likely to have a mechanistic influence on reef substrates and benthic communities. 251 Bathymetry for the ROMS model was provided from EMODnet (EMODnet Portal, September 252 2015 release) and bottom friction was controlled through a quadratic bottom drag coefficient 253 set at 0.003 (Ward et al., 2015). Ocean boundary conditions were taken from the 254 TOPEX/POSEIDON global tidal model (TPXO). The model validates well against the Holyhead 255 tide gauge harmonic data (Supporting information Fig S2). We resampled the 150 m resolution 256 bed shear stress data to 20 m using nearest neighbour without interpolation to match the 257 spatial resolution of the morphological environmental data. As the hydrodynamic model 258 incorporated bathymetry, and raw bathymetry within the depth range of the study site was not 259 expected to have a mechanistic effect on benthic substrate or biogenic reef distribution, raw 260 bathymetry was not included as a predictor variable. High quality backscatter data were not 261 available for the full extent of the study area.

263 **Table 2.** Environmental predictor variables used to predict reef substrate and biogenic reef for each 20m

264 x 20 m pixel in the study area after systematic removal of multi-collinear variables. *Vector ruggedness

265 measure at 60 m scale was included in the reef substrate model but not the biogenic reef model.

Variable	Scale (m)
Curvature	3
Curvature	140
	3
Eastness	30
	140
	3
Northness	30
	140
	3
Relative difference from mean value	15
Relative unierence if on mean value	60
	140
Clana	30
Slope	140
	3
	15
Vector ruggedness measure	30
	60*
	140
Mean bed shear stress	150

266

267

268 2.4 Classification model and predictive mapping

269 For classification and predictive mapping of reef substrate and potential biogenic reef we used 270 Random Forests, an ensemble machine learning algorithm based on classification trees 271 (Breiman, 2001; Cutler et al., 2007). Radom Forests perform consistently well for benthic 272 habitat mapping in a range of contexts and require minimal tuning (Mitchell et al., 2018; 273 Wicaksono et al., 2019). The approach is non-parametric, making it a suitable choice given the 274 characteristics of our sampling design and data. We implemented classification algorithms using the randomForest and caret packages in R (Kuhn, 2008; Liaw and Wiener, 2002; R Core Team, 275 276 2021). To estimate model performance with spatially clustered observations we implemented 277 spatially buffered leave-one-out cross validation using the *blockCV* package (R Core Team, 2021; 278 Valavi et al., 2019), using a buffer radius of 250 m, exceeding the median spatial autocorrelation 279 range of our environmental predictor variables. In this method, a Random Forest model is 280 trained on all reference data except for a test sample and the samples within a spatial buffer 281 around it, then the model is used to predict the test sample. This is repeated using all reference 282 samples as test samples and model performance is estimated from an error matrix of 283 observations against predictions. Each Random Forest classification model used 1500 trees and

284 3 variables tested at each split, hyperparameters that we derived from preliminary tuning. We 285 used down-sampling to balance classes in training data. The entire reference dataset was then 286 used to train a final model to make predictions for all pixels across the study site. We mapped 287 spatially explicit uncertainty in predictions as the model-generated probability of the predicted 288 class for each pixel (Mitchell et al., 2018). Tree-based classifiers can resolve complicated non-289 linear relationships but cannot extrapolate beyond the extent of the training data. We therefore 290 also mapped the area of applicability for the model performance estimates, outside of which the 291 combinations of environmental predictor data were too dissimilar to the training data to be able 292 to estimate performance (Meyer and Pebesma, 2021). To help interpret the model performance 293 we produced plots of variable importance and partial dependence plots using the *randomForest* 294 package. Variable importance plots show how strongly each variable influences model 295 predictions. We used the Gini index to measure importance, describing the purity of nodes in a 296 tree-based classifier (Breiman, 2001). Partial dependence plots visualise the influence of an 297 individual variable on the relative likelihood that an observation will be predicted as a certain 298 class (Friedman, 2001).

299 To assess the performance of a predictive mapping model, an error matrix and a selection of 300 metrics should be considered in the context of the aims of the model and the user's interests 301 (Foody, 2002; Olofsson et al., 2014). The error matrix documents the predicted and observed 302 classes of the test samples, giving an estimate of the model performance for new, unknown 303 observations. We generated a selection of standard and recommended performance metrics 304 from the error matrix (Foody, 2002; Mitchell et al., 2018; Olofsson et al., 2014; Pontius and 305 Millones, 2011). No single measure can fully describe performance of a classification model, but 306 here we present balanced accuracy as an overall measure that accounts for imbalance in class 307 prevalence (Brodersen et al., 2010). For consistency with other studies we also present overall 308 accuracy as the proportion of correct predictions out of total predictions, and Cohen's kappa 309 coefficient (Cohen, 1960), although their use has been discouraged (Brodersen et al., 2010; 310 Foody, 2020; Pontius and Millones, 2011). To give context to the overall accuracy value, the no 311 information rate is provided, equal to the proportion of the most prevalent class and therefore 312 being the accuracy value that would be achieved by predicting all observations as one class. 313 User's and producer's accuracies provide class-wise insight. The user's accuracy estimates the 314 reliability of the map for a user, describing the proportion of the predictions of a class that were 315 actually observed to be that class. The producer's accuracy, also known as sensitivity, or true 316 positive rate, estimates the ability of a model to correctly map the land- or seascape, describing 317 the proportion of known observations of a particular class that were correctly predicted as that 318 class. The complement of sensitivity is specificity. Specificity, or true negative rate, describes

- 319 how many observations that were known to not be a class were correctly predicted to not be
- 320 that class. Finally, we present quantity disagreement and allocation disagreement (Pontius and
- 321 Millones, 2011). These measures provide information about the way in which the observations
- 322 and predictions differ. High quantity disagreement indicates large differences in class
- 323 prevalence while a high allocation disagreement indicates a large proportion of
- 324 misclassifications. For further explanation of the metrics used see the Supporting Information.
- 325

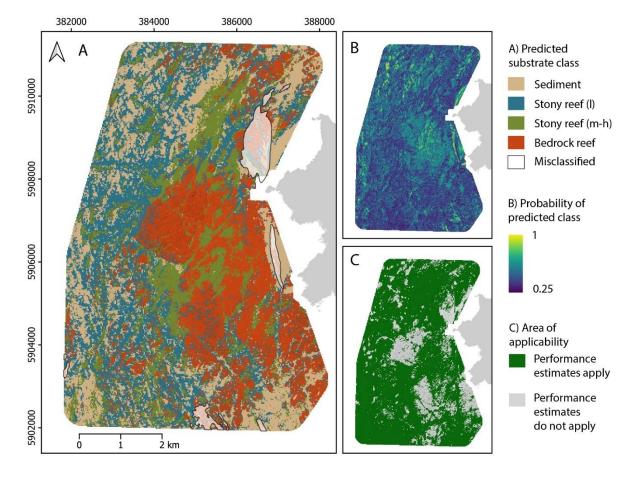




Figure 2. A) Predicted reef substrate classes with visually apparent misclassified areas are masked out. B)
 Probability of the predicted class for each pixel. C) Area of applicability for the performance estimates of
 the classifier. Areas in grey have environmental variables too dissimilar to the model training data to
 estimate performance.

332 3. Results

- 333 3.1 Reef substrate
- We predicted the distribution of reef substrate in the study area by classifying the substrate into
- four classes: sediment (not reef), stony reef (low resemblance), stony reef (mid-high
- resemblance) and bedrock reef (Fig. 2A). Most observations were correctly predicted for each
- 337 class (Table 3), reflected in the overall balanced accuracy of 71.7% (Table 4). For all classes,
- 338 misclassifications were mostly in classes similar to the target class (Table 3). For example,
- 339 sediment was mostly misclassified as stony reef (low resemblance) and rarely as bedrock.
- 340 User's accuracy, estimating the reliability of the mapped pixels, was highest for stony reef (mid-
- high resemblance) (65.5%) and lowest for stony reef (low resemblance) (47.2%). Producer's
- 342 accuracy, indicating the consistency of correctly predicting known observations, was highest for
- 343 sediment (66.9%) and lowest for stony reef (low resemblance) (47.6%). The reference data and
- 344 predictions differed due to misclassification (allocation disagreement = 37.2%), more than due
- to differences in class prevalence (quantity disagreement = 6%) (Table 4).
- Table 3. Error matrix for the model predicting reef substrates following spatially buffered cross validation.
 True positives are in grey. Values are normalised by the total number of observations for each class, such that the columns sum to 1.

		Observed					
		Sediment	Stony reef (l)	Stony reef (m-h)	Bedrock reef		
	Sediment	0.669	0.315	0.049	0.012		
Predicted	Stony reef (l)	0.269	0.476	0.224	0.107		
Pred	Stony reef (m-h)	0.038	0.105	0.517	0.226		
	Bedrock reef	0.023	0.105	0.210	0.655		

- 350
- Table 4. Performance estimates for the model predicting reef substrates following spatially buffered cross
 validation.

	Overall	Sediment	Stony reef (l)	Stony reef (m-h)	Bedrock reef
Total observations	500	130	143	143	84
User's accuracy	0.571	0.621	0.472	0.655	0.534
Producer's accuracy / Sensitivity	0.579	0.669	0.476	0.517	0.655
Specificity	0.855	0.857	0.787	0.891	0.885
Quantity disagreement	0.06	0.02	0.002	0.06	0.038
Allocation disagreement	0.372	0.172	0.3	0.156	0.116

Balanced accuracy	0.717
Accuracy	0.568
No information rate	0.286
Карра	0.421

354

355 The most important variables for predicting reef substrate classes in the study area were vector 356 ruggedness measure at scales from 3 m to 140 m, and mean bed shear stress (Fig. 3). Partial 357 dependence plots of the three most important variables showed that areas with high fine-scale 358 (3 m) ruggedness were more likely to be classified as bedrock and less likely to be classified as 359 sediment, while areas with high broad-scale (140 m) ruggedness were more likely to be 360 classified as stony reef and less likely to be classified as bedrock (Fig. 4). Areas with high mean 361 bed shear stress (over 2.55 Nm⁻²) were more likely to be classified as bedrock or stony reef 362 (mid-high resemblance) and less likely to be classified as sediment or stony reef (low 363 resemblance) (Fig. 4). A reliability heat map of classification probabilities showed variation in 364 the consistency of predictions among samples (Supporting information Figure S3).

The model predicted much of the visually rugged ground in the highest energy central region of 365 366 the study area to be bedrock reef, with stony reef (mid to high resemblance) predictions 367 concentrated in the high energy region where the ground was less rugged (Fig. 2A). A mixture of 368 the two stony reef classes was predicted throughout the moderate energy regions where there 369 was relatively smooth seabed and a mixture of sediment and stony reef (low resemblance) was 370 predicted in the lowest energy regions. We could visually interpret certain seabed features like 371 bedrock outcrops from the raw bathymetry data and qualitatively assess the performance of the 372 predive model for some of the study area extent. The model appeared to perform well for these 373 areas, with most visually apparent bedrock outcrops being correctly classified. Visually 374 apparent misclassifications were mostly concentrated around feature boundaries, but there 375 were notable misclassifications of apparent sediment waves as bedrock. Spatially explicit 376 classification probabilities showed that the probability of assigned classes was moderate for 377 most of the mapped area, with a mean \pm sd of 0.47 \pm 0.11 (Fig. 2B). The area of applicability 378 analysis indicated regions of the study area where combinations of environmental variables 379 were poorly represented in the training data and therefore model performance estimates were 380 not reliable. The regions outside the area of applicability were mostly high energy, high 381 ruggedness areas of apparent bedrock in the central study area and very low energy areas close 382 to the shore in the eastern study area (Fig. 2C).

384

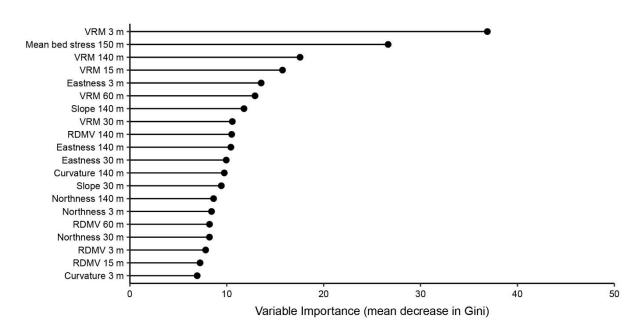


Figure 3. Relative importance of predictor variables in the model predicting reef substrate. Variable
 importance is quantified by the mean decrease in the Gini index if the variable is not included within the
 Random Forest model. The Gini index is a measure of node purity.



385

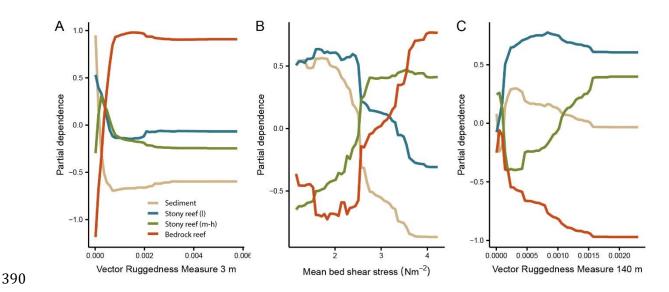


Figure 4. Partial dependence plots for the three variables with highest importance in the model predicting reef substrate. The plots visualise the influence of each variable on the likelihood that an observation is predicted to be each of four classes. For example, observations with low mean bed shear stress are less likely to be classified as bedrock reef or stony reef (mid-high resemblance) and more likely to be classified as sediment or stony reef (low resemblance).

397 3.2 Potential Sabellaria spinulosa biogenic reef

- 398 Our classification model aimed to predict two classes for *Sabellaria spinulosa*: not reef,
- 399 encompassing samples with no *S. spinulosa* seen and those with *S. spinulosa* present but not
- 400 forming reef, and potential reef, encompassing samples with low, medium or high resemblance
- 401 to a biogenic reef. The model predicted most observations correctly with a balanced accuracy of
- 402 63.4%, but there was a high proportion of misclassifications (Table 5, Table 6). The potential
- 403 reef class had a producer's accuracy of 64% but a low user's accuracy of 29.6% due to a high
- 404 number of false positives (Table 6), suggesting that a map of predicted spatial distribution
- 405 based on environmental variables would not be reliable. A reliability diagram indicated that the
- 406 model was not well calibrated and underpredicted the potential reef class (Supporting
- 407 information Figure S4).
- 408

Table 5. Error matrix for the model predicting potential *Sabellaria spinulosa* reef following spatially
 buffered cross validation. True positives are in grey. Values are normalised by the total number of

411 observations for each class, such that the columns sum to 1.

		Observed				
		Not reef	Potential reef			
Predicted	Not reef	0.628	0.360			
	Potential reef	0.372	0.640			

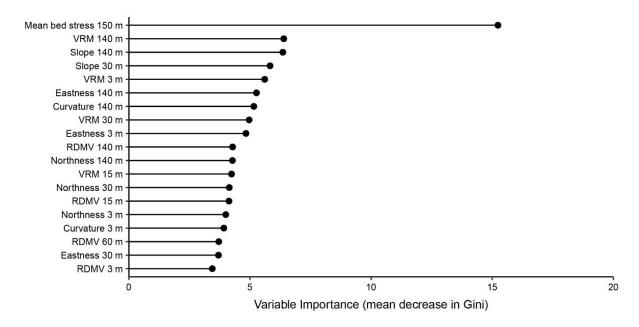
412

413

Table 6. Performance estimates for the model predicting potential *Sabellaria spinulosa* reef following
 spatially buffered cross validation.

	Overall	Not reef	Potential reef
Observations	509	409	100
User's accuracy	0.587	0.877	0.296
Producer's accuracy / Sensitivity	0.634	0.628	0.64
Specificity	0.634	0.64	0.628
Quantity disagreement	0.228	0.228	0.228
Allocation disagreement	0.141	0.141	0.141
Balanced accuracy	0.634		
Accuracy	0.631		
No information rate	0.804		
Карра	0.187		

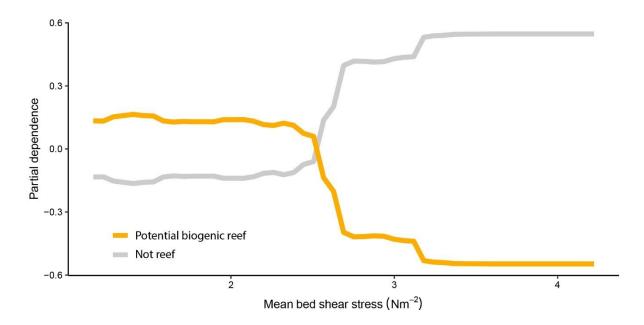
- 417 The variable importance plot for this model showed that mean bed shear stress was the single
- 418 most important variable for predicting potential S. spinulosa reef, with the remaining variables
- 419 having much lower importance (Fig. 5). A partial dependence plot for the effect of mean bed
- 420 shear stress on class predictions showed that the potential *S. spinulosa* reef was less likely to be
- 421 predicted above mean bed stress of 2.52 Nm⁻² (Fig. 6B).
- 422



423

- Figure 5. Relative importance of predictor variables in the model predicting potential *Sabellaria spinulosa* reef. Variable importance is quantified by the mean decrease in the Gini index if the variable is not included
- 426 within the Random Forest model. The Gini index is a measure of node purity.

427





430 **Figure 6.** Partial dependence plot showing the influence of mean bed shear stress in the model predicting

reef substrate. The plot visualises the influence of a single variable on the likelihood that an observation is

432 predicted to be potential biogenic reef or not. Observations with high mean bed shear stress are less

433 likely to be classified as potential reef and more likely to be classified as not biogenic reef.

434 4. Discussion

We used a machine learning approach to map previously unresolved temperate reef habitats in

436 a high tidal energy marine region, finding that hydrodynamic energy at the seabed and

437 ruggedness measured at multiple scales were the most important predictors of potential reef

438 habitats. Our model predicting geogenic reef classes generated useful predictions, but our

439 model predicting biogenic *Sabellaria spinulosa* reef did not satisfy our objectives.

440 Our reef substrate model performed well, with a balanced accuracy of 71.7%. The performance 441 was sufficient to provide useful information about the distribution of potential temperate reef 442 habitats relative to the environmental variables in our study site. While not directly comparable, 443 other studies with similar contexts and model frameworks have reported overall accuracies of 444 81-93% (Haggarty and Yamanaka, 2018), and 69.7% (Porskamp et al., 2018). We were able to 445 predict stony reef using hydrodynamic and seabed morphology data with a user's accuracy of 446 65.5%. As an ecologically important habitat listed in the EC Habitats Directive Annex 1, there is 447 a need for environmental managers of member states to understand the spatial distribution of 448 this habitat in their jurisdictional waters. Identifying and evaluating the habitat by remote 449 sensing rather than direct observation or sampling has historically proved challenging (Irving, 450 2009; Limpenny et al., 2010). Our findings are encouraging and suggest that it will be possible 451 to develop protocols to identify areas of potential stony reef using remotely sensed and 452 modelled environmental data, enabling targeted sampling and improved efficiency in resource 453 use for environmental management.

454 Mean tidally induced bed shear stress was one of the most important variables in predictive 455 models for both reef substrate and potential Sabellaria spinulosa biogenic reef. Our results 456 support findings from wave exposed coastal regions (Porskamp et al., 2018; Rattray et al., 457 2015), showing that hydrodynamic energy is an important predictor of reef habitats in high 458 energy waters. Seabed ruggedness calculated at scales of 3 m, 15 m and 140 m were also 459 important variables for predicting reef substrate. These variables had low multicollinearity 460 indicating that they represented features of different scales in the seascape. For instance, 3 m 461 ruggedness may represent individual boulders or topographically complex bedrock, 15 m 462 ruggedness may represent raised patches of cobbles and boulders surrounded by more erodible 463 sediment, and 140 m ruggedness may represent large-scale bedforms and glacial features in the 464 region (Van Landeghem et al., 2009). Interestingly, where there was high 140 m scale 465 ruggedness, stony reef was predicted rather than bedrock, suggesting that bedrock bathymetry 466 was more homogenous than stony reef at this scale in our study area. Our results support an 467 increasingly recognised need to include predictor variables at multiple scales for benthic habitat 468 mapping (Lecours et al., 2015; Misiuk et al., 2021; Porskamp et al., 2018). As with bathymetric

469 indices, the ability of bed shear stress to structure and predict benthic habitats is likely to differ 470 across spatial scales. Variation in water flow influences species distribution by controlling 471 proximal factors across scales. For instance, suspended food availability is influenced by 472 topographically driven turbulence at the centimetre scale (Prado et al., 2020), and by 473 oceanographic processes like upwelling at the kilometre scale (Navarrete et al., 2005). Fine-474 scale hydrodynamic energy information with resolution comparable to bathymetry data across 475 regional extents would likely enhance the performance of predictive models. This would benefit 476 benthic habitat mapping and marine species distribution modelling to better understand 477 patterns and processes at organism-centric scales. However, unlike bathymetry that is relatively 478 stable through time, hydrodynamic conditions are highly variable, making simulating and 479 validating them at fine spatial scales logistically and computationally challenging with current 480 technology.

481 Our predictive model for Sabellaria spinulosa biogenic reef was largely driven by the singular 482 important variable of bed shear stress. Although the performance metrics were low and the use 483 of the model to generate a predictive map was not appropriate, the results still provide valuable 484 insight into the environmental variables characterising S. spinulosa reef. S. spinulosa reef was 485 not predicted to occur in the areas of the study site with highest energy, suggesting that bed 486 shear stress was a limiting factor for the habitat above 2.52 Nm⁻². Higher flow rates may present 487 barriers to larval settlement, tube building or feeding, but there is little existing information on 488 the environmental limits of the species (Davies et al., 2009). This threshold in bed shear stress 489 corresponded with one driving substrate predictions, above which bedrock and stony reef (mid-490 high resemblance) were more likely to be predicted. This may indicate that substrate suitability 491 influenced a lack of *S. spinulosa* reef predictions in this area. While few observations of *S.* 492 spinulosa reef on bedrock were recorded, stony reef substrate was found to support S. spinulosa 493 reef in lower energy parts of the study area. There may be an interaction between substrate and 494 bed shear stress influencing biogenic reef development that would need further research to 495 elucidate. Bathymetric derivatives had low importance as predictor variables for potential S. 496 spinulosa biogenic reef, suggesting that they were ineffective in explaining the variation in S. 497 *spinulosa* reef presence among observations. *S. spinulosa* is difficult to detect using multibeam 498 bathymetry acoustic data and expert interpretation of higher resolution side scan sonar data is 499 recommended to locate potential reefs (Limpenny et al., 2010). Although our original acoustic 500 data resolution was relatively high at 1 m, it may have still been too low to distinguish S. 501 spinulosa reef morphology in a topographically variable area dominated by stony reef, and more 502 observations of reef presence may be needed to train an effective model. Sabellariid reefs are 503 dynamic in both space and time in terms of their emergence, density and patchiness (Jackson-

- Bué et al., 2021; Jenkins et al., 2018; Pearce et al., 2014), and can survive periods of burial due to
- sediment transport (Hendrick et al., 2016). This presents further challenges in both detecting
- reef habitats and identifying its environmental niche with a limited temporal scale.
- 507 Observations through time are needed for an improved understanding of the environmental
- 508 conditions suitable for *S. spinulosa* reef habitat development.

509 Misclassifications were identified both in the error matrices and through manual inspection of 510 the generated predicted maps. Most misclassifications were in classes most similar to the target 511 class, which is to be expected with a classification system that discretises the continuous 512 variation of a natural environment (Foody, 2002; Wang, 1990). This was most evident in the low 513 performance metrics for the stony reef (low resemblance) class, which represented an intermediate on a continuum of cobble and boulder percent cover between sediment and stony 514 515 reef classes. The challenging nature of this classification task was reflected in the high 516 proportion of relatively low pixel-wise predicted class probabilities, particularly where a 517 mixture of sediment and stony reef classes were predicted (Fig. 2B). Continuous mapping 518 approaches can represent gradients in natural environments better than hard classification, but 519 at a cost of interpretability for end users (Feilhauer et al., 2020). Misclassification of sediment 520 wave bedforms as bedrock were visually identified and could largely be explained by a paucity 521 of observations in areas with low energy but high ruggedness. As the classification algorithm 522 can only learn from the training data, with no rugged sediment observations in the training 523 data, rugged ground was most likely to be predicted as bedrock or stony reef. This suggests that 524 semi-automated and manual interpretation mapping methods are complementary and the use 525 of multiple methods will ultimately improve the quality of benthic habitat maps (Diesing et al., 526 2014). Other sources of uncertainty included the limited field of view of video observations 527 (approx. 1 x 1 m) relative to the pixel size of the final map (20 x 20 m), and the potential for the 528 observed substrate (e.g., sediment) to be a veneer over another substrate (e.g., bedrock or 529 biogenic reef). This is a particular concern in areas with strong tidal currents where high 530 volumes of sediment are periodically transported and deposited during a tidal cycle and a single 531 observation in time cannot capture such transience. Our predictive models may have been 532 improved with multibeam echo sounder backscatter data across the extent of the study area. 533 However, collection of high quality backscatter requires additional survey time and optimal sea 534 state conditions, and it is an unstandardised variable (Lamarche and Lurton, 2018). Further, 535 where a thin layer of sediment overlays hard substrate backscatter can be highly variable, 536 making it less valuable as a predictor of observed substrate (Lucieer et al., 2013). 537 Accuracy metrics are useful for assessing the performance and usefulness of a model for a

538 specific application but should not be used in isolation to compare different models and studies

539 (Bennett et al., 2013; Mitchell et al., 2018). The performance of benthic habitat mapping varies 540 with decisions made throughout planning, data collection and analysis, leading to a lack of 541 standardisation (Strong, 2020). For instance, choices in model framework, scale and choice of 542 environmental variables, the number of observation classes used and whether to use a 543 geomorphic or biological basis to classes, all affect different aspects of the resulting map 544 product (Ierodiaconou et al., 2018; Porskamp et al., 2018; Smith et al., 2015). A predicted map 545 should therefore be considered along with its error matrix, several performance metrics and 546 spatially explicit uncertainty estimates in a case-by-case basis to determine its suitability for a 547 particular user and purpose(Congalton, 1991; Foody, 2002). It should also be recognised that 548 that the performance estimates evaluate the classification model, rather than the true accuracy 549 of a predicted map. Ideally probability sampling would be used to collect independent training 550 and validation data for a predictive model to make design-based inference (Cochran, 1977; 551 Olofsson et al., 2014), but this is rarely achieved for benthic mapping with resource limitations 552 and the logistical constraints of sampling at sea, especially in high energy environments. To 553 address the limitations of imperfect sampling design, methods have been developed to estimate 554 a model's ability to predict into unobserved space. These include the methods applied here of 555 spatial cross validation and area of applicability analysis (Meyer and Pebesma, 2021; Ploton et 556 al., 2020).

557 The findings of this study support the use of predictive mapping as an efficient and repeatable 558 tool for ecosystem management in logistically challenging environments like high tidal energy 559 waters. These traditionally less anthropogenically developed and understudied regions are 560 seeing novel industrial interest from the nascent marine renewable energy industry, generating 561 demand for cost effective means to gather baseline ecosystem information (Shields et al., 2011; 562 Wilding et al., 2017). We found that tidally induced seabed shear stress was a powerful variable 563 for predicting reef habitats in high tidal energy temperate seas, and highlighted the importance of calculating bathymetric morphological derivatives at multiple scales for benthic habitat 564 565 mapping. Our results will contribute to a better understanding of the spatial ecology of 566 temperate reef ecosystems and will inform evidence-based decision making for ecosystem 567 management in high energy marine areas.

568

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- 591

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884 Supporting information

885 Accuracy metrics

No single metric can fully describe the accuracy of a predictive map. To assess the accuracy of a

887 predictive map for a specific purpose, a selection of accuracy estimates should be considered

that are derived from the error matrix of predictions and observations. The error matrix is also

889 known as a confusion matrix or contingency table. In this paper we use some of the more

890 common metrics found in the literature. Here, we describe how the metrics we used were

891 calculated using a generic example error matrix with three classes.

892

893 Metric: **Overall accuracy**

- 894 Synonyms: Accuracy
- 895 Description: The proportion of correct positive predictions.
- 896 Calculation: True positives (all classes) / Total observations (all classes)

		Observed					
		А	В	С	Totals		
te	Α	22	7	0	29		
Predicte	В	4	39	9	52		
Pr	С	2	5	12	19		
	Totals	28	51	21	100		

Observed

897

898 Overall accuracy = 0.73

899

- 900 Metric: User's accuracy
- 901 Synonyms: Error of commission, precision, positive predictive value
- 902 Description: For a specific class, the proportion of positive predictions that were observed to be
- 903 that class.
- 904 Calculation: True positives (Class A) / Total predictions (Class A)

		Observed					
		Α	В	С	Totals		
ite	Α	22	7	0	29		
Predicte م	В	4	39	9	52		
Pr	С	2	5	12	19		
	Totals	28	51	21	100		

Observed

905

906 User's accuracy (Class A) = 0.76

- 907 Metric: Producer's accuracy / Sensitivity
- 908 Synonyms: Error of omission, true positive rate, recall
- 909 Description: For a specific class, what proportion of positive observations were correctly
- 910 predicted?
- 911 Calculation: True positives (Class A) / Total observations (Class A)

		Observed					
		A	В	С	Totals		
te	Α	22	7	0	29		
Predicte	В	4	39	9	52		
Pr	С	2	5	12	19		
	Totals	28	51	21	100		

914

915 Metric: **Specificity**

916 Synonyms: True negative rate

917 Description: For a specific class, what proportion of negative observations were correctly

918 predicted?

919 Calculation: True negatives (Class A) / Total negative observations (Class A)

920

		Observed					
		Α	В	С	Totals		
ed	Α	22	7	0	29		
Predicted	В	4	39	9	52		
Pro	С	2	5	12	19		
	Totals	28	51	21	100		

921

922 Specificity (Class A) = 0.90

923

924 Metric: Balanced accuracy

925 Description: An overall accuracy metric that compensates for unbalanced class observations

926 Calculation: The global mean of the class-wise means of sensitivity and specificity

927 (((Sensitivity (Class A) + Specificity (Class A)) / 2) + ((Sensitivity (Class B) + Specificity (Class

928 B)) / 2) + ((Sensitivity (Class C) + Specificity (Class C)) / 2)) / 3

⁹¹³ Producer's accuracy / Sensitivity (Class A) = 0.79

930Metric: Quantity disagreement931Description: Error attributed to differences in the class prevalence of observations and932predictions (Pontius and Millones, 2011; Warrens, 2015).933Calculation: Where
$$p_{ij}$$
 is the proportion of samples observed as class *i* and predicted as class *j*.934 p_{ir} and p_{ir} are the observed and predicted totals for each class respectively, or the column and935row totals of an error matrix of the proportions, such that the full matrix sums to 1, and *c* is the936number of classes (Warrens, 2015)937The quantity disagreement of class i is given by940 $q_l = |p_{l+} - p_{+i}|$ 941 $Q = \frac{1}{2} \sum_{l=1}^{c} |p_{l+} - p_{+i}|$ 942The overall quantity disagreement is given by943 $Q = \frac{1}{2} \sum_{l=1}^{c} |p_{l+} - p_{+i}|$ 944 $Q = \frac{1}{2} \sum_{l=1}^{c} |p_{l+} - p_{+i}|$ 945Secription: Error attributed to differences in per-unit class identities between observations948and predictions (Pontius and Millones, 2011; Warrens, 2015).949Calculation: Using the definitions given for quantity disagreement (Warrens, 2015)951The allocation disagreement for class i is given by952 $a_l = 2 \min(p_{l+}, p_{+l}) - 2p_{ll}$ 953 $a_l = 2 \min(p_{l+}, p_{+l}) - 2p_{ll}$ 954 $A = \left[\sum_{l=1}^{c} \min(p_{l+}, p_{+l}) - \sum_{l=1}^{c} p_{ll}\right]$

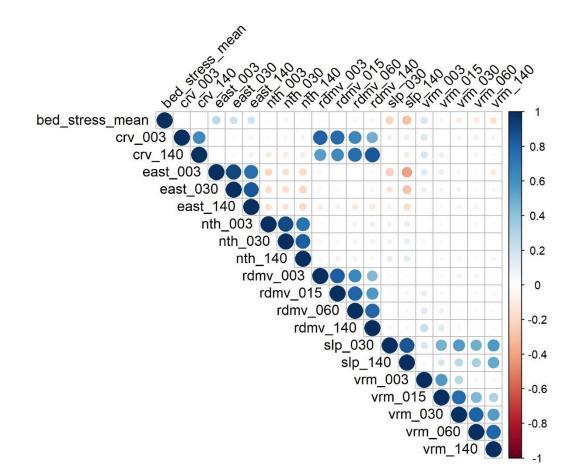


Figure S1. Correlation matrix of environmental predictor variables included in the predictive
models. Circle colour and size indicate the strength and sign of correlation between two
variables. Morphological variable names include the derivative abbreviation and scale (m).
Abberviations: curvature (crv), eastness (east), northness (nth), relative difference from mean
value (rdmv), slope (slp), vector ruggedness measure (vrm). Vrm_60 was included in the
substrate model but not the *Sabellaria spinulosa* model after variable selection by variance
inflation factor.

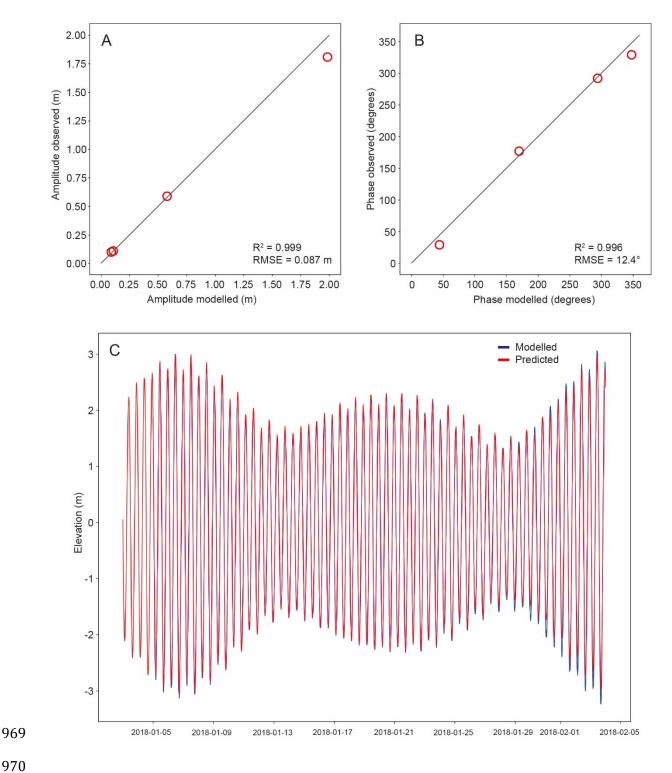
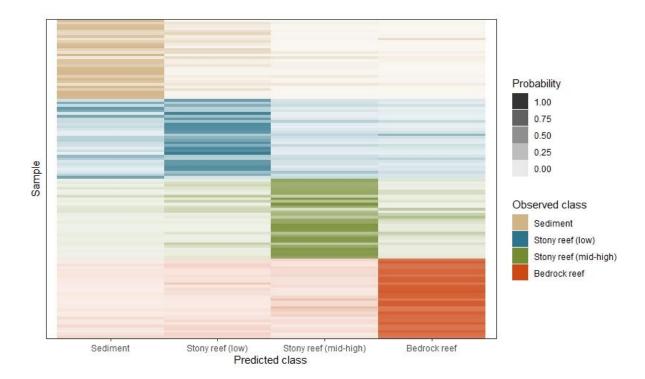




Figure S2. Our hydrodynamic model validates well against Holyhead tidal gauge harmonic data 971 972 in amplitude (A), phase (B) and elevation (C). Tidal elevation was processed using ttide_py¹ for 973 tidal analysis and the numpy python library was used to calculate r-squared values.

¹ https://github.com/moflaher/ttide_py





976 Figure S3. Heat map of predicted class probabilities for a random subset of samples (30 per
977 observed class) from the reef substrate model.



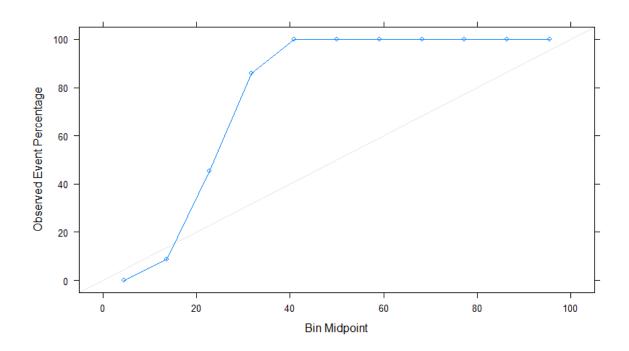


Figure S4. Reliability diagram for the *Sabellaria spinulosa* reef model. The model appears to
underpredict *S. spinulosa* reef, treated as the event.