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## **Comparing spatial and temporal transferability of hydrological model parameters**

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### **Highlights:**

- 1) We compare three different schemes for transfer of hydrological model parameters
- 2) Temporal transfer scheme outperforms spatial and spatiotemporal transfer schemes
- 3) Differences between spatial and spatiotemporal transfer schemes are negligible
- 4) Temporal gap in calibration and validation periods reduces difference among schemes

1 **Abstract**

2 Operational use of hydrological models requires the transfer of calibrated parameters either in  
3 time (for streamflow forecasting) or space (for prediction at ungauged catchments) or both.  
4 Although the effects of spatial and temporal parameter transfer on catchment streamflow  
5 predictions have been well studied individually, a direct comparison of these approaches is  
6 much less documented. Here, we compare three different schemes of parameter transfer, viz.,  
7 temporal, spatial, and spatiotemporal, using a spatially lumped hydrological model called  
8 EXP-HYDRO at 294 catchments across the continental United States. Results show that the  
9 temporal parameter transfer scheme performs best, with lowest decline in prediction  
10 performance (median decline of 4.2%) as measured using the Kling-Gupta efficiency metric.  
11 More interestingly, negligible difference in prediction performance is observed between the  
12 spatial and spatiotemporal parameter transfer schemes (median decline of 12.4% and 13.9%  
13 respectively). We further demonstrate that the superiority of temporal parameter transfer  
14 scheme is preserved even when: (1) spatial distance between donor and receiver catchments  
15 is reduced, or (2) temporal lag between calibration and validation periods is increased.  
16 Nonetheless, increase in the temporal lag between calibration and validation periods reduces  
17 the overall performance gap between the three parameter transfer schemes. Results suggest  
18 that spatiotemporal transfer of hydrological model parameters has the potential to be a viable  
19 option for climate change related hydrological studies, as envisioned in the “trading space for  
20 time” framework. However, further research is still needed to explore the relationship  
21 between spatial and temporal aspects of catchment hydrological variability.

22

23 **Keywords:** Hydrological model; parameter transfer; catchment; streamflow prediction

## 24 1 Introduction

25 All hydrological models contain parameters whose values must be calibrated by  
26 comparing the observed and simulated streamflow values from the past record [*Refsgaard,*  
27 1997; *Beven,* 2001]. Calibrated parameters represent the unique combination of climatic and  
28 physiographic factors that influence the hydrological behaviour of a catchment [*Merz and*  
29 *Blöschl,* 2004; *Wagener and Wheeler,* 2006]. However, operational use of hydrological  
30 models is always outside of the calibration period and/or catchment, which is where the  
31 parameters face their true test [*Klemeš,* 1986; *Refsgaard and Knudsen,* 1996; *Coron et al.,*  
32 2012]. Parameter transfer away from this calibration domain can be in time (for streamflow  
33 forecasting) or space (for prediction at ungauged catchments) or both.

34 Temporal transfer of calibrated parameters is perhaps the most common and  
35 straightforward procedure used in catchment hydrological modelling. The first step involves  
36 choosing a specific historical time period for which all the input and output data required for  
37 running the model are available for the catchment. These data are used to calibrate the model  
38 parameters by finding the best match between the simulated and observed streamflow values.  
39 This procedure is followed by the application of the calibrated model at some other time  
40 period in the same catchment. *Klemeš* [1986] recommends that testing of hydrological  
41 models outside the calibration period is critical to establish their credibility as useful  
42 forecasting tools. An implicit assumption here is that the calibrated model parameters are  
43 temporally stable, i.e., they are suitable for application beyond the calibration period.  
44 However, numerous recent studies have shown that hydrological model parameters are not  
45 always temporally stable [*Merz et al.,* 2011; *Brigode et al.,* 2013; *Westra et al.,* 2014], and  
46 their values depend on the duration as well as the specific physioclimatic conditions of the  
47 calibration period [*Xia et al.,* 2004; *Juston et al.,* 2009; *Vaze et al.,* 2010; *Razavi and Tolson,*  
48 2013]. *Wagener et al.* [2003] used dynamic identifiability analysis (DYNIA) to estimate the

49 parameters of a spatially lumped hydrological model and found that parameter values varied  
50 significantly when calibrated to different parts of the hydrograph. *Merz et al.* [2011]  
51 calibrated the parameters of a semi-distributed version of HBV model for six consecutive 5  
52 year periods between 1976 and 2006 at 273 Austrian catchments, and found that (1) optimal  
53 parameter values were variable across the six calibration periods, and (2) the assumption of  
54 time invariant parameters had a significant impact on model simulations outside the  
55 calibration period. Similar findings were reported by *Coron et al.* [2012] in their study on  
56 temporal parameter transfer using three rainfall-runoff models at 216 catchments in southeast  
57 Australia. *Razavi and Tolson* [2013] compared three different calibration approaches for the  
58 SWAT2000 model at a catchment in the state of New York, USA and concluded that  
59 "...model calibration solely to a short data period may lead to a range of performances from  
60 poor to very well depending on the representativeness of the short data period which is  
61 typically not known a priori".

62 Spatial transfer of calibrated parameters is another widely used procedure in  
63 catchment hydrological modelling and is primarily required for streamflow prediction at  
64 ungauged basins (PUB) [*Sivapalan et al.*, 2003]. A considerable amount of research has been  
65 conducted over the years in the development and comparison of approaches to transfer  
66 hydrological model parameters from gauged to ungauged catchments [*Post and Jakeman*,  
67 1999; *Kokkonen et al.*, 2003; *McIntyre et al.*, 2005; *Young*, 2006; *Oudin et al.*, 2008; *Zhang*  
68 *and Chiew*, 2009; *Patil and Stieglitz*, 2014]. *Blöschl et al.* [2013] and *Hrachowitz et al.*  
69 [2013] provide a comprehensive summary and synthesis of the progress made in PUB  
70 research during the International Association of Hydrological Sciences' (IAHS) PUB decade  
71 initiative (2003-2012) [*Sivapalan et al.*, 2003]. Donor gauged catchments, from which model  
72 parameters can be transferred to the receiver ungauged catchments, are typically identified  
73 using an approach that is either based on spatial proximity or physical similarity to the

74 ungauged catchments. *Oudin et al.* [2008] compared the spatial proximity and physical  
75 similarity approaches at 913 catchments in France and found that the spatial proximity  
76 approach outperformed the physical similarity approach. *Zhang and Chiew* [2009] tested  
77 multiple parameter transfer approaches at 210 catchments in southeast Australia and found  
78 that an integrated similarity approach that combined spatial proximity and physical similarity  
79 slightly outperformed the spatial proximity approach. *Patil and Stieglitz* [2014] compared  
80 two different methods of spatial parameter transfer at 323 catchments in the United States and  
81 found that simulation performance at ungauged catchments is more sensitive to the types of  
82 parameters that are transferred than to the method used for transferring them. However,  
83 regardless of the chosen approach, spatial parameter transfer tends to cause deterioration in  
84 simulation performance (compared to calibration) due to the differences in physiographic  
85 properties and meteorological inputs between the donor and receiver catchments.

86         Although hydrological model simulation following temporal and/or spatial parameter  
87 transfer is expected to cause deterioration in catchment streamflow prediction, not many  
88 studies have focused on a direct comparison of these two approaches. A few PUB focused  
89 studies that have made such a comparison show results that range from a large performance  
90 difference between temporal and spatial parameter transfer (in favour of temporal) [*Merz and*  
91 *Blöschl*, 2004; *Parajka et al.*, 2005] to minor performance difference between them [*Oudin et*  
92 *al.*, 2008]. In our view, further exploration is therefore needed on how the spatial and  
93 temporal parameter transfer approaches compare against each other, especially in the context  
94 of increasing appeal and popularity of the “trading space for time” approaches that are  
95 proposed for assessing the hydrological implications of anthropogenic climate change  
96 [*Wagener et al.*, 2010; *Peel and Blöschl*, 2011; *Singh et al.*, 2011; *Ehret et al.*, 2014;  
97 *Refsgaard et al.*, 2014]. The trading space for time framework assumes that the spatial  
98 variability in catchment hydrological properties (including model parameters) can be used as

99 a proxy for the climate change induced temporal variability in those properties [Merz *et al.*,  
100 2011]. Studies such as Singh *et al.* [2011, 2014] have already demonstrated that the spatial  
101 parameter regionalization techniques developed for PUB can also be applied to make  
102 temporal modifications in model parameters for streamflow predictions under change (PUC)  
103 [Montanari *et al.*, 2013]. Therefore, we argue that a systematic comparison of the spatial and  
104 temporal parameter transfer approaches is likely to provide further insights into the  
105 connections between the PUB and PUC paradigms, and could even help refine the trading  
106 space for time methods.

107 In this paper, we compare three schemes of model parameter transfer, viz., temporal,  
108 spatial, and spatiotemporal, using a hydrological model called EXP-HYDRO [Patil and  
109 Stieglitz, 2014; Patil *et al.*, 2014a, 2014b] at 294 catchments across the continental United  
110 States. The temporal parameter transfer scheme is implemented using a split-sample test  
111 procedure where the available data is divided into two periods, one for calibration and the  
112 other for validation. For the spatial parameter transfer scheme, we use the nearest neighbour  
113 catchment as a donor of calibrated parameters. Comparison of different spatial parameter  
114 transfer techniques is beyond the scope of this study (and has already been done by Patil and  
115 Stieglitz [2014]). In the spatiotemporal parameter transfer scheme, calibrated model  
116 parameters are transferred simultaneously in the spatial (to the nearest neighbour catchment)  
117 and temporal (to a different time period) domain.

118

## 119 **2 Data and Methods**

### 120 **2.1 Hydrological Model**

121 We use the spatially lumped version of EXP-HYDRO model [Patil and Stieglitz,  
122 2014; Patil *et al.*, 2014a, 2014b] to simulate daily streamflow (Figure 1). This model solves  
123 the following two coupled ordinary differential equations simultaneously at each time step:

124 
$$\frac{dS_{Snow}}{dt} = P_{Snow} - Q_{Melt} \quad (1a)$$

125 
$$\frac{dS}{dt} = P_{Rain} + Q_{Melt} - ET - Q_{Bucket} - Q_{Spill} \quad (1b)$$

126 where  $S$  and  $S_{Snow}$  are, respectively, the amounts of stored water (mm) in the catchment and  
 127 snow accumulation buckets.  $P_{Snow}$  and  $P_{Rain}$  are the snowfall and rainfall amounts (mm/day).

128  $ET$  is the actual evapotranspiration (mm/day) from the catchment bucket.  $Q_{Melt}$  is the  
 129 snowmelt (mm/day) from the snow accumulation bucket,  $Q_{Bucket}$  is the subsurface runoff  
 130 (mm/day) generated from the catchment bucket, and  $Q_{Spill}$  is the capacity-excess surface  
 131 runoff (mm/day) that is generated when the catchment bucket is filled to capacity.

132 The incoming daily precipitation  $P$  is classified as snowfall or rainfall based on the  
 133 following conditions:

134 If  $T_a < T_{min}$ ,

135 
$$\begin{aligned} P_{Snow} &= P \\ P_{Rain} &= 0 \end{aligned} \quad (2a)$$

136 Else,

137 
$$\begin{aligned} P_{Snow} &= 0 \\ P_{Rain} &= P \end{aligned} \quad (2b)$$

138 where  $T_a$  is the actual air temperature on a given day,  $T_{min}$  is the air temperature below which  
 139 the precipitation occurs as snowfall and falls directly into the snow accumulation bucket.

140 Snowmelt  $Q_{Melt}$  is modelled using a simple thermal degree day model as follows:

141 If  $T_a > T_{max}$ ,

142 
$$Q_{Melt} = \min \{ S_{Snow}, D_f \cdot (T_a - T_{max}) \} \quad (3a)$$

143 Else,

144 
$$Q_{Melt} = 0 \tag{3b}$$

145 where  $T_{max}$  is the air temperature above which the snow in snow accumulation bucket starts  
 146 melting, and  $D_f$  is the thermal degree day factor that controls the rate of snowmelt.

147 Evapotranspiration  $ET$  from the catchment bucket is calculated as follows:

148 
$$ET = PET \cdot \left( \frac{S}{S_{max}} \right) \tag{4}$$

149 where  $PET$  is the potential evapotranspiration (mm/day), and is calculated from the daily air  
 150 temperature using Hamon's formula [Hamon, 1963].  $S_{max}$  is the total storage capacity (mm)  
 151 of the catchment bucket. The surface and subsurface runoff generated from the catchment  
 152 bucket are calculated as follows:

153 If  $S \leq S_{max}$ ,

154 
$$\begin{aligned} Q_{Bucket} &= Q_{max} \cdot \exp(-f \cdot (S_{max} - S)) \\ Q_{Spill} &= 0 \end{aligned} \tag{5a}$$

155 If  $S > S_{max}$ ,

156 
$$\begin{aligned} Q_{Bucket} &= Q_{max} \\ Q_{Spill} &= S - S_{max} \end{aligned} \tag{5b}$$

157 where  $Q_{max}$  is the maximum subsurface runoff produced (mm/day) when the catchment  
 158 bucket reaches its capacity, and  $f$  is the parameter controlling the storage-dependent  
 159 exponential decline in subsurface runoff (1/mm). Daily streamflow at the catchment outlet is  
 160 the sum of  $Q_{Bucket}$  and  $Q_{Spill}$ .

161 We have now made the entire source code of the spatially lumped version of the EXP-  
 162 HYDRO model (described above) freely available to the research community. This source  
 163 code is written in Python ® programming language and can be downloaded from the  
 164 following web link: <http://sopanpatil.weebly.com/exp-hydro.html>.

## 165 2.2 Model Calibration

166 There are six calibration parameters in the EXP-HYDRO model:  $f$ ,  $S_{\max}$ ,  $Q_{\max}$ ,  $D_f$ ,  
167  $T_{\max}$ , and  $T_{\min}$ . For each catchment, we calibrate these six model parameters using the  
168 Particle Swarm Optimisation (PSO) algorithm [Kennedy and Eberhart, 1995]. PSO is a  
169 stochastic population-based search algorithm that has been used in numerous hydrological  
170 studies for model parameter calibration [Gill *et al.*, 2006; Goswami and O'Connor, 2007;  
171 Liu, 2009; Zhang *et al.*, 2009]. PSO is initialised with a group of random particles (parameter  
172 sets in our case), and this 'swarm' of particles searches for an optimal solution within the  
173 parameter domain by iteratively updating the velocity and position of each particle. We  
174 initialise the PSO algorithm with 10 randomly generated EXP-HYDRO parameter sets  
175 (sampled from a uniform distribution) and allow for a maximum of 50 swarm iterations to  
176 find the optimal solution. The upper and lower bound values of all six parameters are same  
177 as those in Patil and Stieglitz [2014]. We use Kling-Gupta efficiency (KGE) [Gupta *et al.*,  
178 2009] as the objective function that is to be maximised during calibration:

$$179 \quad KGE = 1 - \sqrt{(r-1)^2 + (\alpha-1)^2 + (\beta-1)^2} \quad (6)$$

180 where  $r$  is the Pearson's linear correlation coefficient between the observed and simulated  
181 streamflow,  $\alpha$  is the ratio of standard deviations of observed and simulated streamflow, and  
182  $\beta$  is the ratio of mean values of observed and simulated streamflow. The value of KGE  
183 varies from  $-\infty$  to 1, with  $KGE = 1$  being a perfect fit between the observed and simulated  
184 values.

185 As shown by Gupta *et al.* [2009], KGE consists of three main components, correlation  
186 ( $g_1$ ), variability ( $g_2$ ), and bias ( $g_3$ ), whose relative contribution to the KGE value varies  
187 from 0 to 1 and is calculated as follows:

188 
$$g_i = \frac{G_i}{\sum_{j=1}^3 G_j} \quad (7a)$$

189 and,

190 
$$\begin{aligned} G_1 &= (r - 1)^2 \\ G_2 &= (\alpha - 1)^2 \\ G_3 &= (\beta - 1)^2 \end{aligned} \quad (7b)$$

191 **2.3 Study Catchments**

192 We begin the catchment selection process by implementing the EXP-HYDRO model  
 193 at 756 catchments in the continental United States (Figure 2a). These are the same  
 194 catchments that have been used in our two previous studies [*Patil and Stieglitz, 2012, 2014*];  
 195 they belong to the U. S. Geological Survey’s Hydro-Climate Data Network (HCDN) [*Slack et*  
 196 *al., 1993*] and have a continuous daily streamflow record from water year (WY) 1970 to 1988  
 197 (i.e., 1st October, 1969 to 30th September, 1988). Daily precipitation and air temperature  
 198 data for each catchment are obtained from the gridded meteorological dataset developed by  
 199 *Maurer et al. [2002]*. This data has a spatial resolution of 0.125 degree and covers the entire  
 200 continental United States.

201 We split the timeline from WY 1970 to 1988 into the following three periods: WY  
 202 1970 is the spin-up period that is not used for parameter calibration, WY 1971 to 1978 is  
 203 calibration period 1, and WY 1979 to 1988 is calibration period 2 (see Figure 2b). For each  
 204 catchment, we calibrate the EXP-HYDRO model parameters separately for calibration  
 205 periods 1 and 2 using the methods described in Section 2.2. Only those catchments where the  
 206 simulated streamflow provides  $KGE > 0.6$  for both calibration periods are retained as our  
 207 study catchments. This is done to ensure that only those catchments for which the EXP-  
 208 HYDRO model structure seems suitable for providing good hydrological simulations are  
 209 used for any further analyses. The above condition reduces the number of acceptable study

210 catchments to 294 (Figure 2a). The geographic distribution of the acceptable catchments is  
211 similar to that obtained by *Patil and Stieglitz* [2014]. The drainage area of the study  
212 catchments ranges from 24 km<sup>2</sup> to 4790 km<sup>2</sup>, with median drainage area of 620 km<sup>2</sup>. The  
213 majority of catchments are located in the eastern part of the continental United States, to the  
214 east of Mississippi River. In the western United States, the study catchments are primarily  
215 located along the Rocky, Cascade and Pacific Coastal mountain ranges. Mean annual  
216 precipitation among the study catchments ranges from 340 mm to 2556 mm (median = 1160  
217 mm).

#### 218 **2.4 Parameter Transfer Schemes**

219 For the 294 study catchments, we test the following three schemes of model  
220 parameter transfer:

- 221 (1) Temporal transfer: For the same catchment, model parameters from calibration period 1  
222 are transferred to calibration period 2, and vice versa.
- 223 (2) Spatial transfer: Model parameters of a catchment are obtained from its nearest  
224 neighbour catchment over the same time period. This is done separately for calibration  
225 periods 1 and 2.
- 226 (3) Spatiotemporal transfer: Model parameters of a catchment are obtained from its nearest  
227 neighbour catchment across different time periods (i.e., from calibration period 1 to 2,  
228 and vice versa).

229

### 230 **3 Results**

231 We first compare the simulation performance of EXP-HYDRO model that is obtained  
232 across the two calibration periods. Figure 3 shows a 1:1 comparison of the KGE values  
233 obtained at the 294 catchments during calibration periods 1 and 2. The relationship between  
234 calibrated KGE values of the two periods is somewhat weak (Pearson's  $r = 0.53$ ), with data

235 points scattered along both sides of the 1:1 line. Figure 4 shows the comparison of  $g_1$ ,  $g_2$ ,  
236 and  $g_3$  (the three components of KGE) during calibration periods 1 and 2. Similar to KGE, a  
237 weak relationship exists between the values obtained at these two different periods ( $r = 0.55$   
238 for  $g_1$ ,  $r = 0.4$  for  $g_2$ ,  $r = 0.65$  for  $g_3$ ). Figures 5a-f show a 1:1 comparison of the values of  
239 all six EXP-HYDRO parameters during calibration periods 1 and 2. The relationship among  
240 parameter values across the two calibration periods is strongest for  $f$  ( $r = 0.81$ , Figure 5a),  
241 followed by  $S_{\max}$  ( $r = 0.59$ , Figure 5b),  $D_f$  ( $r = 0.36$ , Figure 5d),  $Q_{\max}$  ( $r = 0.26$ , Figure 5c),  
242  $T_{\min}$  ( $r = 0.26$ , Figure 5e), and  $T_{\max}$  ( $r = 0.17$ , Figure 5f).

243 We next compare the performance of EXP-HYDRO model across the three parameter  
244 transfer schemes. Figure 6 shows a box-plot comparison of the KGE values among the  
245 following four modelling scenarios: calibration, temporal transfer, spatial transfer, and  
246 spatiotemporal transfer. Note that the KGE values shown in Figure 6 are the average values  
247 of two sub-scenarios that are present in each scenario. For example, KGE of each catchment  
248 in the calibration scenario is an average of its KGE values from calibration period 1 and  
249 calibration period 2. As seen in Figure 6, the overall model performance is highest for the  
250 calibration scenario (median KGE = 0.72), followed by temporal transfer (median KGE =  
251 0.69; decline of 4.2% (compared to calibration)), spatial transfer (median KGE = 0.63;  
252 decline of 12.4%), and spatiotemporal transfer (median KGE = 0.62; decline of 13.9%)  
253 scenarios.

254 Figure 7 shows the box-plot comparison of the above four scenarios with respect to  
255 the three KGE components,  $g_1$ ,  $g_2$ , and  $g_3$ . For correlation component  $g_1$ , calibration  
256 scenario has the highest overall contribution value (median  $g_1 = 0.85$ ), and is followed by  
257 temporal (median  $g_1 = 0.68$ ), spatial (median  $g_1 = 0.54$ ), and spatiotemporal (median  $g_1 =$

258 0.54) transfer scenarios. For variability component  $g_2$ , calibration scenario has the lowest  
259 contribution value (median  $g_2 = 0.06$ ), and is followed by the temporal (median  $g_2 = 0.17$ ),  
260 spatial (median  $g_2 = 0.23$ ), and spatiotemporal (median  $g_2 = 0.24$ ) transfer schemes. The  
261 bias component  $g_3$  has a similar trend as  $g_2$ , but is less prominent. The calibration scenario  
262 has the lowest contribution value (median  $g_3 = 0.05$ ), and is followed by the temporal  
263 (median  $g_3 = 0.11$ ), spatial (median  $g_3 = 0.12$ ), and spatiotemporal (median  $g_3 = 0.13$ )  
264 transfer schemes.

265 Results from Figures 6 and 7 demonstrate that the overall model performance of the  
266 temporal parameter transfer scheme is superior to that of the spatial and spatiotemporal  
267 parameter transfer schemes. However, it is not clear from these results whether our  
268 experimental setup provides any undue advantage to the temporal parameter transfer scheme  
269 over the other two schemes. Below, we briefly mention two such potential scenarios:

270 Scenario 1: It is likely that for some of our study catchments, the distance between them and  
271 their nearest neighbour catchment is too high. Such a scenario puts the spatial and  
272 spatiotemporal transfer schemes at a clear disadvantage compared to the temporal transfer  
273 scheme.

274 Scenario 2: There is no temporal lag between calibration periods 1 and 2, i.e., calibration  
275 period 2 immediately follows calibration period 1 (Figure 2b). For catchments where the  
276 meteorological input patterns have not changed much across the two periods, the temporal  
277 parameter transfer scheme is much more likely to outperform the other two schemes.

278 To mitigate the impacts from above two potential scenarios on our results, we repeat the  
279 parameter transfer experiment for the two following special conditions:

280 Special Condition 1: Eliminate all study catchments that have a nearest neighbour catchment  
281 more than 50 km away. The 50 km distance limit is slightly less than the median nearest

282 neighbour distance (53.1 km) among all the 294 study catchments. This reduces the number  
283 of catchments from 294 to 138.

284 Special Condition 2: Shorten the calibration period 1 to span from WY 1971 to 1975 (instead  
285 of WY 1971 to 1978) and calibration period 2 to span from WY 1984 to 1988 (instead of WY  
286 1979 to 1988). This creates a temporal lag of 8 years between the two calibration periods.  
287 Nonetheless, unlike Special Condition 1, all 294 study catchments are used for simulations.  
288 Note that these new calibration periods span 5 years each, which is the minimum time span  
289 recommended by some studies to adequately capture the temporal hydrological variability of  
290 a catchment [Merz *et al.*, 2009].

291         Figures 8a and 8b show the box-plot comparison of KGE values from the four  
292 modelling scenarios for Special Conditions 1 and 2 respectively. In both cases, the results are  
293 similar to those observed in Figure 6. For Special Condition 1, the highest model  
294 performance is obtained for the calibration scenario (median KGE = 0.74), followed by the  
295 temporal (median KGE = 0.71; decline of 4%), spatial (median KGE = 0.67; decline of  
296 9.5%), and spatiotemporal (median KGE = 0.66; decline of 10.8%) parameter transfer  
297 schemes. For Special Condition 2, the median KGE values are 0.72 for calibration, 0.66 for  
298 temporal transfer scheme (decline of 8.3%), 0.62 for spatial transfer scheme (decline of  
299 13.9%), and 0.62 for spatiotemporal transfer scheme (decline of 13.9%).

300

#### 301 **4 Discussion**

302         Comparison of the optimal KGE values (Figure 3) and the individual KGE  
303 components (Figure 4) between calibration periods 1 and 2 demonstrates that the  
304 performance of a hydrological model can, at least in some cases, vary considerably in the  
305 same catchment for different calibration periods. Similar findings have been reported by  
306 Vaze *et al.* [2010] and Razavi and Tolson [2013]. The data points shown in Figures 3 and 4

307 are scattered along both sides of the 1:1 line. This suggests that for our study catchments no  
308 systematic bias exists in terms of one calibration period providing better calibration  
309 performance than the other. For the majority of study catchments (213 out of 294), the  
310 difference between optimal KGE values for the two calibration periods is less than 10%  
311 (median = 6%). This is consistent with *Merz et al.* [2011], who found that the calibrated  
312 Nash-Sutcliffe efficiency values [*Nash and Sutcliffe*, 1970] of the HBV model, averaged  
313 across their 273 Austrian catchments, showed small variability across six different calibration  
314 periods. However, they found this variability to increase when only drier study catchments  
315 were considered in their calculations. Although our data set does have a few catchments that  
316 show large performance difference between the calibration periods (largest difference is  
317 35%), we did not detect any specific geographic or climatic pattern among those catchments.

318 Results from Figure 5 show that the temporal variability of parameter values is  
319 different for each parameter, with values of the  $f$  parameter showing the highest correlation  
320 (and therefore lowest variability) between the two calibration periods, followed by  $S_{\max}$ ,  $D_f$ ,  
321  $Q_{\max}$ ,  $T_{\min}$ , and  $T_{\max}$ . Interestingly, this trend is similar to the parameter sensitivity trend  
322 shown in our previous study [*Patil and Stieglitz*, 2014]. *Patil and Stieglitz* [2014] performed  
323 a sensitivity analysis of all 6 EXP-HYDRO parameters and found that  $f$ ,  $S_{\max}$ , and  $D_f$   
324 were the most sensitive parameters (i.e., sensitive to the objective function) with better  
325 defined optimal values and posterior distributions. On the other hand,  $Q_{\max}$ ,  $T_{\min}$ , and  $T_{\max}$   
326 were characterised as the insensitive parameters with virtually no difference between their  
327 prior (uniform) and posterior distributions. Combined, these results suggest that the high  
328 sensitivity model parameters are also more likely to have low variability across different  
329 calibration periods, thereby making them more representative of the catchment's intrinsic  
330 physiographic conditions rather than the specific input conditions during the calibration

331 period. For the EXP-HYDRO model, the two most temporally stable parameters ( $f$  and  
332  $S_{\max}$ ) represent: (1) the rate of storage decline within the soil bucket in response to  
333 subsurface runoff, and (2) the total soil bucket capacity. Both these parameters are, at least in  
334 theory, linked to the intrinsic soil and topographic properties of a catchment that are unlikely  
335 to undergo drastic temporal change. Nonetheless, we suspect that the proportion of sensitive  
336 and temporally stable parameters is likely to be different for different types of hydrological  
337 models. For instance, *Merz and Blöschl* [2004] calibrated the lumped version of HBV model  
338 (containing 11 parameters) at 308 catchments in Austria for two different calibration periods.  
339 They found that the correlation coefficient ( $R^2$ ) between the parameter values of the two  
340 calibration periods ranged from 0.09 to 0.64, with only 5 of the 11 parameters having  $R^2 >$   
341 0.5. *Oudin et al.* [2008] compared the parameters of two spatially lumped hydrological  
342 models, GR4J (4 parameters) and TOPMO (6 parameters), for 913 French catchments across  
343 two calibration periods, and showed that the correlation across calibration periods was higher  
344 for GR4J parameters compared to TOPMO parameters. However, it must be noted we still  
345 do not have a complete understanding of how these model parameter values will change in  
346 response to land cover changes within a catchment [*Eckhardt et al.*, 2003; *Croke et al.*, 2004;  
347 *Wang and Kalin*, 2011].

348 Results from the parameter transfer experiment (Figures 6 and 7) demonstrate the  
349 overall superior performance of the temporal parameter transfer scheme over the spatial and  
350 spatiotemporal parameter transfer schemes. Analysis of the three KGE components (Figure  
351 7) shows that the correlation component ( $g_1$ ) is the most dominant contributor to KGE value,  
352 which is consistent with *Gupta et al.* [2009]. However, this component also undergoes the  
353 most decline when moving away from calibration to the parameter transfer scenarios. The  
354 decline in  $g_1$  is compensated by a proportional increase in the contribution from the other two

355 components (variability  $g_2$  and bias  $g_3$ ) for the parameter transfer scenarios compared to  
356 calibration. *Gupta et al.* [2009] note that the relative contributions of the bias and variability  
357 components tend to increase for non-optimal parameter sets, as is observed in all our  
358 parameter transfer scenarios. When the three parameter transfer schemes are individually  
359 compared across each of the 294 catchments, the temporal transfer scheme shows best  
360 performance at 204 catchments (and worst at 50 catchments), the spatial transfer scheme is  
361 best at 65 catchments (and worst at 106 catchments), whereas the spatiotemporal transfer  
362 scheme is best at 27 catchments (and worst at 147 catchments). Figure 9 shows the map of  
363 catchment locations where either the spatial or spatiotemporal parameter transfer scheme is  
364 the best performing scheme. No specific geographic pattern is noticeable from this figure in  
365 terms of the catchments that prefer the spatial and spatiotemporal transfer schemes over the  
366 temporal transfer scheme. Table 1 shows the comparison of these two catchment groups  
367 (Group 1: spatial or spatiotemporal transfer scheme performing best; Group 2: temporal  
368 transfer scheme performing best) with respect to three commonly used hydro-climatic  
369 metrics, viz., mean annual rainfall (P), annual runoff ratio (Q/P) and climate aridity index  
370 (PET/P). Although the median values of these metrics suggest that Group 1 catchments are  
371 slightly drier (lower P and higher PET/P) and flashier (higher Q/P), there does not seem to be  
372 much difference among the two catchment groups. Nonetheless, Figure 9 clearly illustrates  
373 that even in regions with low catchment density and larger distances among neighbouring  
374 catchments (e.g., in the western US), the temporal parameter transfer schemes does not  
375 always outperform the spatial and spatiotemporal schemes.

376         Parameter transfer experiments under the two special conditions (see Section 3) show  
377 that the temporal parameter transfer scheme still preserves its advantage over the spatial and  
378 spatiotemporal schemes. For Special Condition 1, i.e., when only those catchments with  
379 nearest neighbour < 50 km away are retained, the spatial and spatiotemporal schemes exhibit

380 performance improvement as the KGE difference between them and calibration is about 3%  
381 lower than the base scenario. This is an expected result because lower spatial distances  
382 between catchments will most likely reduce the spatial variability of hydrological behaviour  
383 [Oudin *et al.*, 2008]. On the other hand, for Special Condition 2 (when the temporal gap  
384 between calibration periods is increased to 8 years), the KGE difference between calibration  
385 and the temporal scheme is about 4% higher than the base scenario, and is virtually  
386 unchanged between calibration and the spatial and spatiotemporal schemes. Thus, an  
387 increase in the temporal distance between calibration and validation periods reduces the  
388 model performance gap between the temporal scheme and the spatial and spatiotemporal  
389 schemes. This has important implications for the “trading space for time” framework [Peel  
390 and Blöschl, 2011; Refsgaard *et al.*, 2014] because a sufficiently large time lag between the  
391 calibration and validation periods (as is common in climate change scenarios) has the  
392 potential to make spatiotemporal parameter transfer a more viable option than temporal  
393 parameter transfer. However, even though the introduction of an 8 year temporal gap  
394 between the calibration and validation periods shows reduced performance gap among the  
395 parameter transfer schemes, it is not entirely clear how these schemes will compare for much  
396 larger (> 40-50 years) temporal gaps.

397

## 398 **5 Conclusion**

399 In this paper, we compared three different schemes for the transfer of hydrological  
400 model parameters, viz., temporal, spatial, and spatiotemporal, using a spatially lumped  
401 hydrological model called EXP-HYDRO at 294 catchments across the continental United  
402 States. In our view, such a comparison is highly relevant especially within the context of  
403 increasing appeal and popularity of the “trading space for time” framework proposed for  
404 assessing the hydrological implications of anthropogenic climate change. Results showed

405 that the temporal parameter transfer scheme performs best, with lowest decline in prediction  
406 performance compared to calibration (median decline of 4.2%); whereas negligible difference  
407 in prediction performance was observed between the spatial and spatiotemporal parameter  
408 transfer schemes (median decline of 12.4% and 13.9% respectively). These results suggest  
409 that the stability of hydrological model parameters tends to be higher in the temporal domain  
410 than in the spatial domain, and are consistent with previous studies conducted in different  
411 parts of the world [Parajka *et al.*, 2005; Zhang and Chiew, 2009]. We also demonstrated that  
412 the relative superiority of temporal parameter transfer scheme is preserved even when: (1) the  
413 spatial distance between donor and receiver catchments is reduced, or (2) the temporal lag  
414 between calibration and validation periods is increased. Nonetheless, we found that an  
415 increase in the temporal lag between calibration and validation periods reduces the model  
416 performance gap between the temporal scheme and the spatial and spatiotemporal schemes.  
417 This finding, combined with the negligible difference observed between the spatial and  
418 spatiotemporal schemes, suggest that spatiotemporal transfer of hydrological model  
419 parameters has the potential to be a viable option for climate change related studies, as  
420 envisioned in the trading space for time framework. However, further research is still needed  
421 to better understand the relationship between the spatial and temporal aspects of catchment  
422 hydrological variability with increasing time lag between the calibration and validation  
423 periods.

424

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431

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575

576 Table 1: Comparison of the two catchment groups (from Figure 9) in terms of mean annual  
577 rainfall, annual runoff ratio and climate aridity index.  
578

<b>Catchment group</b>	<b>Median value of mean annual rainfall (P)</b>	<b>Median value of annual runoff ratio (Q/P)</b>	<b>Median value of climate aridity index (PET/P)</b>
Group 1: Spatial or spatiotemporal transfer performs best	1110 mm	0.43	0.73
Group 2: Temporal transfer performs best	1185 mm	0.41	0.69

579

580

**Figures**

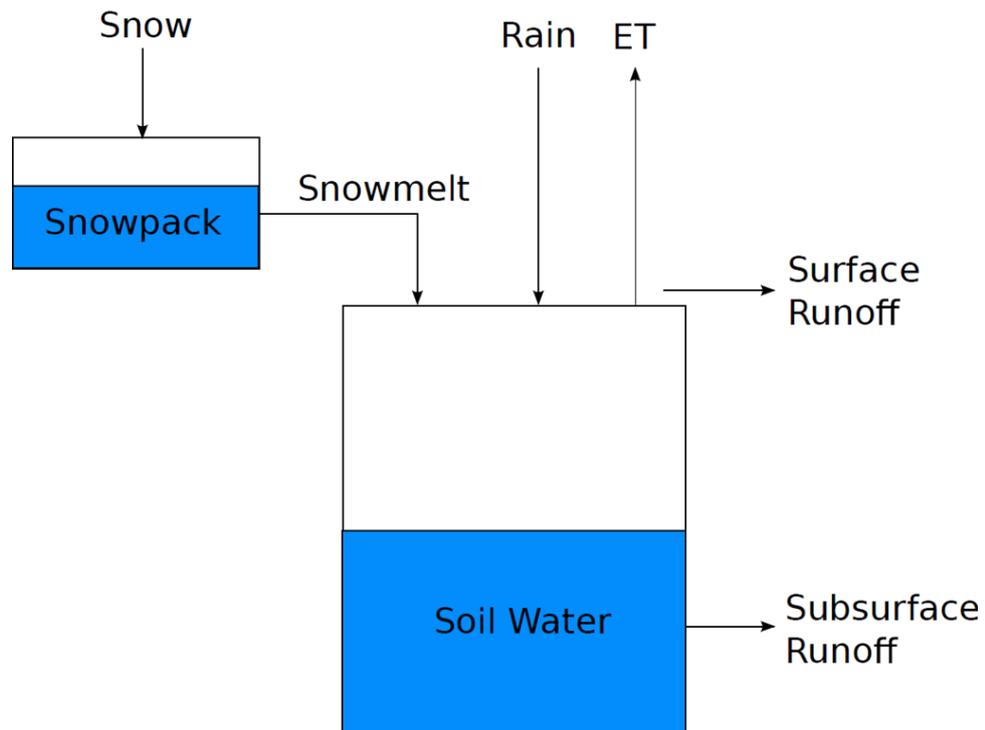


Figure 1: Overview of the EXP-HYDRO model components and fluxes (from *Patil et al.* [2014a]).



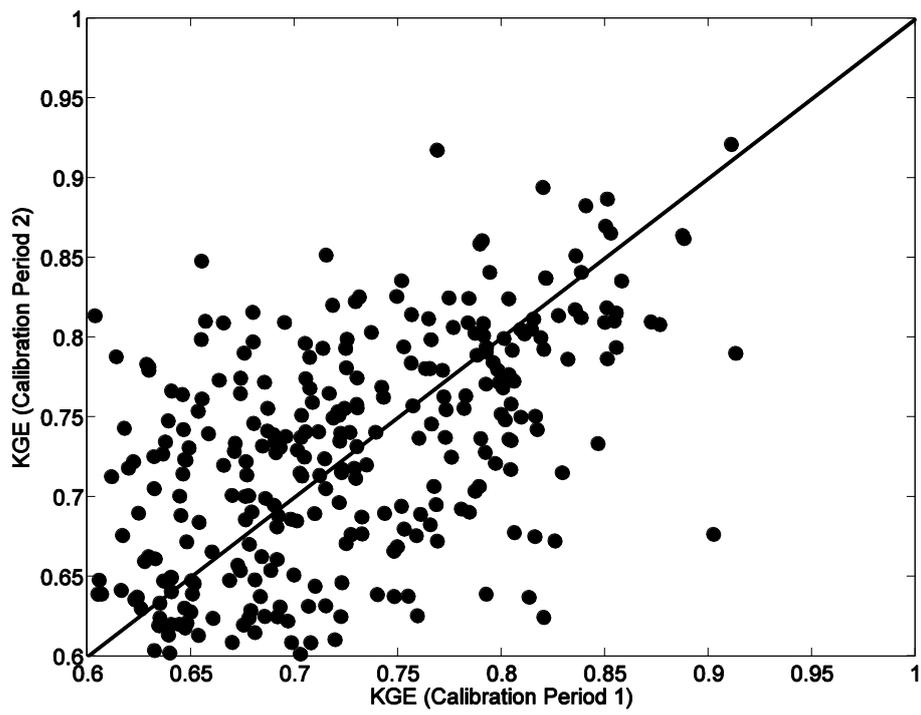


Figure 3: A 1:1 comparison of the KGE values for Calibration Periods 1 and 2.

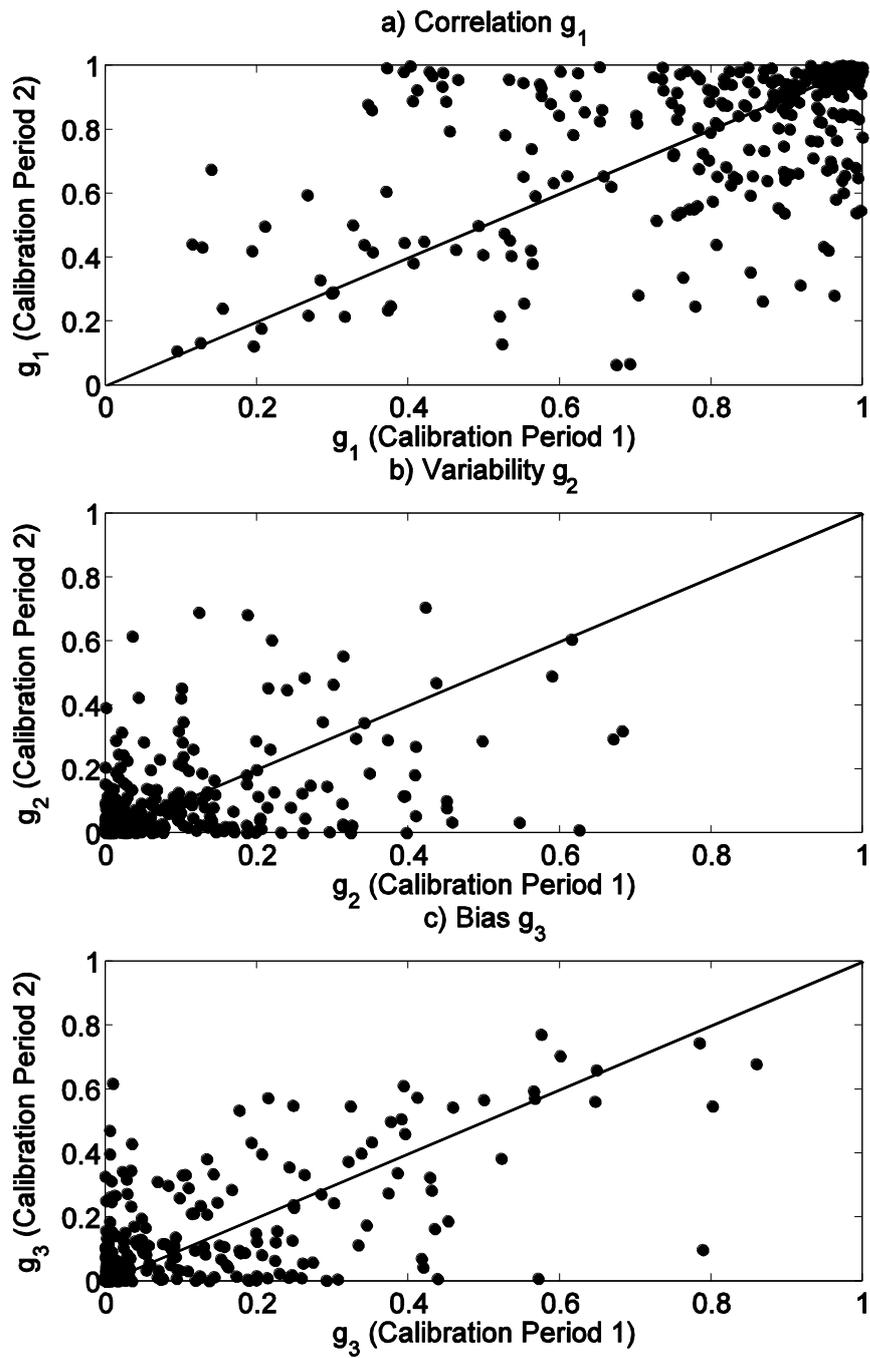


Figure 4: A 1:1 comparison of the three KGE components for Calibration Periods 1 and 2: a) Correlation  $g_1$ , b) Variability  $g_2$ , and c) Bias  $g_3$ .

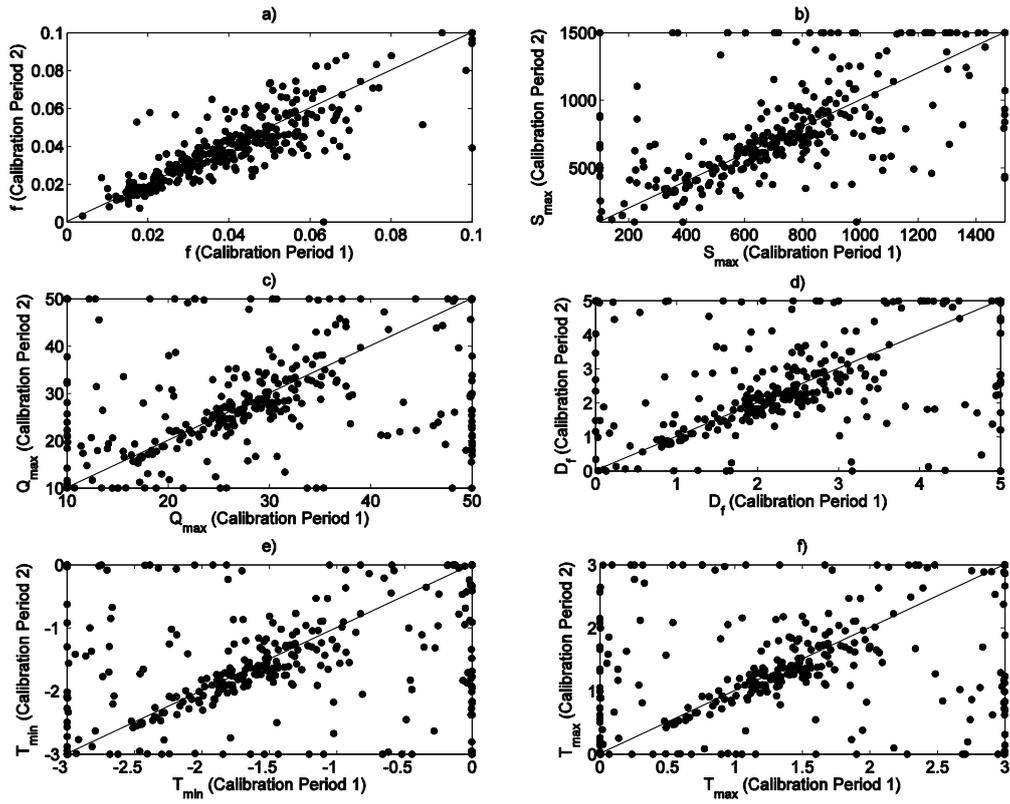


Figure 5: A 1:1 comparison of all 6 EXP-HYDRO parameter values for Calibration Periods 1 and 2.

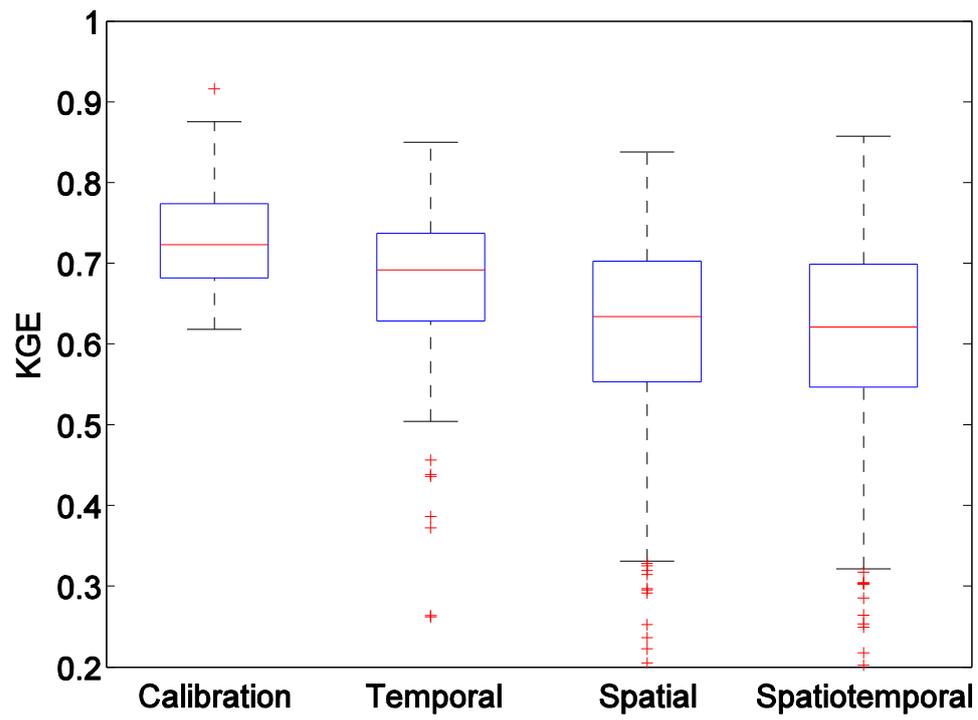


Figure 6: A box-plot comparison of the KGE values for calibration and the three parameter transfer scenarios.

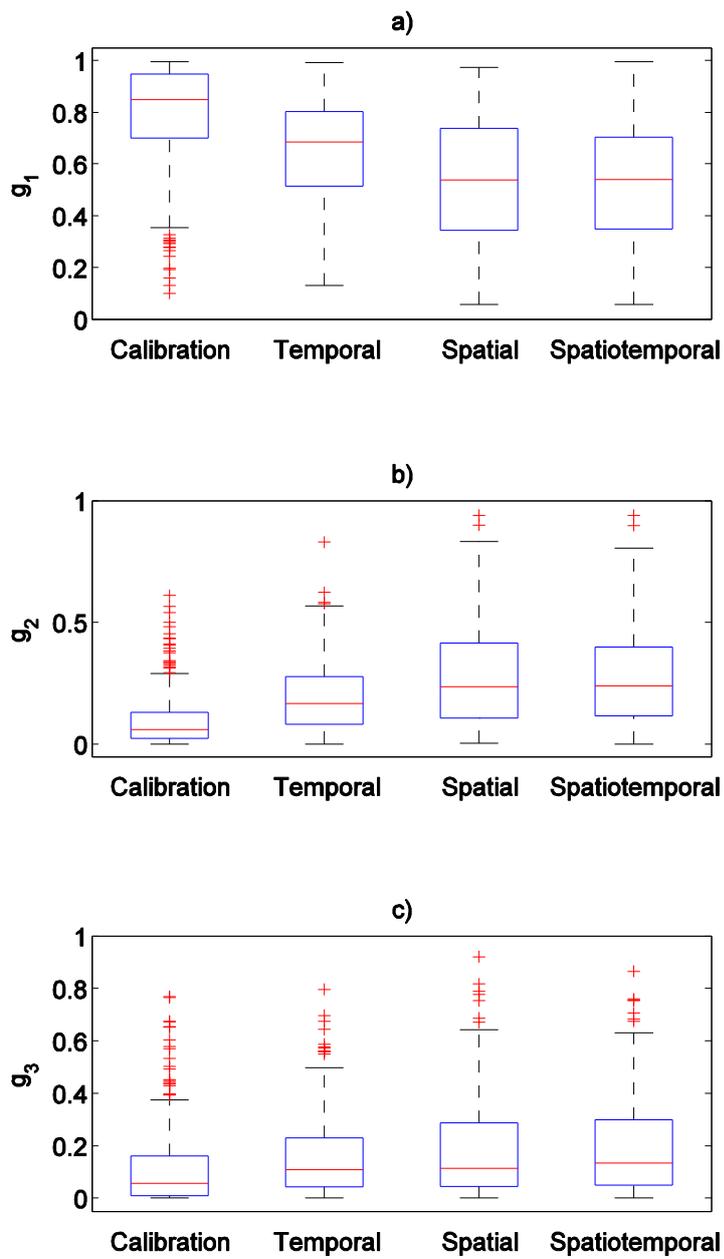


Figure 7: A box-plot comparison of the three KGE components for calibration and the three parameter transfer scenarios.

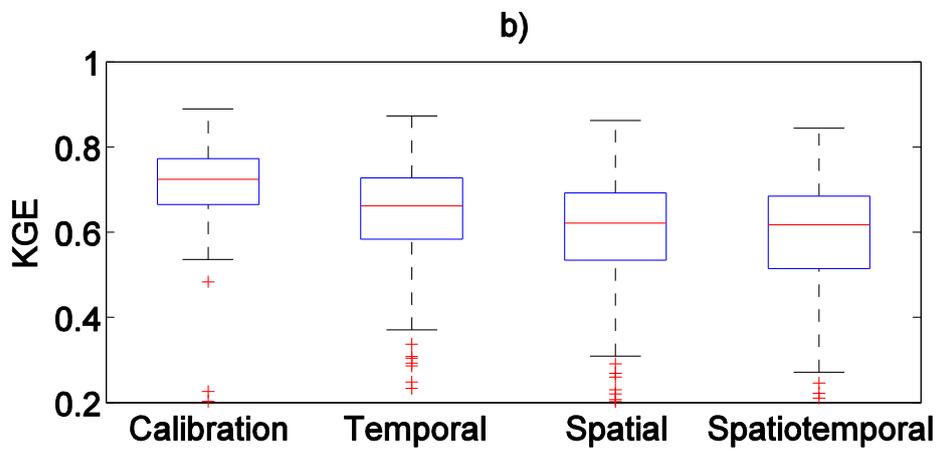
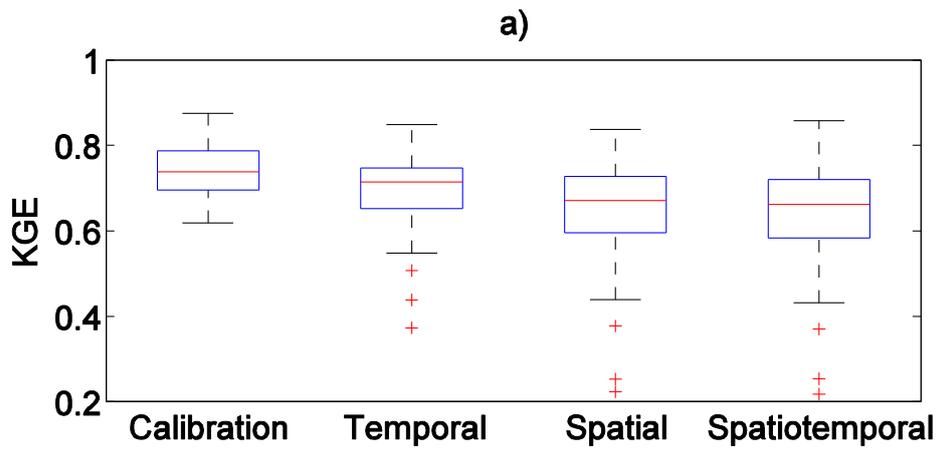


Figure 8: A box-plot comparison of the KGE values for calibration and the three parameter transfer scenarios, shown separately for a) Special Condition 1, and b) Special Condition 2.

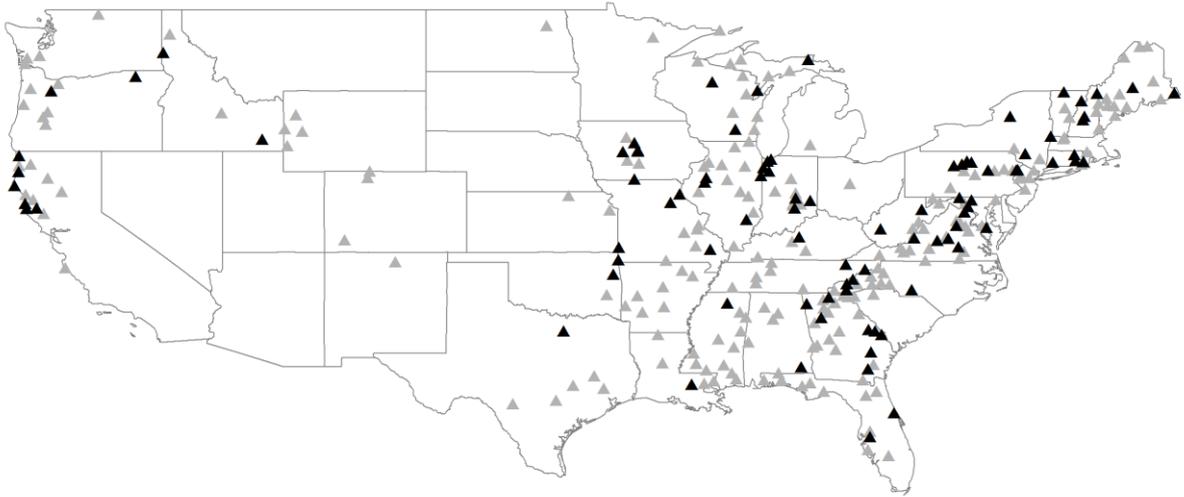


Figure 9: Location of the catchments where either the spatial or spatiotemporal parameter transfer scheme performs best (Black triangles). Catchments where the temporal parameter transfer scheme performs best are shown as grey triangles.