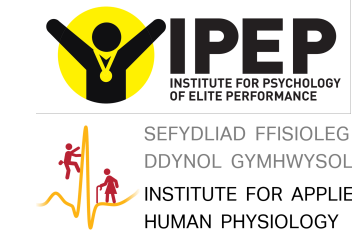


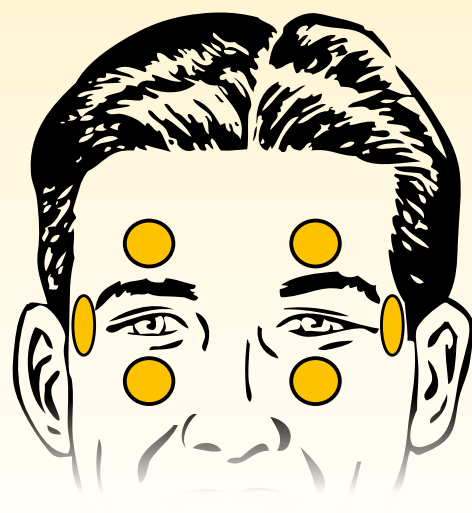
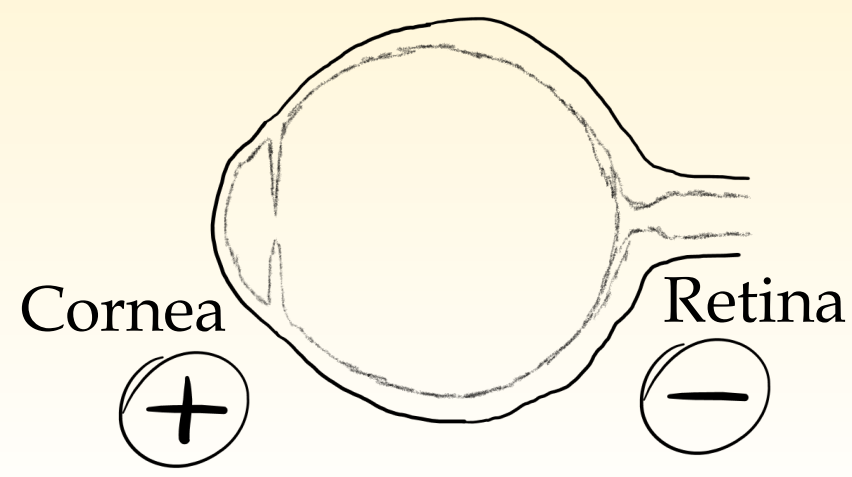
Temporal and spectral electrooculographic features in an aiming task

Germano Gallicchio¹ Donghyun Ryu² Guy L. Tasker² Mudit Krishnani² Alessandra Pecunioso³ Robin C. Jackson²

¹ Bangor University, School of Human and Behavioural Sciences
² Loughborough University, School of Sport, Exercise, and Health Sciences
³ University of Padova, Department of General Psychology



BACKGROUND



Growing interest in using **electrooculography (EOG)** to study eye movements in target sports

temporal features (e.g., Quiet Eye durations)

temporal & spectral features (time-frequency power)

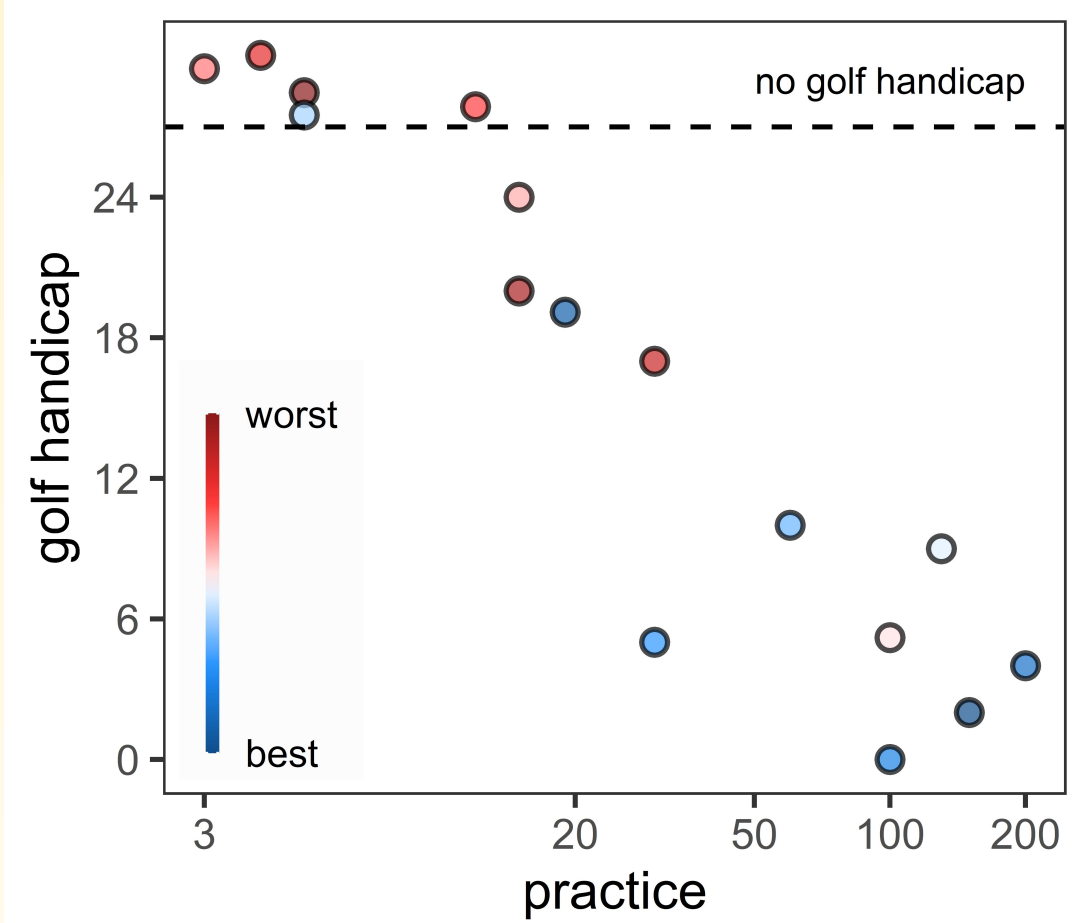
validity?

utility?

which processing settings?

METHOD

Participants ($n = 16$) novices to experts



Task: 60 4-m golf putts

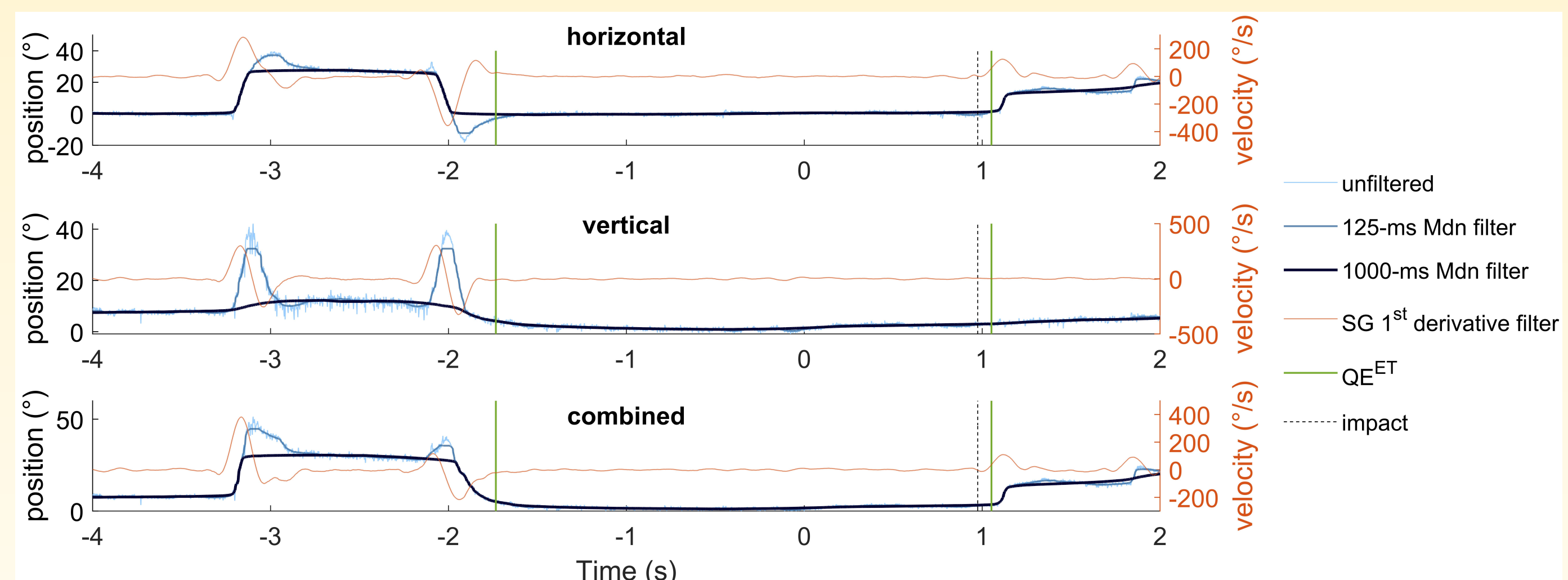
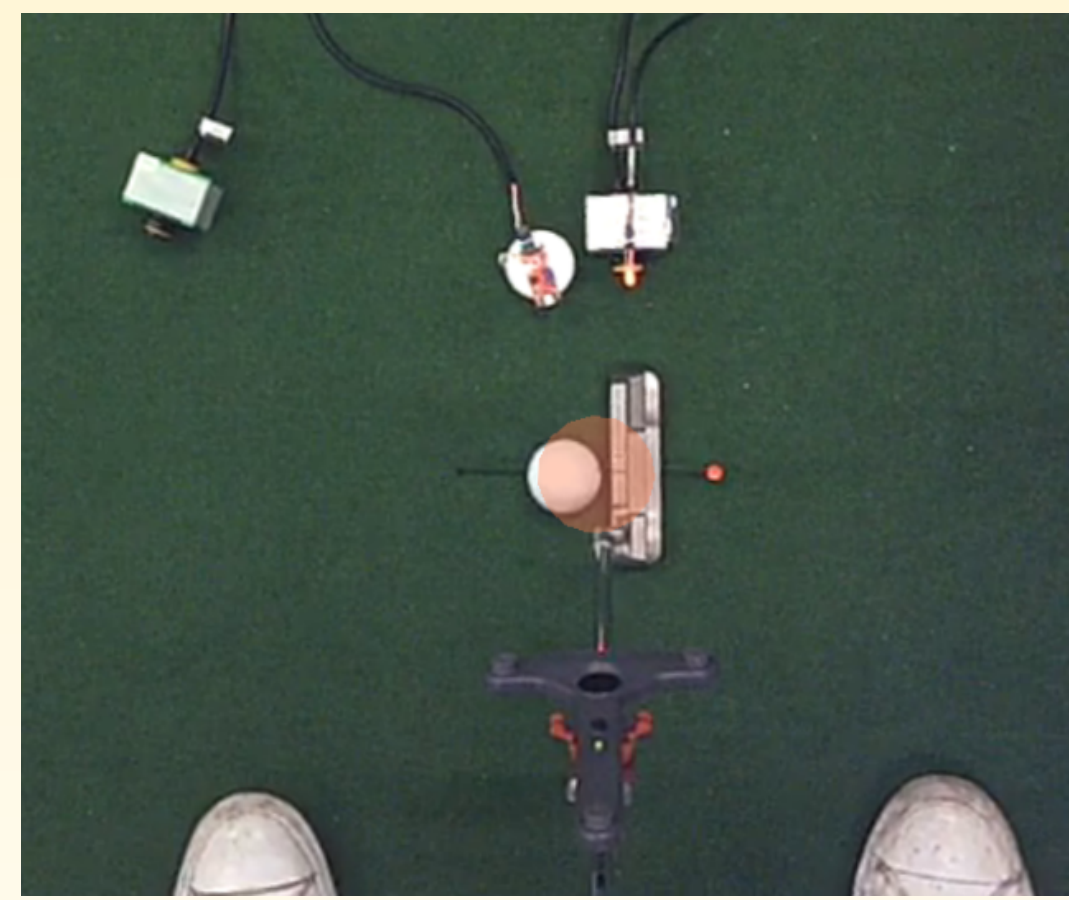


Figure 1. Participants' expertise in terms of recent practice and golf handicap. The color indicates individual performance accuracy in this study.

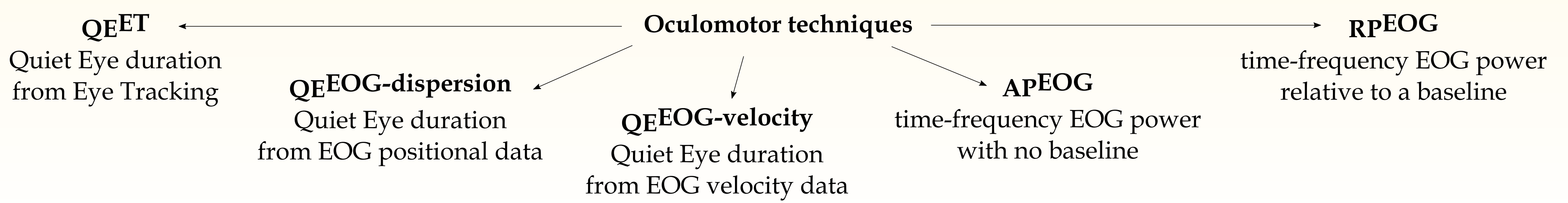
Figure 2. Eye tracker view showing the putting setup. The shaded orange circle represents the gaze location within a 3° diameter.

Figure 3. Effects of filters (median, Savitzky-Golay differentiation) applied to the EOG signals. Units were converted to degrees of visual angle (°) through gaze calibration. Time 0 s corresponds to movement initiation. The black dotted line indicates putter-ball impact. The green vertical lines indicate QE onset and offset as scored from Eye Tracking data.

Performance accuracy

Radial Error

$$\text{Mdn} \left(\sqrt{(x_i - x_0)^2 + (y_i - y_0)^2} \right)_{\text{trials}}$$



FINDINGS

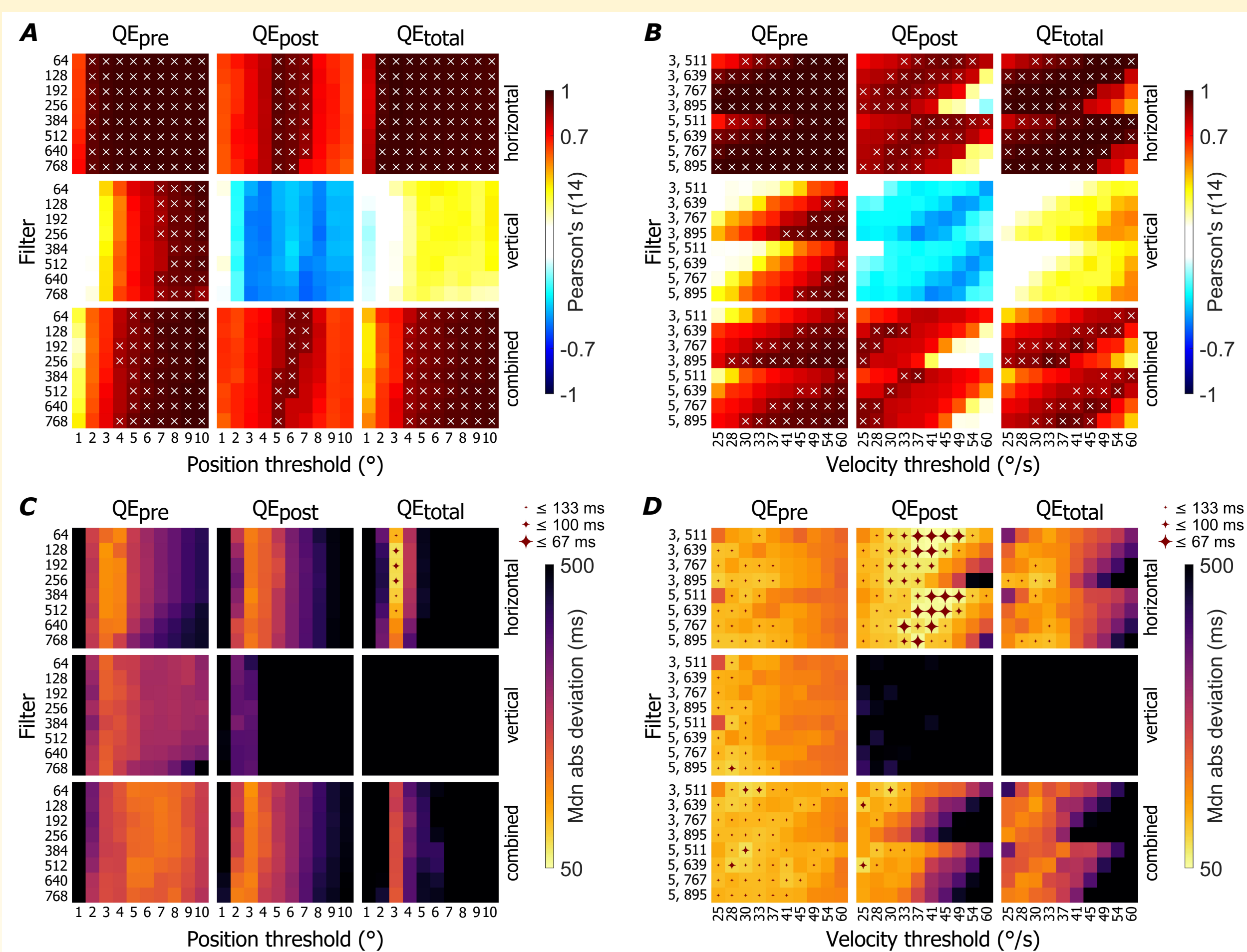


Figure 4. Concurrent validity of QEEOG against QEET through Pearson's correlations as a function of processing settings (*panel A*: dispersion; *panel B*: velocity). The X symbol highlights statistically significant results ($p < .05$) obtained through permutation testing with the extreme-value correction. Temporal discrepancy as Median absolute deviation from the values obtained from Eye Tracking (*panel C*: dispersion; *panel D*: velocity).

Table 1. Results of the nested cross-validated Theil-Sen regression predicting performance (i.e., radial error) using each of the five oculomotor techniques. Median squared logarithmic error on the test set ($\text{MdnSLE}_{\text{test}}$) is reported as measure of generalization error (i.e., expected error on unseen data), along with interquartile range of the logarithmic errors on the test set ($\text{IQRLE}_{\text{test}}$) and their ranges ($\text{RangeLE}_{\text{test}}$). The technique with the smallest $\text{MdnSLE}_{\text{test}}$ value is the best at predicting performance when applied to unseen data. The technique with the smallest $\text{IQRLE}_{\text{test}}$ value is the most consistent across different test sets.

Technique	$\text{MdnSLE}_{\text{test}} \cdot 10^4$	$\text{IQRLE}_{\text{test}} \cdot 10^2$	$\text{RangeLE}_{\text{test}} \cdot 10^2$
QEEOG-dispersion	124.02	22.74	[-15.36, 27.88]
QEET	68.58	16.37	[-14.88, 20.22]
QEEOG-velocity	54.96	15.36	[-32.66, 26.27]
APeOG	22.11	11.61	[-8.48, 25.57]
RPeOG	4.96	5.49	[-7.68, 31.16]

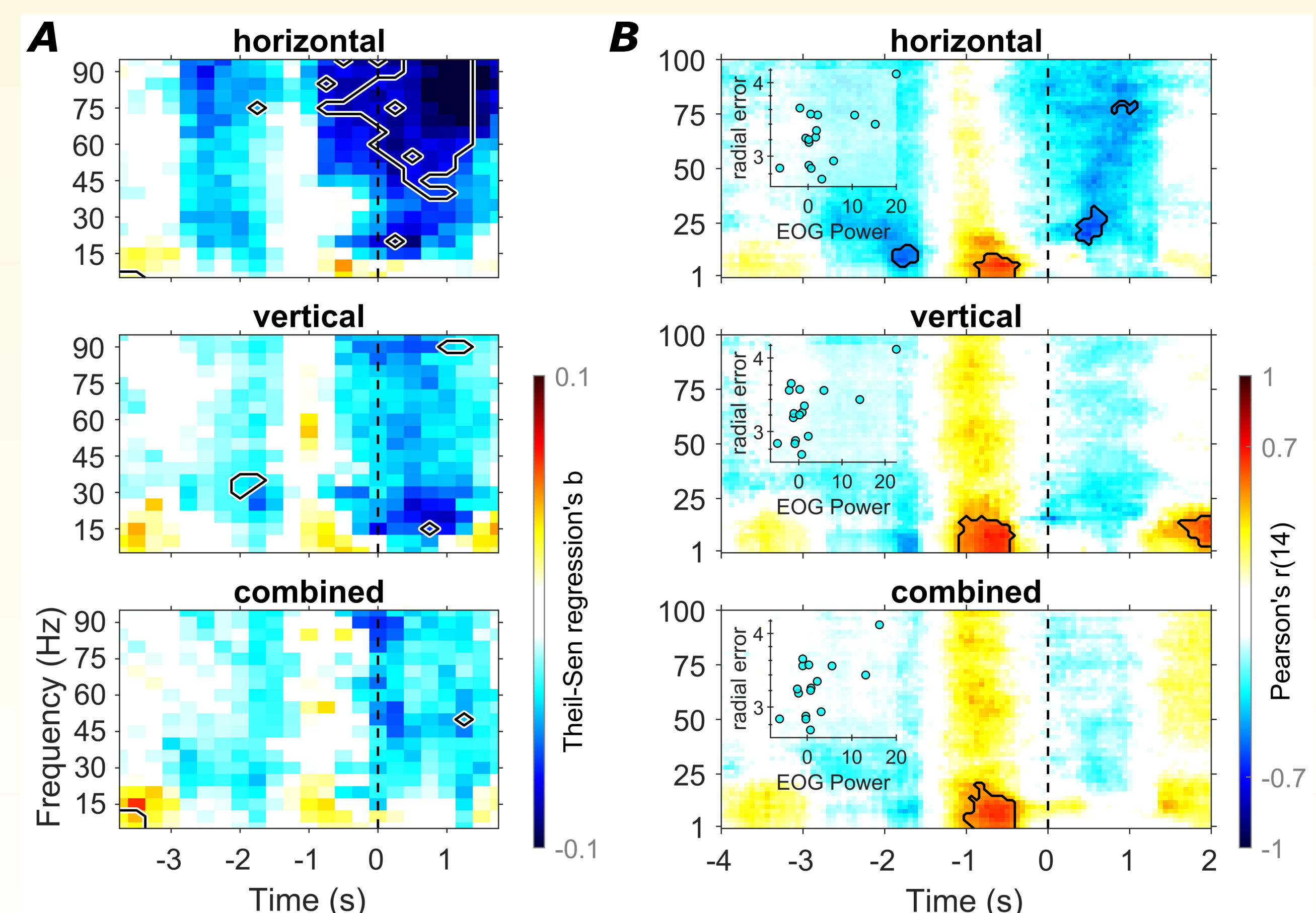


Figure 5. *Panel A:* Theil-Sen regression slopes describing RPEOG hyperparameters as predictors of performance. The contour lines highlight the full dataset slopes corresponding to cross-validation errors below the 5th percentile. *Panel B:* Correlation coefficients between performance (radial error) and RPEOG. The contour lines highlight statistically significant results ($p < .05$) obtained through permutation testing with cluster correction. Scatterplots describe the relation identified by the largest time-frequency clusters for each channel.

Threshold algorithms can yield valid and accurate measurements

QEEOG validity

- best settings
 - QEEOG-dispersion: horizontal channel, 3° threshold, 256-point median filter
 - QEEOG-velocity: horizontal channel, 33°/s threshold, 5th-degree, 767-point SG diff. filter

Combined temporal and spectral features are more reliably associated with performance than temporal features alone

RPEOG utility

- best settings
 - time-frequency power expressed as decibel change from a standing baseline
 - high-frequency horizontal power during movement